### CS-5630 / CS-6630 Visualization Graphs Alexander Lex alex@sci.utah.edu





# **Applications of Graphs**



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## **Graph Visualization Case Study**



## Graph Theory Fundamentals



Hypergraph



Bipartite Graph



### Königsberg Bridge Problem (1736)



Want to make \$1 million? Find an O(n<sup>k</sup>) algorithm to find Hamiltonian Paths (path that visits each vertex exactly once) - example of P vs. NP problem.

# Graph Terms (1)

A graph **G(V,E)** consists of a set of **vertices V** (also called nodes) and a

set of **edges E** connecting these vertices.





# Graph Terms (2)

A simple graph G(V,E) is a graph which contains **no multi-edges** and **no loops** 



Not a simple graph!→ A *general graph* 

# Graph Terms (3)

A directed graph (digraph) is a graph that discerns between the edges  $A \rightarrow B$  and  $A \rightarrow B$ .

A hypergraph is a graph with edges connecting any number of vertices.



Hypergraph Example

# Graph Terms (4)

### Independent Set G contains no edges

### Clique G contains all possible edges



### Independent Set



### Clique

# **Graph Terms (5)**

### **Path** G contains only edges that can be consecutively traversed

*Tree* G contains no cycles

*Network* G contains cycles



Path





# Graph Terms (6)

### *Unconnected graph* An edge traversal starting from a given vertex cannot reach any other vertex.

### Articulation point

Vertices, which if deleted from the graph, would break up the graph in multiple sub-graphs.



Unconnected Graph



Articulation Point (red)

# Graph Terms (7)

### **Biconnected graph** A graph without articulation points.

### **Bipartite graph** The vertices can be partitioned in two independent sets.



**Bipartite Graph** 

### Tree A graph with no cycles - or: **A collection of nodes** contains a root node and 0-n subtrees subtrees are connected to root by an edge







**Binary Trees Contains no nodes, or** Is comprised of three disjoint sets of nodes: a root node, a binary tree called its left subtree, and a binary tree called its right subtree





## Different Kinds of Graphs

### Over 1000 different graph classes





### A. Brandstädt et al. 1999

# Graph Measures

Node degree deg(x) The number of edges being incident to this node. For

**Diameter of graph G** The longest shortest path within G.

Pagerank

count number & quality of links

# directed graphs indeg/outdeg are considered separately.



# Graph Algorithms (1)

### Traversal: Breadth First Search, Depth First Search



- generates neighborhoods
- hierarchy gets rather wide than deep
- solves single-source shortest paths (SSSP)



- classical way-finding/back-tracking strategy
- tree serialization
- topological ordering

## Hard Graph Algorithms (NP-Complete)

- Longest path
- Largest clique
- Maximum independent set (set of vertices in a graph, no two of which are adjacent)
- Maximum cut (separation of vertices in two sets that cuts most edges)
- Hamiltonian path/cycle (path that visits all vertexes once)
- Coloring / chromatic number (colors for vertices where no adjacent v. have same color)
- Minimum degree spanning tree

### Graph and Tree Visualization

## Setting the Stage



How to decide which **representation** to use for which **type of** graph in order to achieve which kind of goal?

## **Different Kinds of Tasks/Goals**

- **Localize** find a single or multiple nodes/edges that fulfill a given property • ABT: Find the edge(s) with the maximum edge weight.
  - TBT: Find all adjacent nodes of a given node.

### **Quantify** – count or estimate a numerical property of the graph

- ABT: Give the number of all nodes.
- TBT: Give the indegree (the number of incoming edges) of a node.

- Sort/Order enumerate the nodes/edges according to a given criterion • ABT: Sort all edges according to their weight.
  - TBT: Traverse the graph starting from a given node.

### Two principal types of tasks: attribute-based (ABT) and topology-based (TBT)

### Three Types of Graph Representations



### Explicit (Node-Link)





Matrix

Implicit

## **Explicit Graph Representations**

Node-link diagrams: vertex = point, edge = line/arc





## Criteria for Good Node-Link Layout

Minimized edge crossings Minimized **distance** of neighboring nodes Minimized drawing area Uniform edge length Minimized edge **bends** Maximized angular distance between different edges Aspect ratio about 1 (not too long and not too wide) Symmetry: similar graph structures should look similar

list adapted from Battista et al. 1999

## **Conflicting Criteria**

Minimum number of edge crossings



VS.

Uniform edge length





Schulz 2004

## Force Directed Layouts

Physics model: edges = springs, vertices = repulsive magnets in practice: damping

Computationally <sup>Expander</sup> (pushing nodes apart) expensive: O(n<sup>3</sup>) Limit (interactive): ~1000 nodes



(pulling nodes together)

\_\_\_



### Giant Hairball

### Adress Computational Scalability: Multilevel Approaches



[Schulz 2004]

## Abstraction/Aggregation



30k nodes



## **Collapsible Force Layout**

Supernodes: aggregate of nodes

manual or algorithmic clustering





### **HOLA: Human-like Orthogonal** Layout Study how humans lay-out a graph Try to emulate layout

Left: human, middle: conventional algo, right new algo



### Graph 1



Initial





 $\bar{\mu}_1 = 0.00$ 

 $\tilde{\mu}_1=0.00$ 

 $\bar{\mu}_1 = 0.00$ 

Graph 2





 $\bar{\mu}_1 = 0.02$ 

 $\bar{\mu}_1 = 0.02$ 

 $\bar{\mu}_1 = 0.09$ 

Graph 3









 $P_1 = 0.00$ 

 $\mu_1 = 0.00$ 

 $\mu_1 = 0.00$ 









 $\bar{\mu}_1 = 0.00$ 

Graph 5



### Human 2nd

Human 1st

yFiles

HOLA









 $\hat{\mu}_2 = 0.48$ 







 $\bar{\mu}_1=0.51,\,\bar{\mu}_2=0.41$ 

 $\bar{\mu}_1=0.25,\,\bar{\mu}_2=0.21$ 



 $\bar{\mu}_2 = 0.49$ 

 $P_1 = 0.59$ 

 $\hat{\mu}_1 = 0.58$ 





 $\mu_1=0.33,\,\mu_2=0.10$ 











 $\hat{\mu}_1 = 0.59$ ,  $\hat{\mu}_2 = 0.59$ 

 $\bar{\mu}_1=0.21,\,\bar{\mu}_2=0.11$ 

## **Styled / Restricted Layouts**

**Circular Layout** Node ordering **Edge Clutter** 



ca. 3% of all possible edges

ca. 6,3% of all possible edges
### Example: MizBee



[Meyer et al. 2009]

# **Reduce Clutter: Edge Bundling**







Bundling Strength

Holten et al. 2006

# Fixed Layouts

### Can't vary position of nodes Edge routing important





## **Bundling Strength**

tension: -





mbostock.github.com/d3/talk/20111116/bundle.html

Michael Bostock

## **Explicit Tree Visualization**

### Reingold– Tilford layout

http://billmill.org/pymagtrees/



## **Tree Interaction, Tree Comparison**





## Multivariate Graphs

## Node Attributes

### Coloring Glyphs -> Limited in scalability









# Small Multiples

### Cerebral [Barsky, 2008] Each dimension in its own window





# Data-driven node positioning

### GraphDice Nodes are laid out according to attribute values



[Bezerianos et al, 2010]



# Path Extraction & Multiple Views



## Experimental Data and

### Pathways

[Partl, BioVis '12]

real-world data mutation, etc.

- **Cannot account for variation found in**
- **Branches can be (in)activated due to** 

  - changed gene expression,
  - modulation due to drug treatment,





### How to visualize experimental data on pathways?

## Many Node Attributes

Node	Sample 1	Sample 2	Sample 3	•••
Α	0.55	0.95	0.83	•••
В	0.12	0.42	0.16	•••
С	0.33	0.65	0.38	•••
•••	•••	•••	•••	

Node	Sample 1	Sample 2	Sample 3	•••
Α	low	low	very high	•••
В	normal	low	high	•••
С	high	very low	normal	•••
•••	•••	•••	•••	



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## **Good Old Color Coding**

- 4.2 5.1 4.2 -3.4 Α
- 1.8 1.3 1.1 B 2.8
- -2.2 2.4 2.2 3.1 С
- -3 -2.8 1.6 1.0 D
- 0.3 -1.1 1.3 Ε 0.5
  - 0.3 1.8 -0.3 0.3







## **Challenge: Data Scale & Heterogeneity**

Large number of experiments Large datasets have more than 500 experiments **Multiple groups/conditions Different** types of data



## **Challenge: Supporting Multiple Tasks**

### **Two central tasks:**

- **Explore topology of pathway**
- **Explore the attributes of the nodes** (experimental data)
- **Need to support both!**



	Sample 1	Sample 2	Sample 3
Gene 1	1	1.1	0.4
Gene 2	2	0.5	1.2
Gene 3	1.4	0.2	0.5
Gene 4	0.3	0.5	0.7





## Concept



### enRoute



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Pathways
Pathway
Filter:
<none></none>
1 C donor
2-Oxocarboxylic acid
ABC transporters
ABC-family proteins
ACE Inhibitor Pathwa
Acetylcholine Synthes
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Adipocyte TarBase
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Adipogenesis
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Aflatoxin B1 metaboli
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AhR pathway
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## **Case Study: CCLE Data**





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## Design Critique

## **Connected China**



### https://goo.gl/YXkWYX

http://china.fathom.info/





Instead of node link diagram, use adjacency matrix





### Examples:







Well suited for neighborhood-related TBTs



### Not suited for path-related TBTs

van Ham et al. 2009 Shen et al. 2007



## Order Critical!





### Pros:

can represent all graph classes except for hypergraphs puts focus on the edge set, not so much on the node set simple grid -> no elaborate layout or rendering needed well suited for ABT on edges via coloring of the matrix cells well suited for neighborhood-related TBTs via traversing rows/columns

Cons:

quadratic screen space requirement (any possible edge takes up space) not suited for path-related TBTs

# Special Case: Genealogy





# Hybrid Explicit/Matrix



NodeTrix [Henry et al. 2007]

# Implicit Layouts



### Explicit (Node-Link)





Matrix

Implicit

# **Explicit vs. Implicit Tree Vis**



Fig. 2. (a) Explicit, node-link layout, (b) Implicit layout by inclusion, (c) Implicit Layout by overlap, (d) Implicit layout by adjacency.




Johnson and Shneiderman 1991

# Zoomable Treemap

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# Example: Interactive TreeMap of a Million Items



Fekete et al. 2002

## Sunburst: Radial Layout



[Sunburst by John Stasko, Implementation in Caleydo by Christian Partl]









Icicle Plot

http://hci.stanford.edu/jheer/files/zoo/ex/hierarchies/icicle.html

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http://hci.stanford.edu/jheer/files/zoo/ex/hierarchies/treemap.html



http://hci.stanford.edu/jheer/files/zoo/ex/hierarchies/pack.html Source: The Flare Toolkit http://flare.prefuse.org



http://hci.stanford.edu/jheer/files/zoo/ex/hierarchies/sunburst.html

# Implicit Representations

### Pros:

in most cases well suited for ABTs on the node set depending on the spatial encoding also useful for TBTs Cons:

can only represent trees

(e.g., to reflect geographical positions)

useless to pursue any task on the edges

spatial relations such as overlap or inclusion lead to occlusion

- space-efficient because of the lack of explicitly drawn edges: scale well up to very large graphs

since the node positions are used to represent edges, they can no longer be freely arranged



### **Tree Visualization Reference**

















Munzner 2014

# Graph Tools & Applications

# Gephi http://gephi.org



#### The Open Graph Viz Platform

Gephi is a visualization and exploration platform for all kinds of networks and complex systems, dynamic and hierarchical graphs.

Runs on Windows, Linux and Mac OS X. Gephi is open-source and free.

**Download FREE** 

Gephi 0.7 alpha

Release Notes | System Requirements

Features

Quick start

Learn More on Gephi Platform »





Screenshots

Videos



Gephi has been accepted again for Google Summer of Code! The program is the best way for students around the world to start contributing to an open-source project. Students, apply now for Gephi proposals. Come to the GSOC forum section and say Hi! to this topic.

Learn More »

# Cytoscape



### Open source pla



#### http://www.cytoscape.org/

### Cytoscape Web http://cytoscapeweb.cytoscape.org/

<b>•</b> • • • •	Feature Showcase Demo						
Cytoscape web	This is a separate demo application, built around the Cytoscape V Because this showcase is complex, you may experience issues, s						
Save file Open file S	Style ▼ Layout ▼						



### NetworkX https://networkx.github.io/

### NetworkX

NetworkX Home | Documentation | Download | Developer (Github)

#### High-productivity software for complex networks

NetworkX is a Python language software package for the creation, manipulation, and study of the structure, dynamics, and functions of complex networks.

**Documentation** all documentation

#### Examples using the library

#### Features

- Python language data structures for graphs, digraphs, and multigraphs.
- Nodes can be "anything" (e.g. text, images, XML records)
- Edges can hold arbitrary data (e.g. weights, time-series)
- Generators for classic graphs, random graphs, and synthetic networks
- Standard graph algorithms
- Network structure and analysis measures
- Open source BSD license
- Well tested: more than 1800 unit tests, >90% code coverage
- Additional benefits from Python: fast prototyping, easy to teach, multi-platform



**Reference** all functions and methods Versions

Latest Release

1.8.1 - 4 August 2013 downloads | docs | pdf

#### Development

1.9dev github | docs | pdf build passing coverage 83%

#### Contact

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