CS-5630 / CS-6630 Visualization for Data Science Graphs Alexander Lex alex@sci.utah.edu







New York Times*



Politico



https://twitter.com/niko_tinius/status/1060185135918866433

Washington Post*

Graph Exercise

Nodes and Node Attributes

Author (# papers) Carolina (6), Miriah (42) Alex (36), Sean (8), Marc (40)Nils (51), Silvia (110)

Links and Link Attributes

Co-author, co-author - # joint papers Carolina, Alex - 2 Sean, Miriah - 7 Miriah, Alex - 2 Alex, Sean - 1 Alex, Nils - 10 Alex, Marc - 24 Marc, Silvia - 1 Marc, Nils - 8



	Carolina (6)	Miriah (42)	Alex (36)
Carolina (6)			2
Miriah (42)			2
Alex (36)	2	2	
Sean (8)		7	1
Marc (40)			14
Nils (51)			10
Silvia (110)			

Alex (36)	Sean (8)	Marc (40)	Nils (51)	Silvia (110)	
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Graphs

Applications of Graphs Without graphs, there would be none of these:









Biological Networks

The brain: connections between neurons Phylogeny: the evolutionary relationships of life



- Interaction between genes, proteins and chemical products
- Your ancestry: the relations between you and your family





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Graph Analysis Case Study



Graph Theory fundamentals

Network



Tree



See also "Network Science", Barabasi http://barabasi.com/networksciencebook/chapter/2

> Hypergrap h

Bipartite Graph



Königsberg Bridge Problem (1736)

Can you take a walk and visit every land mass without crossing a bridge twice?



Leonhard Euler: Only possible with a graph with at most two nodes with an odd number of links. This graph has four nodes with odd number of links.

http://barabasi.com/networksciencebook/chapter/2#bridges

Graph Terms

A graph **G(V,E)** consists of a set of **vertices V** (also called nodes) and a

set of **edges E** (also called links) connecting these vertices.

Graph and **Network** are often used interchangeably





Graph Term: Simple Graph

A simple graph G(V,E) is a graph which contains **no multi-edges** and **no loops**



Not a simple graph! → A *general graph*

Graph Term: Directed Graph

A directed graph (digraph) is a graph that discerns between the edges A-B and A-B.

Graph Terms: Hypergraph

A hypergraph is a graph with edges connecting any number of vertices.



Hypergraph Example

Graph Terms

Independent Set G contains no edges

Clique G contains all possible edges



Independent Set



Unconnected Graphs, Articulation Points

Unconnected graph

An edge traversal starting from a given vertex cannot reach any other vertex.

Articulation point

Vertices, which if deleted from the graph, would break up the graph in multiple sub-graphs.



Unconnected Graph



Articulation Point (red)

Biconnected, **Bipartite Graphs Biconnected graph** A graph without articulation points.

Bipartite graph The vertices can be partitioned in two independent sets.



Biconnected Graph



Tree A graph with no cycles - or: **A collection of nodes** contains a root node and 0-n subtrees subtrees are connected to root by an edge













Different Kinds of Graphs

Over 1000 different graph classes





A. Brandstädt et al. 1999

Degree

Node degree deg(x) The number of edges connecting a node. For directed graphs in- and out-degree are considered separately.

Average degree

$$\langle k \rangle = \frac{1}{N} \sum_{i=1}^{N} k_i = \frac{2L}{N}$$

Degree distribution



Degree Distribution of a real Network





Protein Interaction Network



Degrees

Degree is a measure of local importance



Betweenness Centrality

a measure of how many shortest paths pass through a node good measure for the overall relevance of a node in a graph





Degree vs BC





Paths & Distances

- Path is route along links
- Path length is the number of links contained
- Shortest paths connects nodes i and j with the smallest number of links
- **Diameter of graph G** The longest shortest path within G.



A path from 1 to 6

Shortest paths (two) from 1 to 7.



Graph and Tree Visualization

Setting the Stage



of graph in order to achieve which kind of goal?

How to decide which **representation** to use for which **type**

Different Kinds of Tasks/Goals

- **Localize** find a single or multiple nodes/edges that fulfill a given property • ABT: Find the edge(s) with the maximum edge weight.
 - TBT: Find all adjacent nodes of a given node.

Quantify – count or estimate a numerical property of the graph

- ABT: Give the number of all nodes.
- TBT: Give the degree of a node.

- Sort/Order enumerate the nodes/edges according to a given criterion • ABT: Sort all edges according to their weight.
 - TBT: Traverse the graph starting from a given node.

Two principal types of tasks: attribute-based (ABT) and topology-based (TBT)

Task Taxonomy for Graph Visualization

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ABSTRACT

tasks used in those studies. Our goal is to define a list of tasks for graph visualization that has enough detail and specificity to be useful to: 1) designers who After making those two lists, we considered the set of low-level want to improve their system and 2) to evaluators who want to Visual Analytics tasks proposed by Amar et al. [2]. These tasks compare graph visualization systems. In this paper, we suggest a were extracted from a corpus of questions about tabular data. We realized that our tasks all seem to be compound tasks made up of list of tasks we believe are commonly encountered while analyzing graph data. We define graph specific objects and Amar *et al*'s primitive tasks applied to the graph objects. When demonstrate how all complex tasks could be seen as a series of some tasks could not be represented with those tasks and objects, low-level tasks performed on those objects. We believe that our we added either an object or a low-level task. In this paper, we taxonomy, associated with benchmark datasets and specific tasks, demonstrate how all complex tasks could be seen as a series of would help evaluators generalize results collected through a series low-level tasks performed on those objects. of controlled experiments.

Categories and Subject Descriptors H.5.2 [Information Interfaces and Presentation]: User Interfaces – Graphical user interfaces (GUI) Jean-Daniel Fekete, Nathalie Henry INRIA Futurs/LRI Bat. 490 Université Paris-Sud, 91405 ORSAY, France

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user studies of graph visualization techniques and extracted the tasks used in those studies.

2. GRAPH-SPECIFIC OBJECTS

A graph consists of two types of primitive elements, nodes and links. A subgraph of a graph G is a graph whose nodes and links are subsets of G. There are several meaningful subgraphs such as

Three Types of Graph Representations



Explicit (Node-Link)





Matrix

Implicit

Explicit Graph Representations

Node-link diagrams: vertex = point, edge = line/arc





Criteria for Good Node-Link Layout

Minimized edge crossings Minimized **distance** of neighboring nodes Minimized drawing area Uniform edge length Minimized edge **bends** Maximized angular distance between different edges Aspect ratio about 1 (not too long and not too wide) Symmetry: similar graph structures should look similar

list adapted from Battista et al. 1999
Conflicting Criteria





VS.

Uniform edge length





Force Directed Layouts

Physics model: edges = springs, vertices = repulsive magnets

Expander (pushing nodes apart)



(pulling nodes together)

_

Algorithm

Place Vertices in random locations While not equilibrium calculate force on vertex sum of pairwise repulsion of all nodes attraction between connected nodes move vertex by c * force on vertex



What happens when there are no links?



Properties

Generally good layout Uniform edge length Clusters commonly visible Not deterministic

Computationally expensive: $O(n^3)$ n² in every step, it takes about n cycles to reach equilibrium Limit (interactive): ~1000 nodes in practice: damping, center of gravity

http://bl.ocks.org/steveharoz/8c3e2524079a8c440df60c1ab72b5d03



Adress Computational Scalability: Multilevel Approaches



[Schulz 2004]

HOLA: Human-like Orthogonal Layout Study how humans lay-out a graph Try to emulate layout

Left: human, middle: conventional algo, right new algo



Graph 1



Initial





 $\hat{\mu}_1 = 0.00$

 $\bar{\mu}_1 = 0.00$

 $\tilde{\mu}_1=0.00$

Graph 2





 $\bar{\mu}_1 = 0.02$

 $\bar{\mu}_1 = 0.02$

 $\bar{\mu}_1 = 0.09$

Graph 3









 $\mu_1 = 0.00$

 $\mu_1=0.00$





┏—

 $\mu_1 = 0.00$

Graph 4







 $\bar{\mu}_1 = 0.00$





 $\bar{\mu}_{1}=0.00$



Human 2nd

Human 1st

yFiles

HOLA









 $\hat{\mu}_2 = 0.48$







 $\bar{\mu}_1=0.51,\,\bar{\mu}_2=0.41$

 $\bar{\mu}_1=0.25,\,\bar{\mu}_2=0.21$



 $\bar{\mu}_2 = 0.49$

 $P_1 = 0.59$



P ф---0-Q-O

 $\mu_1=0.33,\,\mu_2=0.10$













 $\bar{\mu}_1=0.21,\,\bar{\mu}_2=0.11$

Graphs in 3D

Why, why not visualize graphs in 3D?

Why, why not use AR/VR?



Styled / Restricted Layouts

Circular Layout Node ordering Edge Clutter



ca. 3% of all possible edges

ca. 6,3% of all possible edges

Reduce Clutter: Edge Bundling







Bundling Strength

Holten et al. 2006

Bundling Strength

tension: -





Michael Bostock

mbostock.github.com/d3/talk/20111116/bundle.html

Fixed Layouts

Can't vary position of nodes Edge routing important





Supernodes / Aggregation

Supernodes: aggregate of nodes

manual or algorithmic clustering



Aggregation



https://youtu.be/E1PVTitj7h0?t=57

Explicit Tree Visualization

Reingold– Tilford layout

http://billmill.org/pymagtrees/



Manipulating Aggregation Levels

First interactive tree manipulation



Douglas Engelbart 1968 - http://www.1968demo.org



(a) Drill-Down (b) Roll-Up

(a) Unbalanced Drill-Down

"The mother of all demos" https://www.youtube.com/watch?v=yJDv-zdhzMY

Tree Interaction, Tree Comparison





Explicit Representations

- Pros:
 - able to depict all graph classes
 - can be customized by weighing the layout constraints
 - very well suited for TBTs, if also a suitable layout is chosen
- Cons:
 - computation of an optimal graph layout is in NP (even just achieving minimal edge crossings is already in NP) even heuristics are still slow/complex (e.g., naïve spring embedder is in O(n3)) has a tendency to clutter (edge clutter, "hairball")

Design Critique

Connected China



https://goo.gl/YXkWYX

http://china.fathom.info/





Instead of node link diagram, use adjacency matrix





Examples:



ABCDE



HJ Schulz 2007



Well suited for neighborhood-related TBTs



Not suited for path-related TBTs

van Ham et al. 2009 Shen et al. 2007



Order Critical!





Pros:

can represent all graph classes except for hypergraphs puts focus on the edge set, not so much on the node set simple grid -> no elaborate layout or rendering needed well suited for ABT on edges via coloring of the matrix cells well suited for neighborhood-related TBTs via traversing rows/columns

Cons:

quadratic screen space requirement (any possible edge takes up space) not suited for path-related TBTs

Special Case: Genealogy





Hybrid Explicit/Matrix



NodeTrix [Henry et al. 2007]

Problem #1: used screen real estate is quadratic in the number of nodes Solution approach: hierarchization of the representation



[van Ham et al. 2009]

Problem #1: used screen real estate is quadratic in the number of nodes Solution approach: hierarchization of the representation





[van Ham et al. 2009]

Higher-Order Connectivity

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[Kerzner et al., Graffinity, 2017]
Multivariate Networks

What is a Multivariate Network?



Challenge: Consider topology and attributes simultaneously

Node	Year	Citations	Туре	•••
Α	2006	13	Journal	•••
В	2009	36	Conference	•••
С	2017	5	Journal	•••
•••	•••	•••	•••	

Networks and Attributes

Attributes can influence topology Path can be slow / blocked best route when driving depends on traffic biological network depends on many factors

Show all attributes / many attributes

Show selected nodes / small network

few attributes



Multivariate Network Visualization Strategies



Encoding



Small Multiples

Multiple Coordinated Views

L. п. Layout Adaption

Matrices

Easy to encode edge attributes in cells Easy to encode node attributes adjacent to matrix Common pros and cons of matrices





[Henry and Fekete, MatrixExplorer, 2006]

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•	Bemidji	MN	BJI			
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•	Grand Forks	ND	GFK			
•	Devils Lake	ND	DVL			
•	Cedar Rapids	IA	CID			
•	Jamestown	ND	JMS			
•	Minot	ND	MOT			
•	Rapid City	SD	RAP			
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[Kerzner et al., Graffinity, 2017]

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On-Node Encoding

Canonical way to visualize single attribute. Widely supported. Ideal for topology-attribute interaction **Tricky for multiple attributes**



[McDonnel2009]









[Gehlenborg2010]







On-Node Encoding for Aggregates



[van den Elzen and van Wijk, 2014]



Small Multiples

On-node encoding with small multiples Graphs tend to be small, combine with focus graph



[Lex et al., StratomeX, 2012]





[Barsky et al., Cerebral, 2008]









Multiple Coordinated Views

Can optimize for topology and attributes at the same time Lacking whith regards to interplay



[Shannon et al., Cytoscape, 2003]





[Shannon et al., 2008]





Layout Adaption

Adapt node position in a node-link diagram so that it is well suited for attribute visualization

Layout driven by attributes





Layout driven by Topology





Fixed Layout

Node position defined by attribute values.

Focus on relationship of limited number of attributes **Topology hard to read**



Layout driven by attributes



by **Topology**

Linearization Strategy: Layout that enables juxtaposition with attribute visualizations

Complete Linearization: Pathline



[Meyer et al, Pathline, 2010]

Layout driven by attributes



- **Good solution for smaller** graphs
- Hard to keep track of topology for complex graphs





by Topology

Selective Linearization: enRoute





enRoute





Layout driven by attributes





Selective Linearization: Pathfinder



Show paths as ranked list Path



Path List Query Interface

k

Path Statistics

≡ ≡ ■ Path Topology

Active Page All



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Linearizing a Tree: Lineage



[Nobre et al, Lineage, 2018]

Layout driven by attributes



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Layout driven by Topology











Genealogy with ~400 members rendered with Progeny



Family Selector

ID #People

149 113

• 149 113

27251 404

42623 81

68939 244

176860 426

603481 181

791533 114

903988 58

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1. De-cycle and linearize graph

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2. Plot attributes in table

De-Cycling



De-Cycling





Linearization





Linearization







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Lots of missing data





People of Interest





One row for every person of interest



Others have to share a row

Aggregated Rows



More Aggressive: Hiding



Empty row



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Could we use something like Lineage for general Multivariate Networks?

Use a Spanning Tree to Visualize a Graph



[Lee et al., TreePlus, 2006]



[Munzner, H3Viewer, 1998]



Linearizing a Spanning Tree: Juniper



Spanning Tree

[Nobre et al, Juniper, Preprint 2018]

Layout driven by attributes

Edge Count Adjacency Table Matrix

Attribute Table

Layout driven by **Topology**





















Adjacency Matrix







Adjacency Matrix



Adjacency Matrix

Attribute Table



Adjacency Matrix

Attribute Table



Conclusions

Linearization & Juxtaposition are good options for visualizing Multivariate Graphs

- Many tasks are local, leverage the "Search, Show Context, **Expand on Demand**" principle for multivariate networks

Visualizing Edge Attributes

Good Choice: Matrix



Visualizing Edge Attributes

Quantitative: Width

Ordinal: Saturation

Nominal: Style, Color

Most common ways to encode edge attributes



Visualizing Edge Attributes

In practice very limited Example: Sashimi Plots



Amino acid codingNumber: 489 chr12:98995146-98995778



What's the Problem?





Junction View



Junction View - Group Comparison



Junction View - Group Comparison



Junction View - Group Comparison



Case Study: Leukemia vs Glioblastoma



Tree-Exercise

Tree Exercise

Here is part of a directory structure used for the material for this class and the relative file size.

datavis-17/

lectures/

Intro.key (110 MB)

perception/

Perception.key (113 MB)

Blindness.mov (15MB)

Data.key (12 MB)

Graphs.key (180 MB)

exams/

Exam1-solution.doc (5MB)

Exam1.doc (1MB)

exercise/

Graph.doc (3MB)

Graph-video.doc (210MB)

Sketch two different visualizations that show both, the directory structure and the size of the directories and the contained files.



Implicit Layouts for Trees



Implicit Layout Options

Treemap

Sunburst





Icicle Plot







Squarified Treemaps

Original Algorithm lead to thin slices Squarified treemaps [Bruls, Huizing, Van Wijk 2000]











Seeing Tree Structure



Unframed



Zoomable Treemap



Software

Mac: GrandPerspective Windows: Sequoia View





Example: Interactive TreeMap of a Million Items



Fekete et al. 2002

Sunburst: Radial Layout





[Sunburst by John Stasko, Implementation in Caleydo by Christian Partl]




Icicle Plot

				flare					
	S. S.			⊑ <u>t</u> :	animate	query	scale analytics	data	display physics
operator	data	legend controls	Visualization axis	Stats Sort Dates Arrays Colors Geometry palette Displays Maths Shapes	Tween Transition Easing Transitioner interpolate	Query methods	optimization cluster graph	converters	DirtySprite TextSprite Simulation NBodyForce
filter distortion encoder label layout	ree render TreeBuilder DataSprite ScaleBinding NodeSprite DataList Data	LegendRange Legend SelectionControl TooltipControl	CartesianAxes Axis	FibonacciHeap ColorPalette	Interpolator		AspectRatioBanker HierarchicalCluster MaxFlowMinCut	GraphMLConverter	
Distortion Labeler AxisLayout ForceDirectedLayout StackedAreaLayout CirclePackingLayout RadialTreeLayout NodeLinkTreeLayout									

Differences? Pros, Cons?







Implicit Representations

Pros:

large graphs

in most cases well suited for ABTs on the node set

depending on the spatial encoding also useful for TBTs

Cons:

can only represent trees

arranged (e.g., to reflect geographical positions) useless to pursue any task on the edges

- space-efficient because of the lack of explicitly drawn edges: scale well up to very

- since the node positions are used to represent edges, they can no longer be freely

Tree Visualization Reference



Graph Tools & Applications





The Open Graph Viz Platform

Gephi is a visualization and exploration platform for all kinds of networks and complex systems, dynamic and hierarchical graphs.

Runs on Windows, Linux and Mac OS X. Gephi is open-source and free.

Download FREE

Screenshots

Videos

Gephi 0.7 alpha

Release Notes | System Requirements

Features

Quick start

Learn More on Gephi Platform »



Gephi has been accepted again for Google Summer of Code! The program is the best way for students around the world to start contributing to an open-source project. Students, apply now for Gephi proposals. Come to the GSOC forum section and say Hi! to this topic.

Gephi http://gephi.org



Learn More »

Cytoscape

Open source platform for complex network analysis

http://www.cytoscape.org/



Cytoscape Web http://cytoscapeweb.cytoscape.org/

• • • • •	Feature Showcase Demo					
Cytoscape Web	This is a separate demo application, built around the Cytoscape We Because this showcase is complex, you may experience issues, suc					
Save file Open file S	Style ▼ Layout ▼					



NetworkX https://networkx.github.io/

NetworkX

NetworkX Home | Documentation | Download | Developer (Github)

High-productivity software for complex networks

NetworkX is a Python language software package for the creation, manipulation, and study of the structure, dynamics, and functions of complex networks.

Documentation all documentation

Examples using the library

Features

- Python language data structures for graphs, digraphs, and multigraphs.
- Nodes can be "anything" (e.g. text, images, XML records)
- Edges can hold arbitrary data (e.g. weights, time-series)
- · Generators for classic graphs, random graphs, and synthetic networks
- Standard graph algorithms
- Network structure and analysis measures
- Open source BSD license
- Well tested: more than 1800 unit tests, >90% code coverage
- Additional benefits from Python: fast prototyping, easy to teach, multi-platform



Reference all functions and methods Versions

Latest Release

1.8.1 - 4 August 2013 downloads | docs | pdf

Development

1.9dev github | docs | pdf build passing coverage 83%

Contact

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