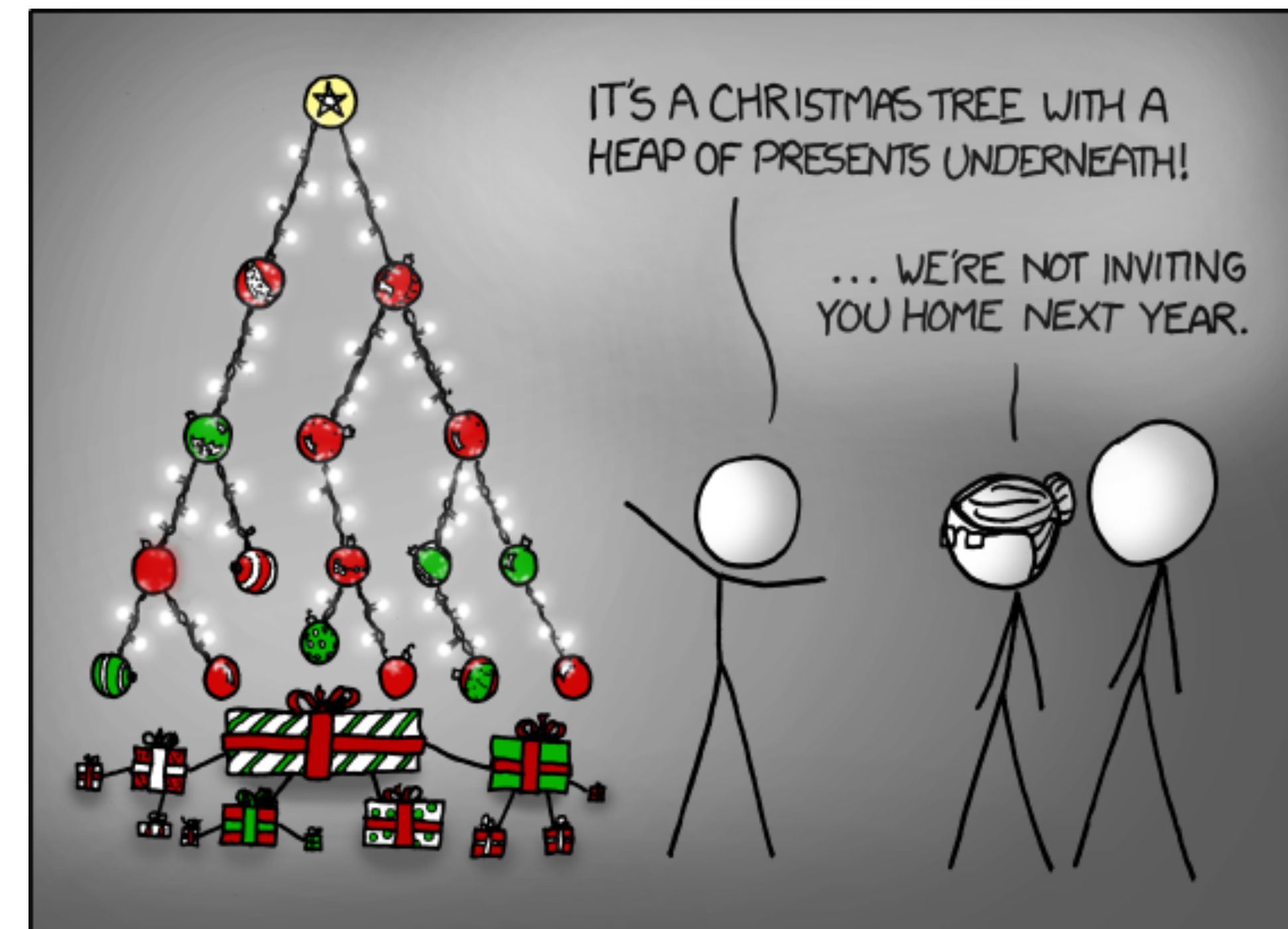


CS-5630 / CS-6630 Visualization for Data Science Networks

Alexander Lex
alex@sci.utah.edu



[xkcd]

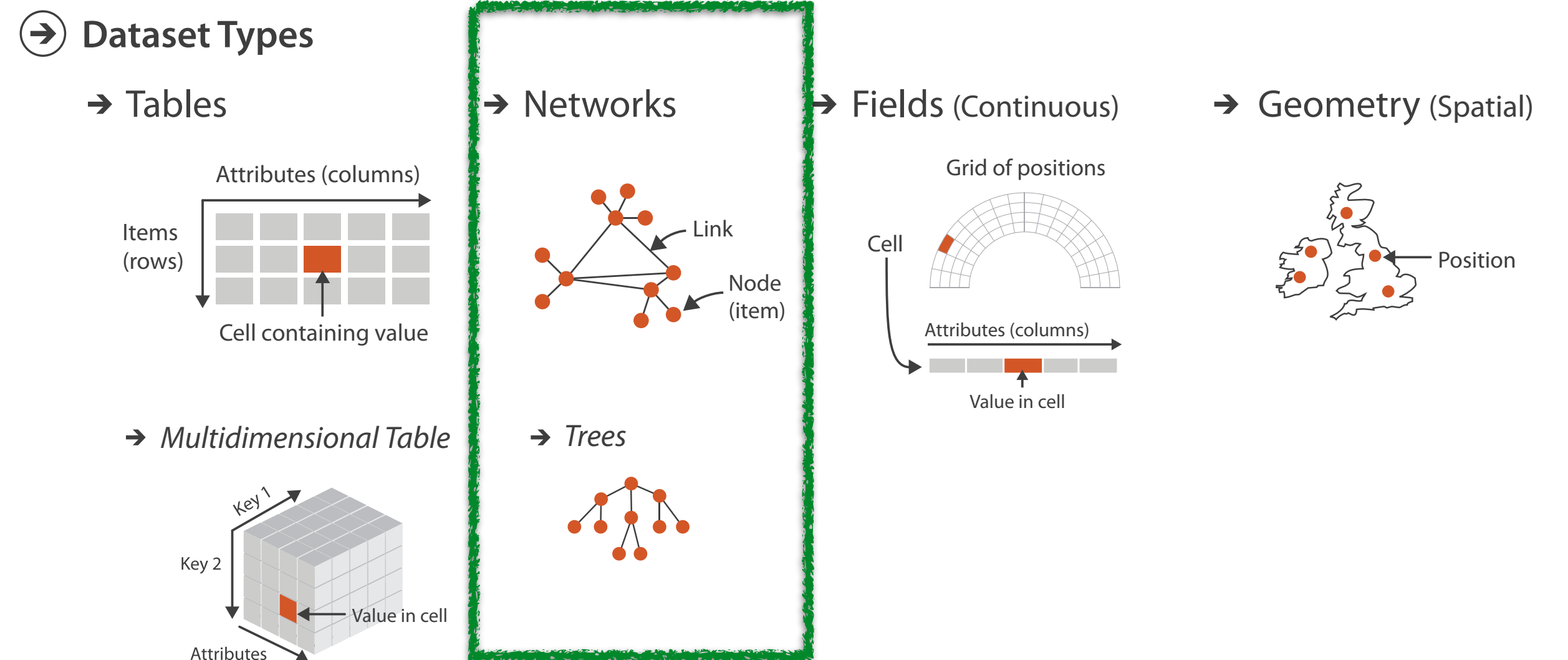
Networks and Graphs

Networks model relationships between items

Network vs Graph

Network: a specific instance
social network...

Graph: the generic term
graph theory...



Network Exercise

Nodes and Node Attributes

Author (# papers)

Carolina (6),

Miriah (42)

Alex (36),

Sean (8),

Marc (40)

Nils (51),

Silvia (110)

Links and Link Attributes

Co-author, co-author - # joint papers

Carolina, Alex - 2

Sean, Miriah - 7

Miriah, Alex - 2

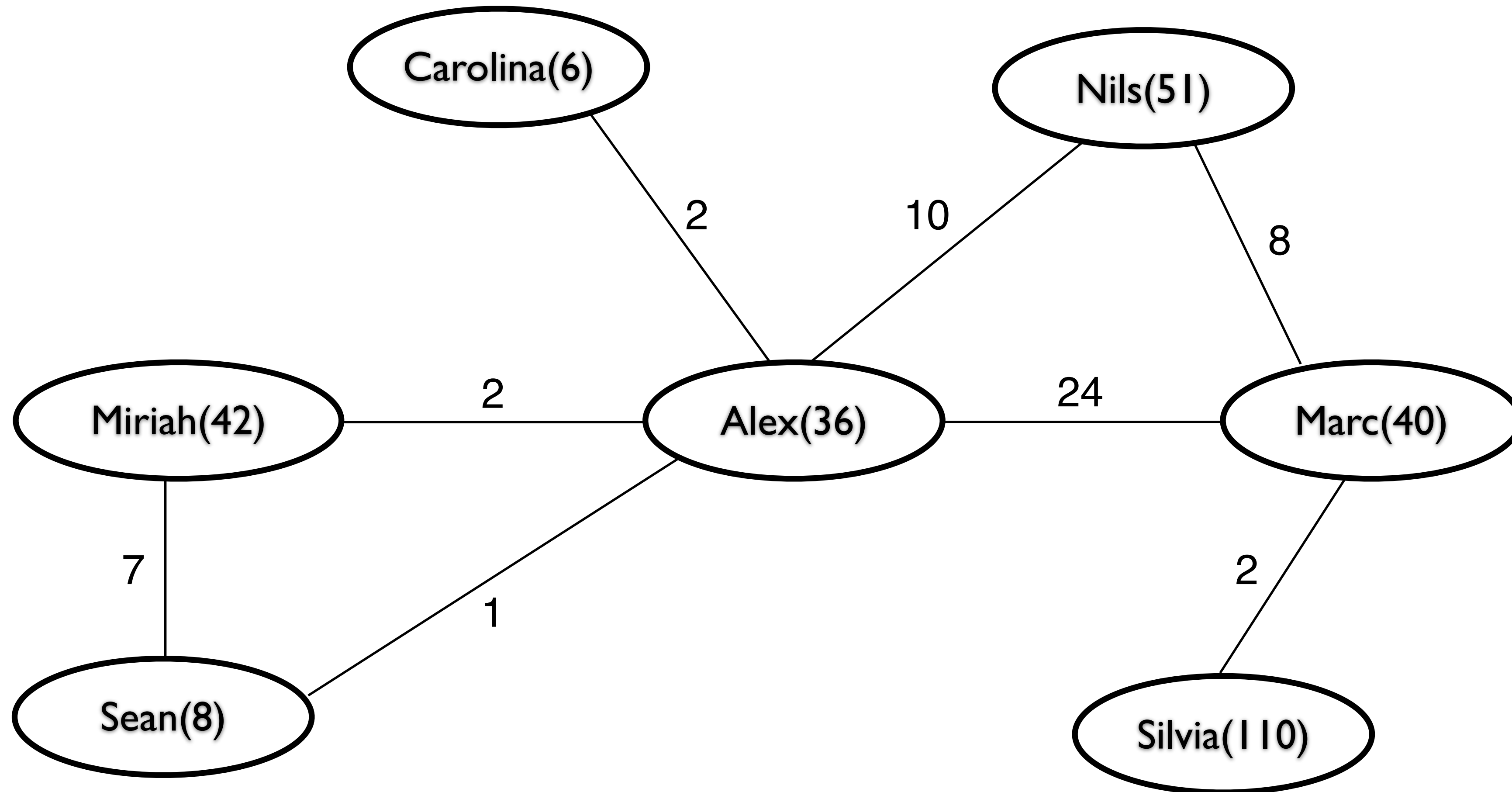
Alex, Sean - 1

Alex, Nils - 10

Alex, Marc - 24

Marc, Silvia - 1

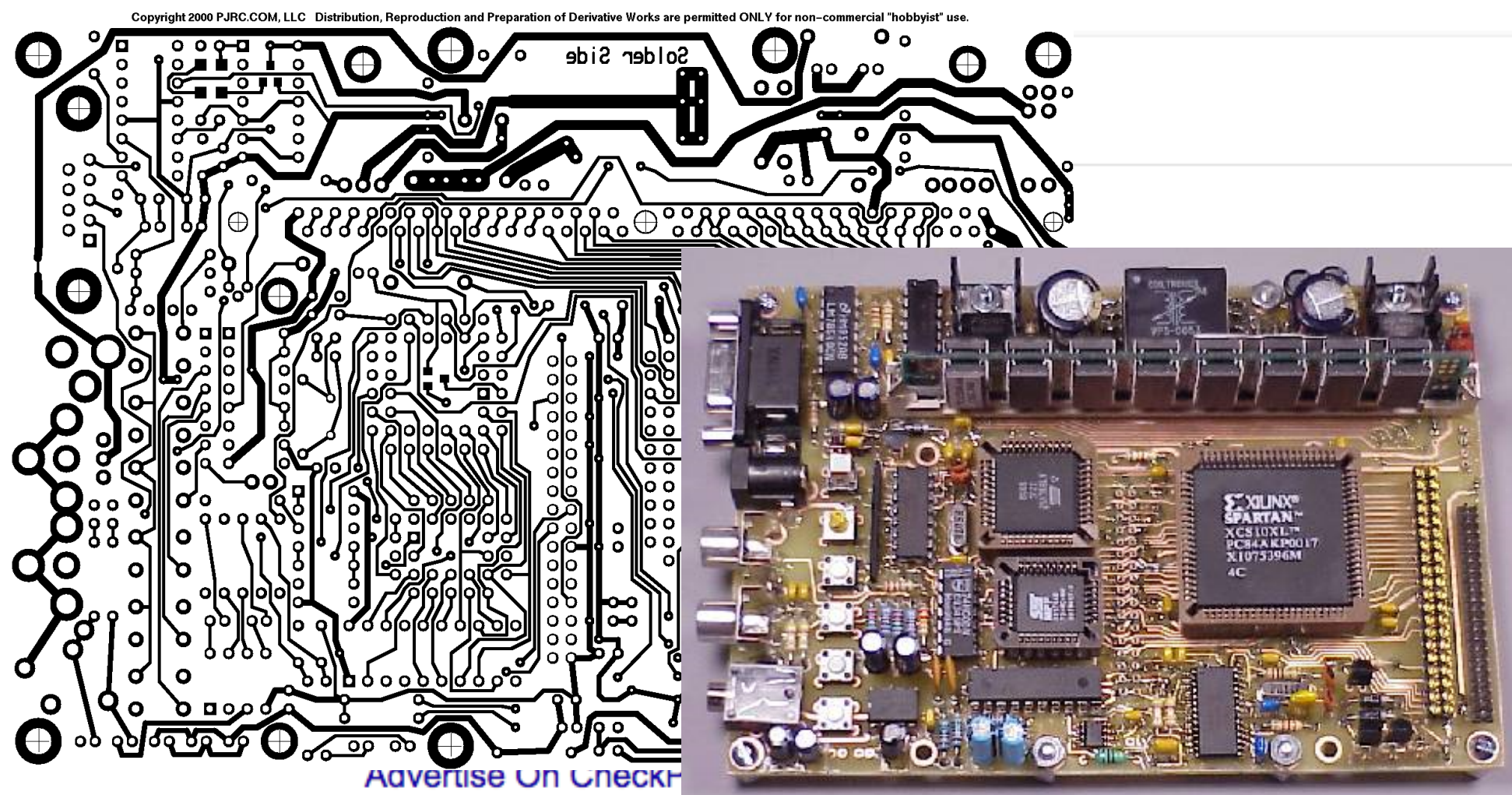
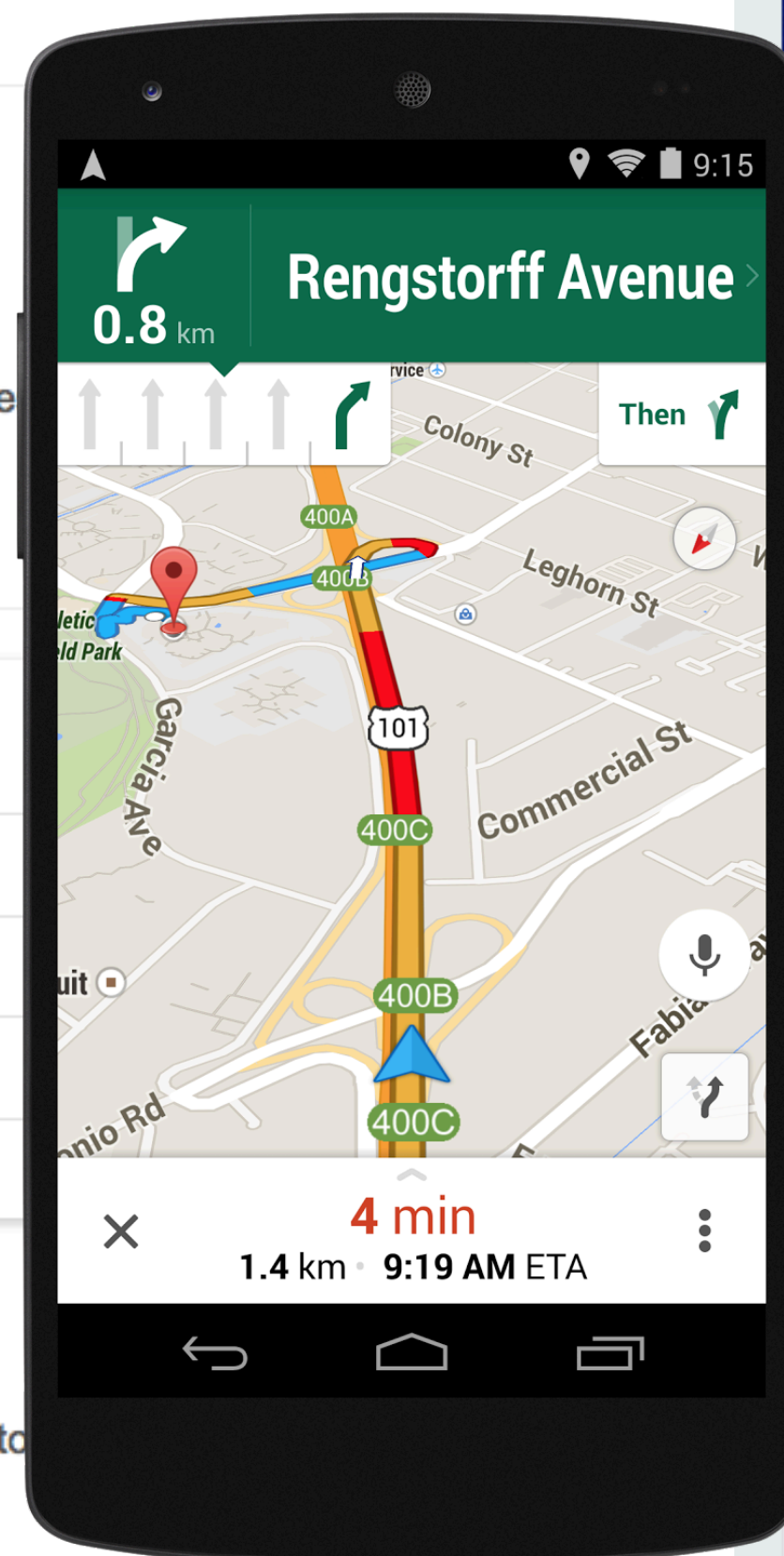
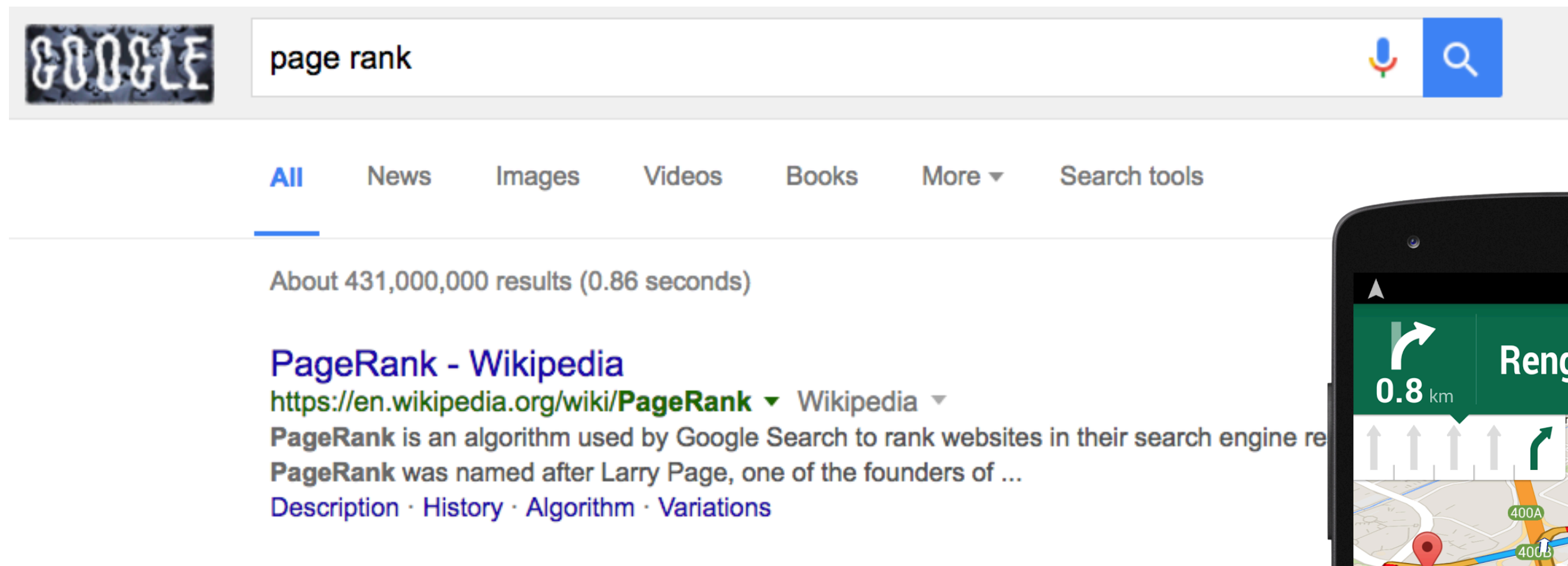
Marc, Nils - 8



	Carolina (6)	Miriah (42)	Alex (36)	Sean (8)	Marc (40)	Nils (51)	Silvia (110)
Carolina (6)			2				
Miriah (42)			2	7			
Alex (36)	2	2		1	14	10	
Sean (8)		7	1				
Marc (40)			14			8	1
Nils (51)			10		8		
Silvia (110)					1		

Applications of Networks

Without graphs, there would be none of these:





facebook

December 2010

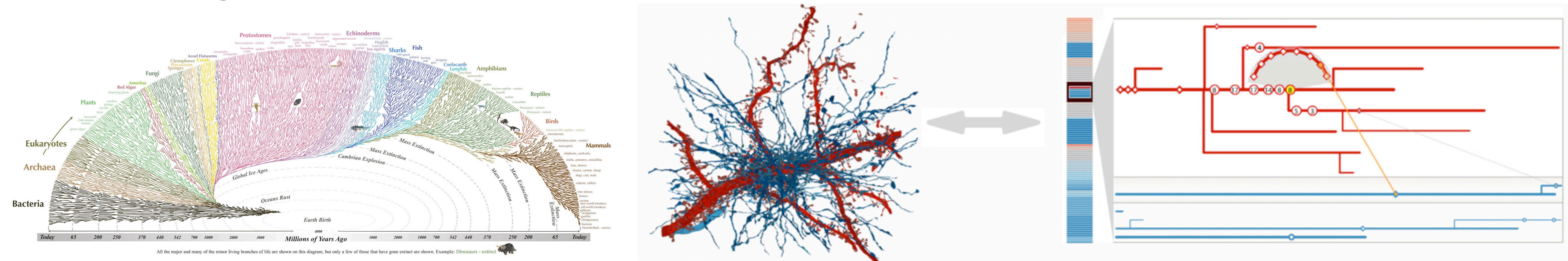
Biological Networks

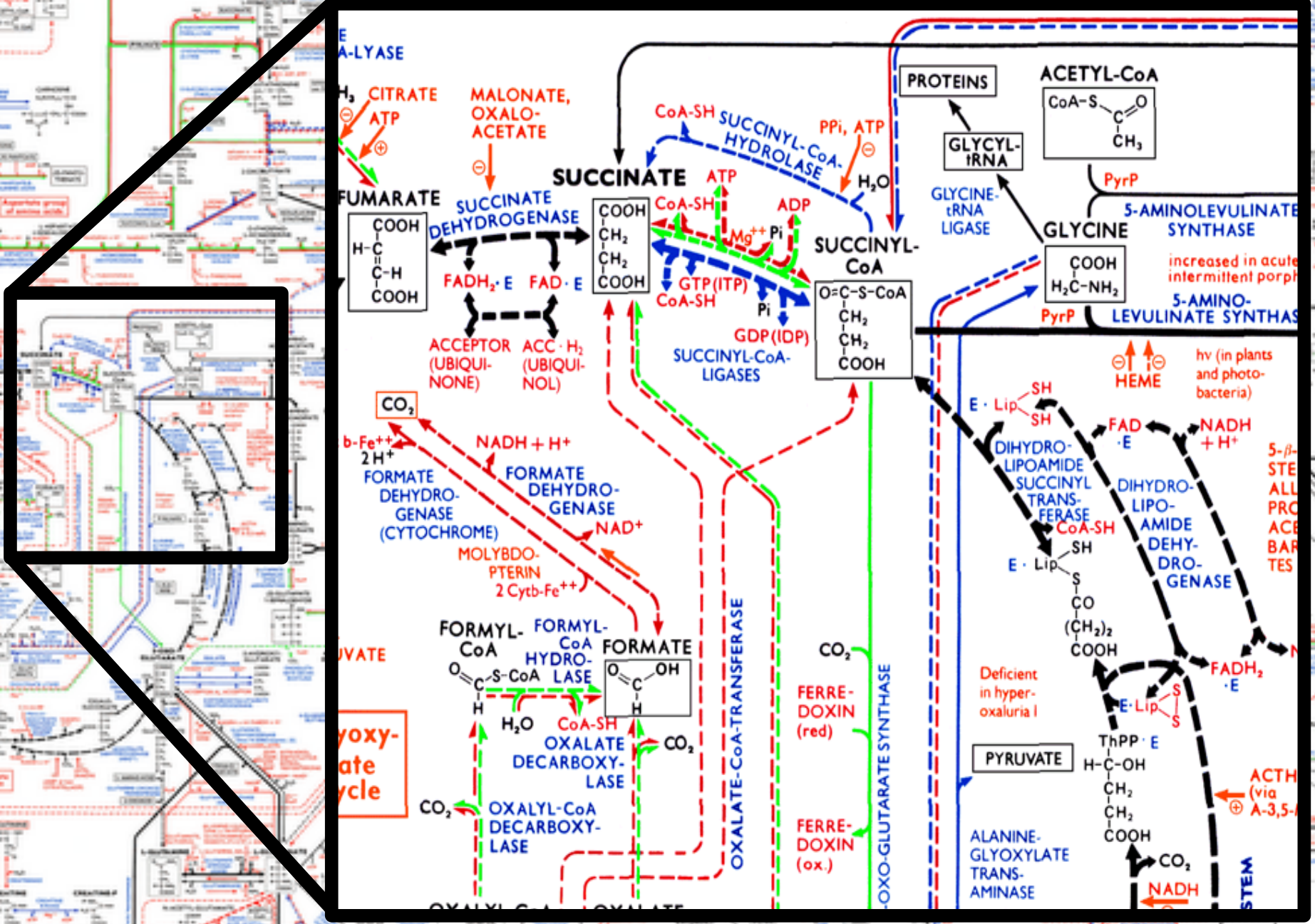
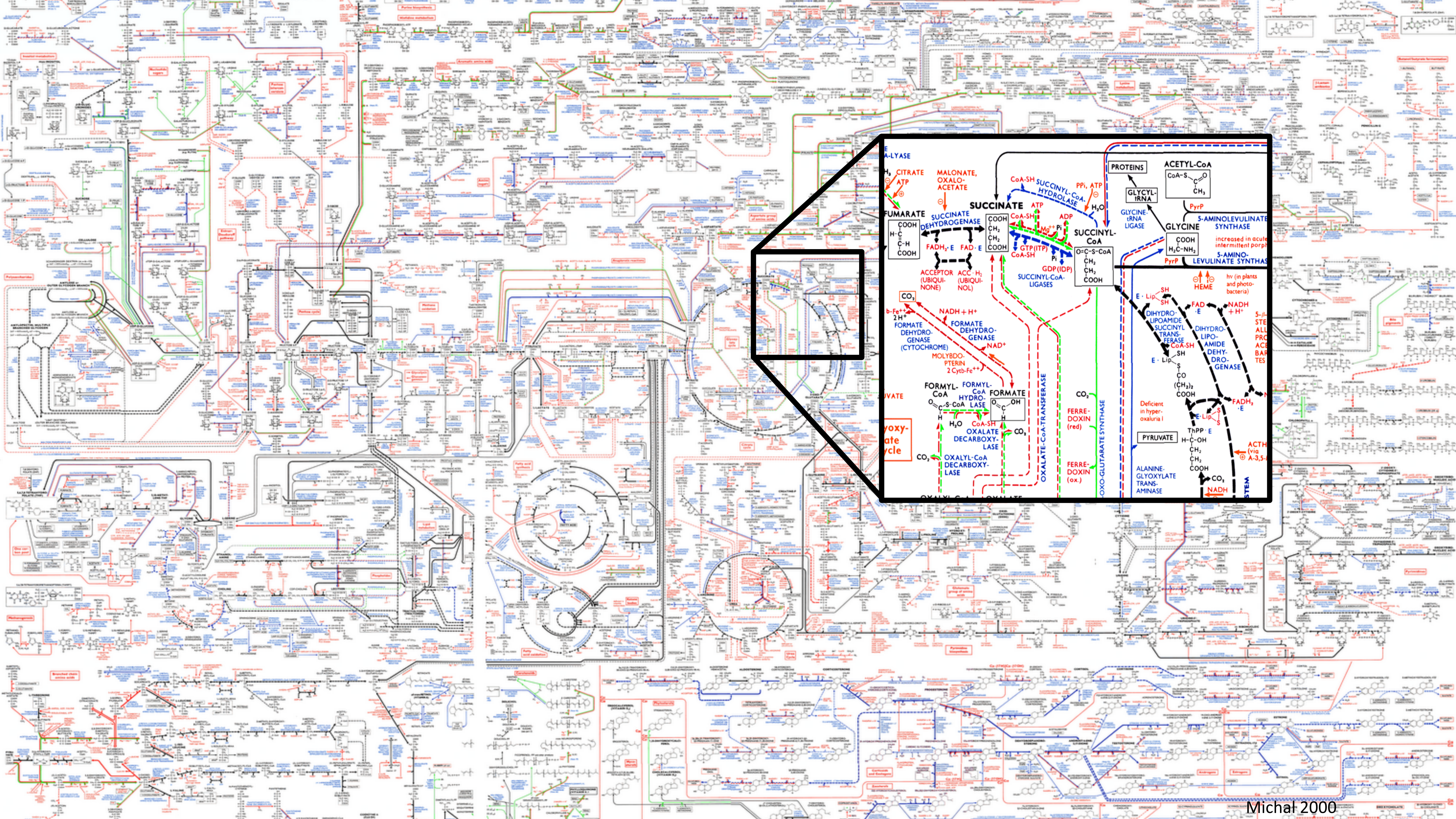
Interaction between genes, proteins and chemical products

The brain: connections between neurons

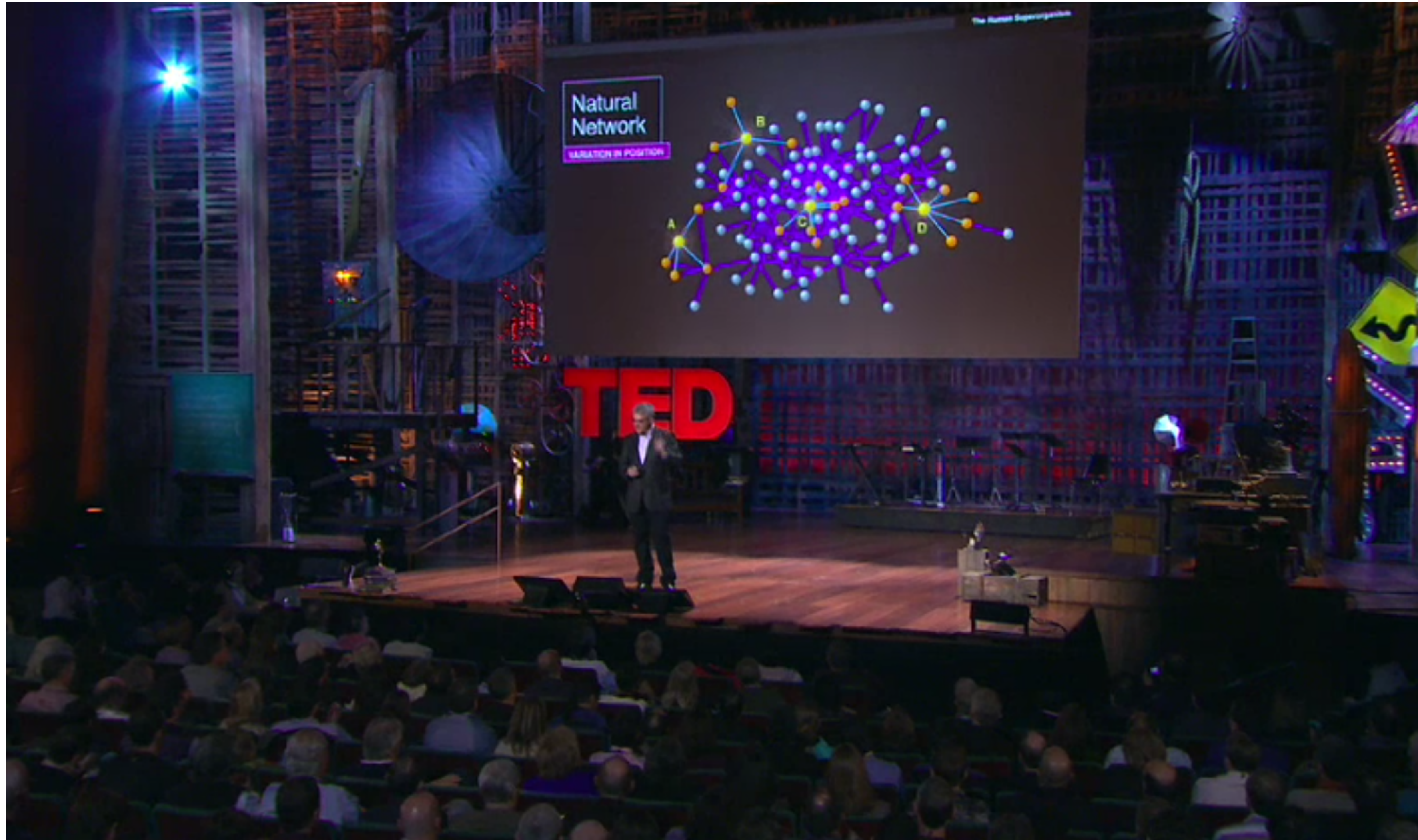
Your ancestry: the relations between you and your family

Phylogeny: the evolutionary relationships of life





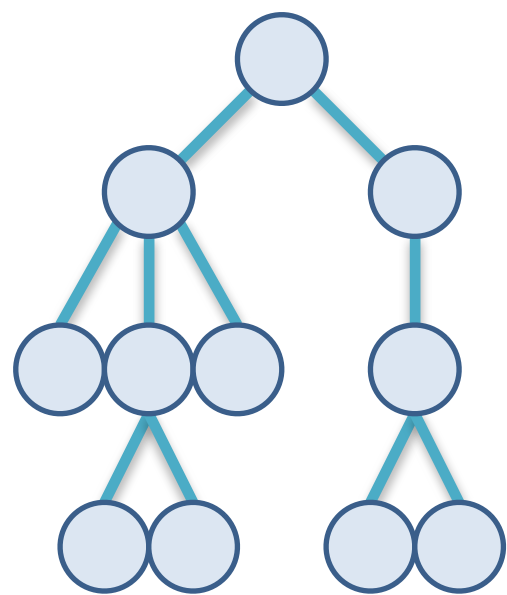
Graph Analysis Case Study



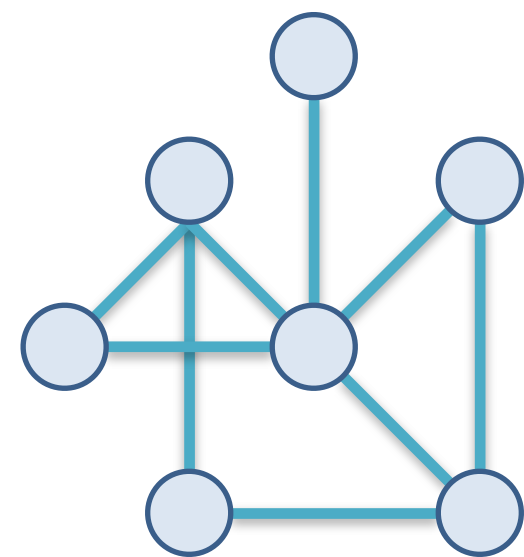
Graph Theory Fundamentals

See also “Network Science”, Barabasi
<http://barabasi.com/networksciencebook/chapter/2>

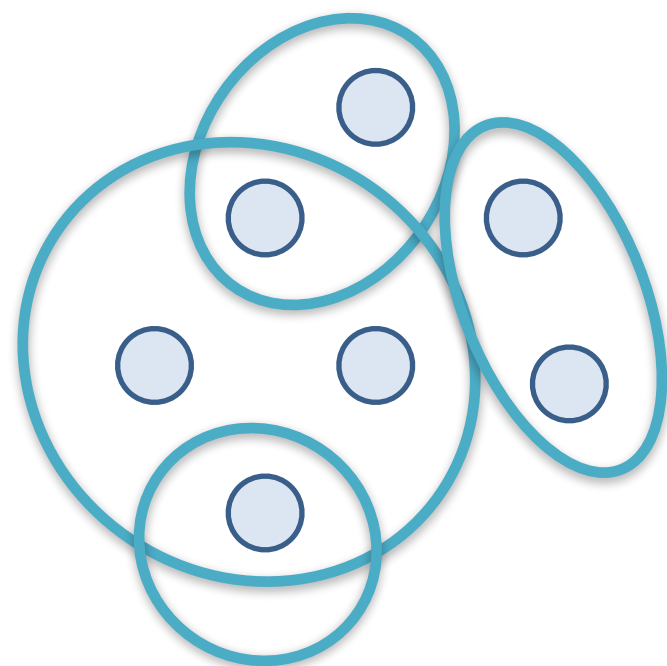
Tree



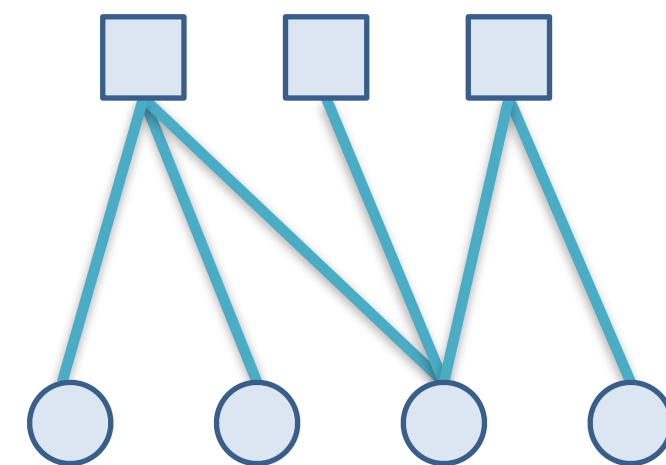
Network



Hypergraph

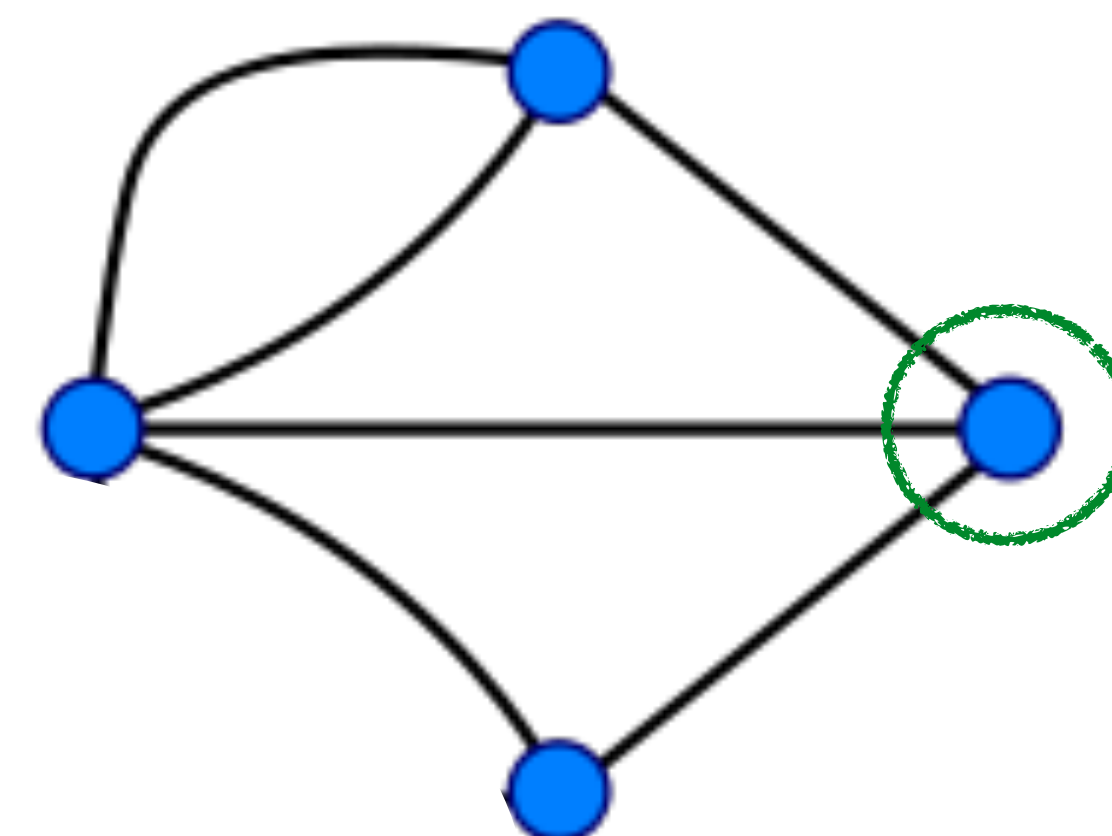
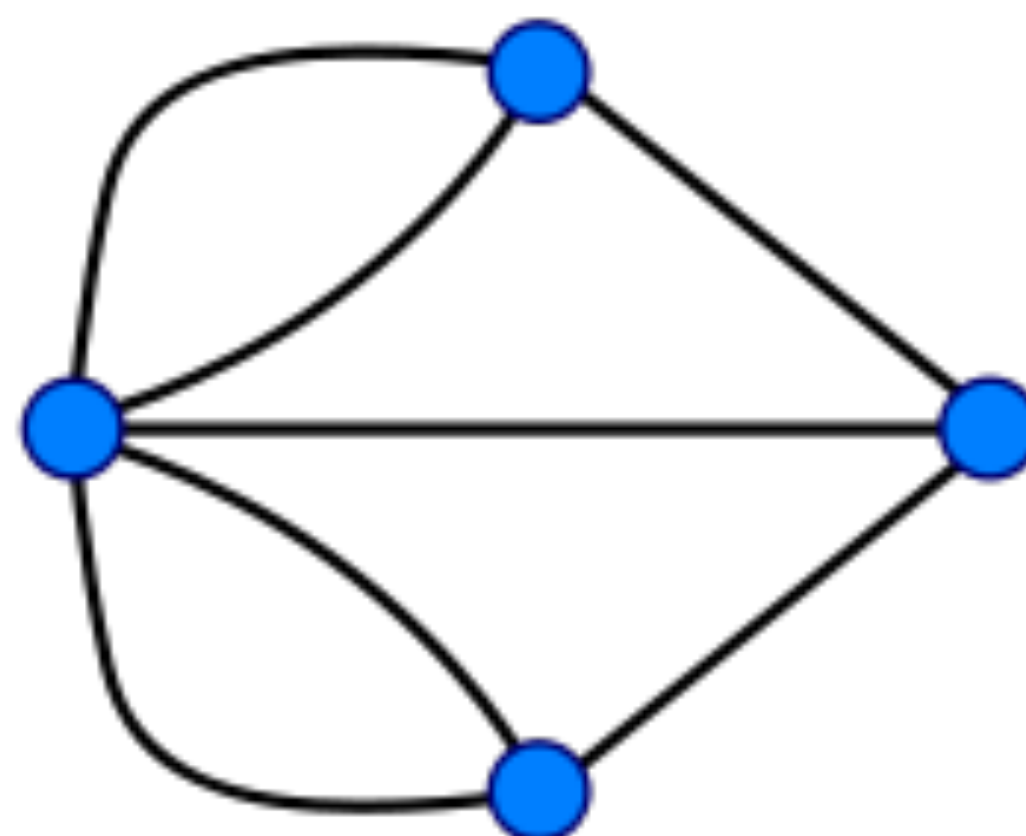
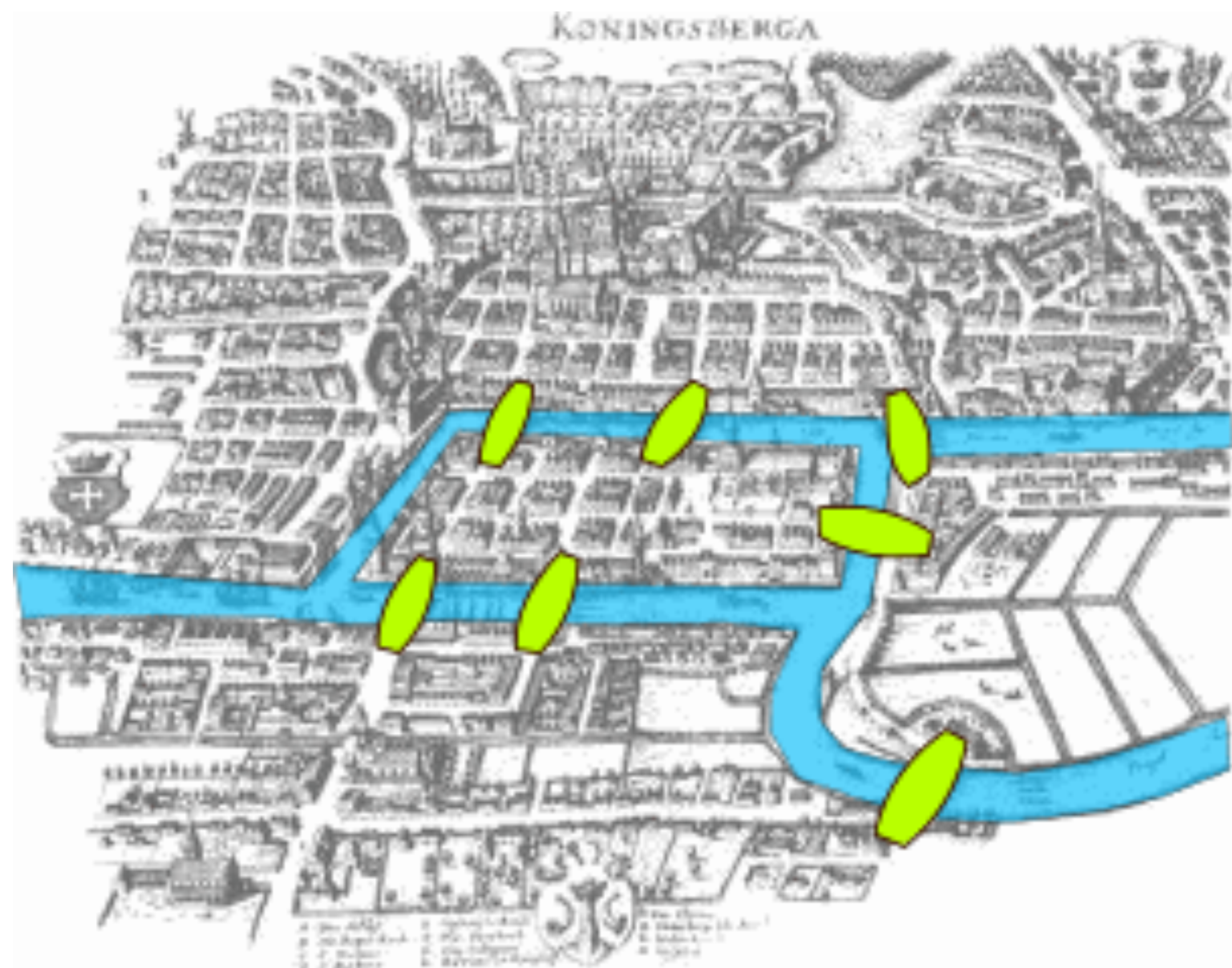


Bipartite Graph



§

Now Kaliningrad: historically German, now a Russian exclave
Can you take a walk and visit every land mass without crossing a bridge twice?

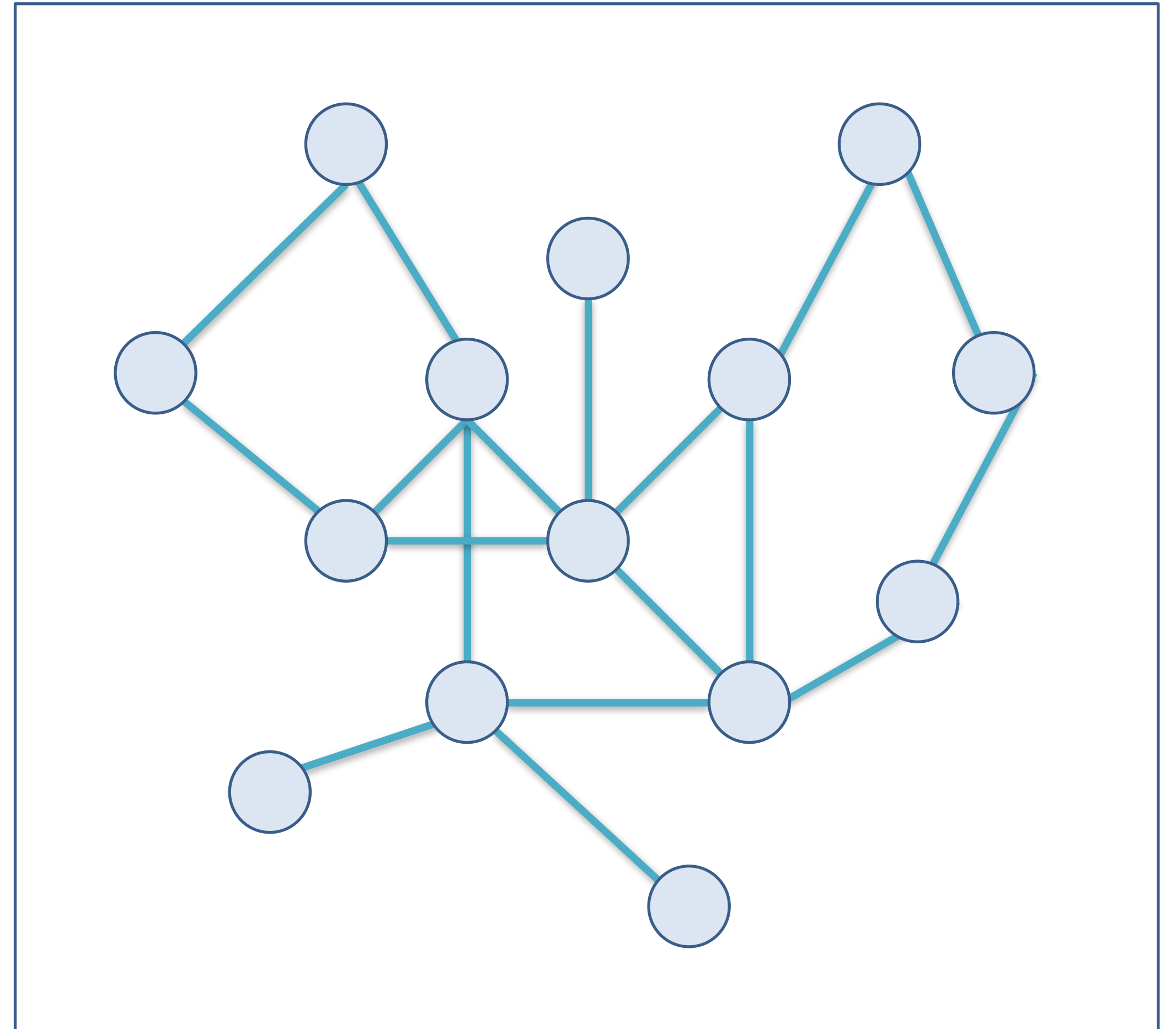


Leonhard Euler:
Only possible with a graph with at most two nodes with an odd number of links.
This graph has four nodes (all) with odd number of links.

Related: a “Hamiltonian path”, i.e., a path that visits each vertex exactly once

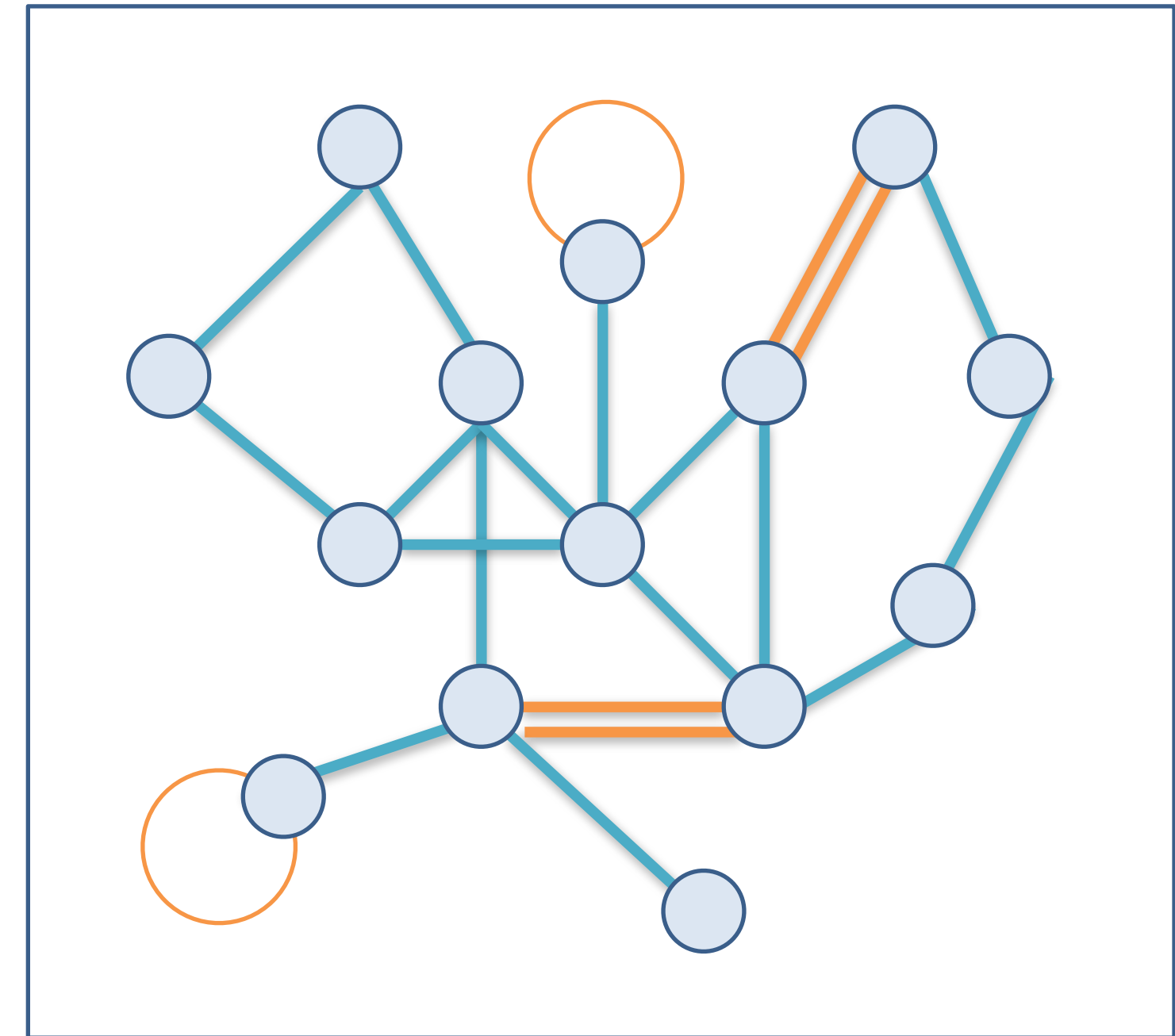
Graph Terms

A graph $G(V,E)$ consists of a set of **vertices** V (also called nodes) and a set of **edges** E (also called links) connecting these vertices.



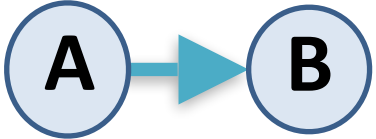
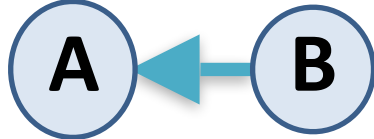
Graph Term: Simple Graph

A simple graph $G(V,E)$ is a graph which contains **no multi-edges** and **no loops**



Not a simple graph!
→ A *general graph*

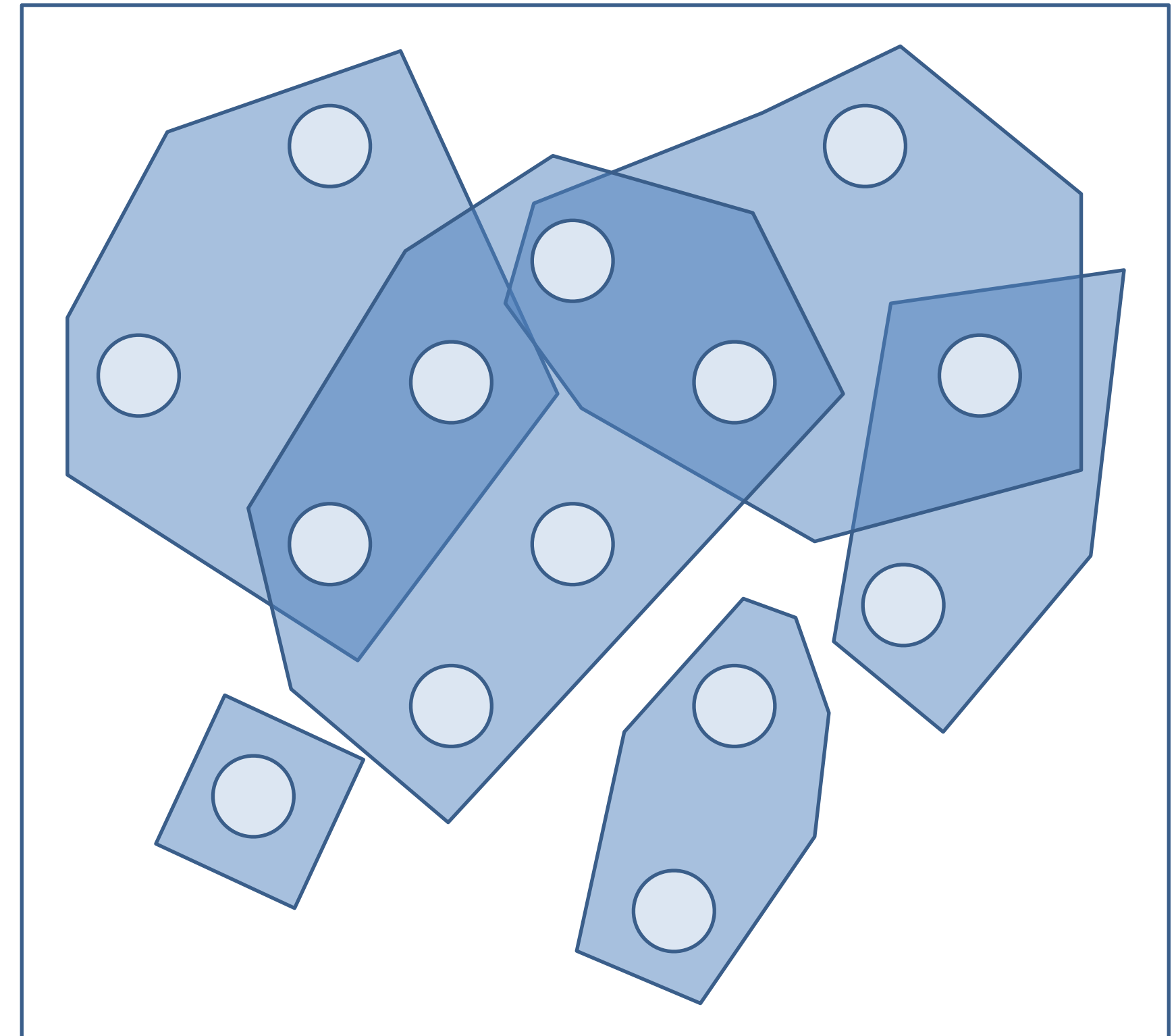
Graph Term: Directed Graph

A directed graph (digraph) is a graph that discerns between the edges  and .

Graph Terms: Hypergraph

A hypergraph is a graph with edges connecting any number of vertices.

Think of edges as sets.

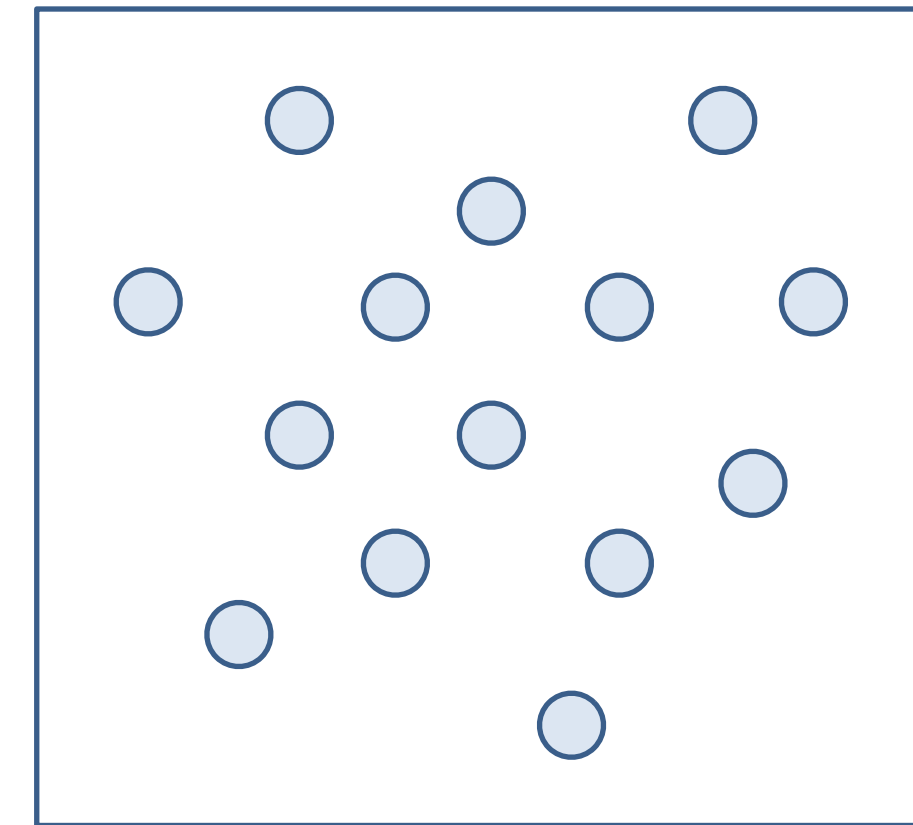


Hypergraph Example

Graph Terms

Independent Set

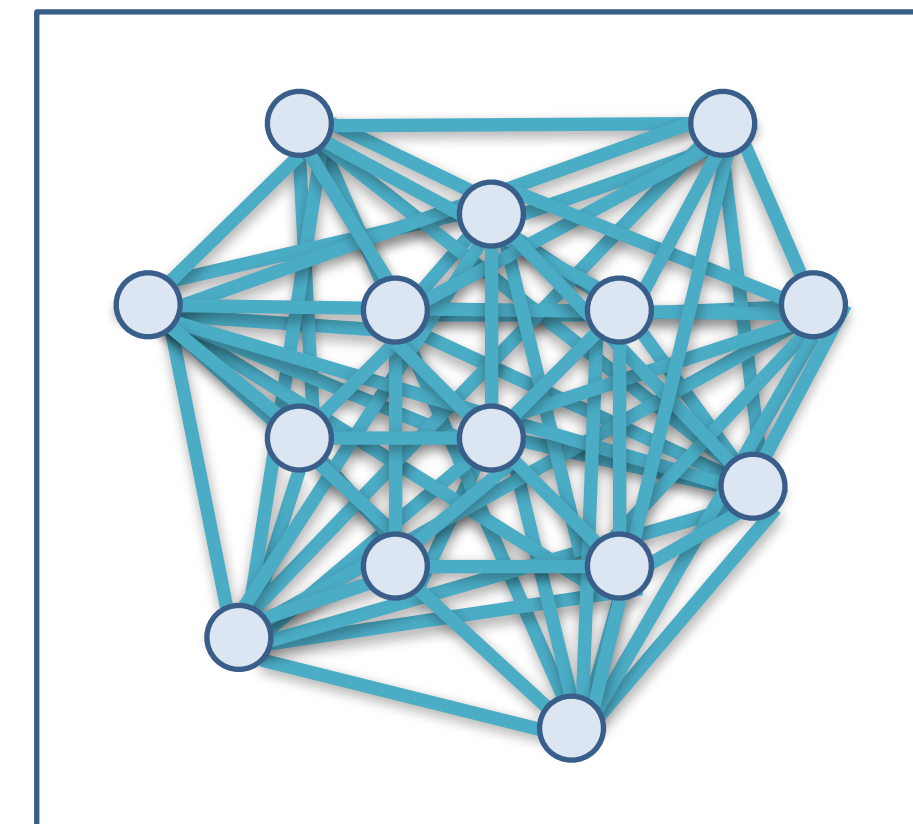
G contains no edges



Independent Set

Clique

G contains all possible edges



Clique

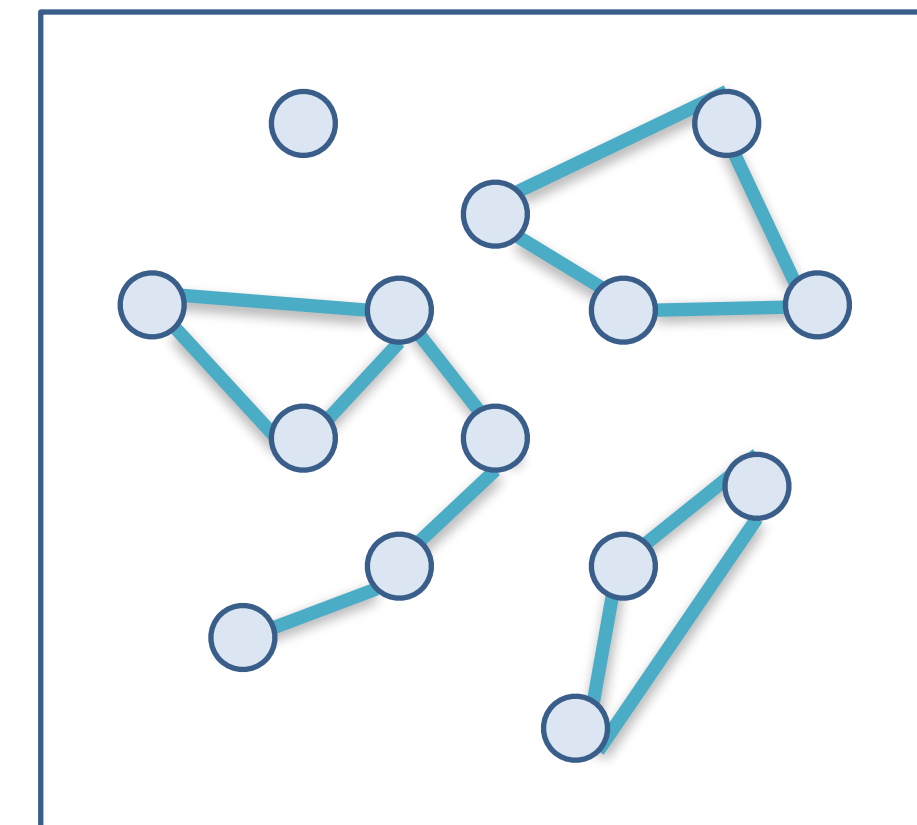
Unconnected Graphs, Articulation Points

Unconnected graph

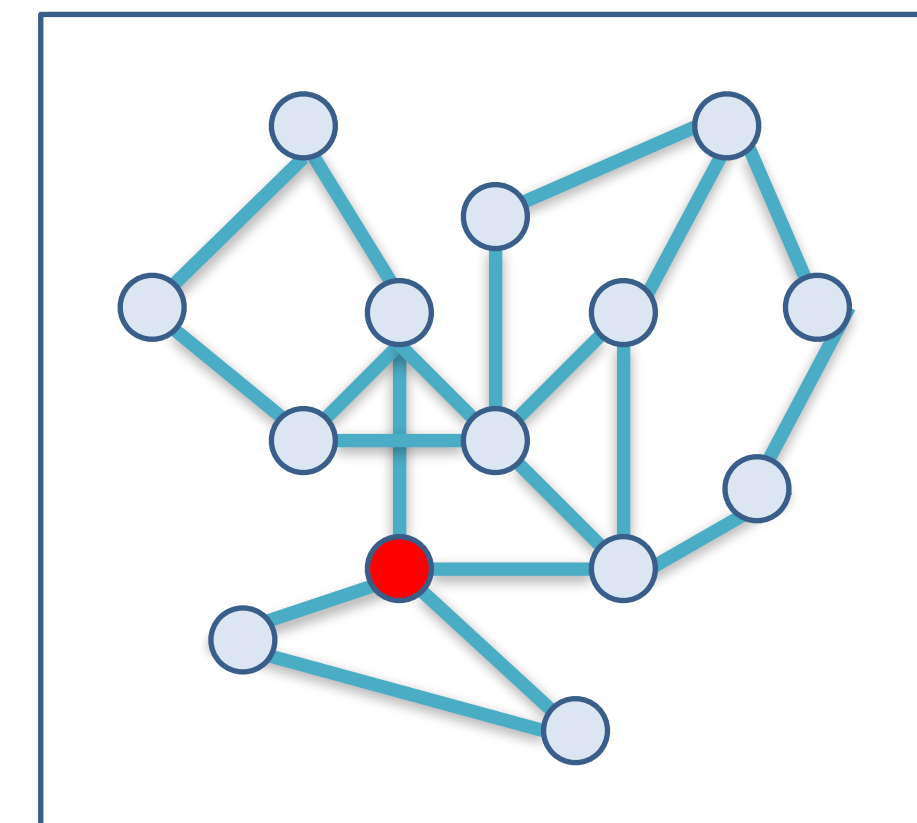
An edge traversal starting from a given vertex cannot reach any other vertex.

Articulation point

Vertices, which if deleted from the graph, would break up the graph in multiple sub-graphs.



Unconnected Graph

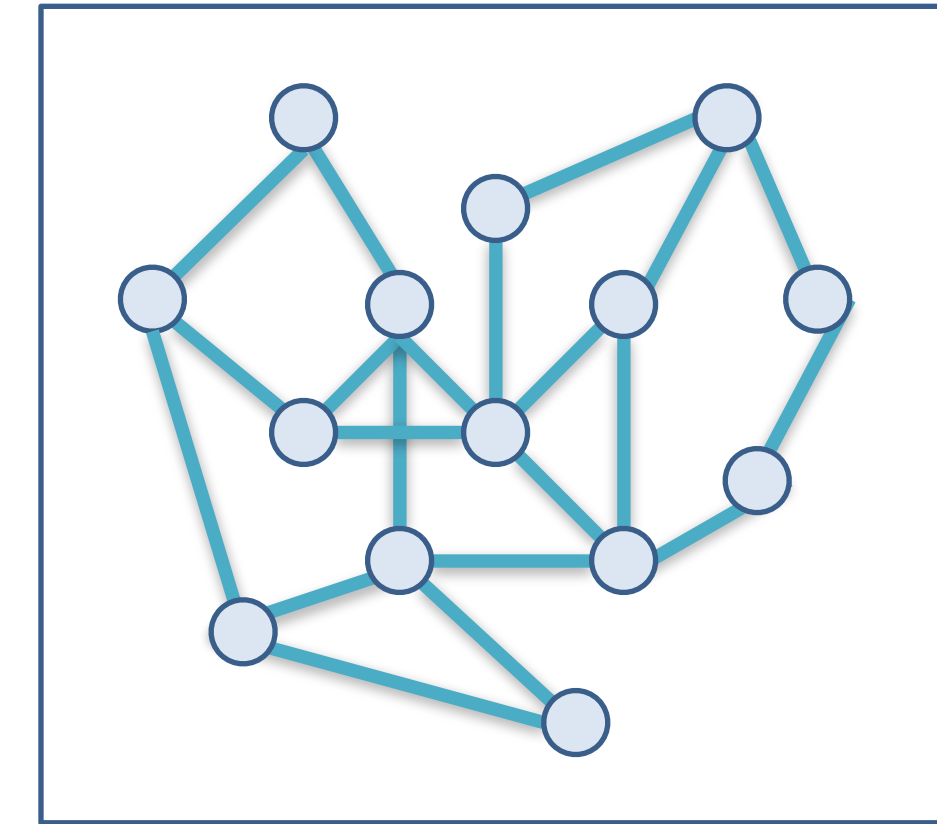


Articulation Point (red)

Biconnected, Bipartite Graphs

Biconnected graph

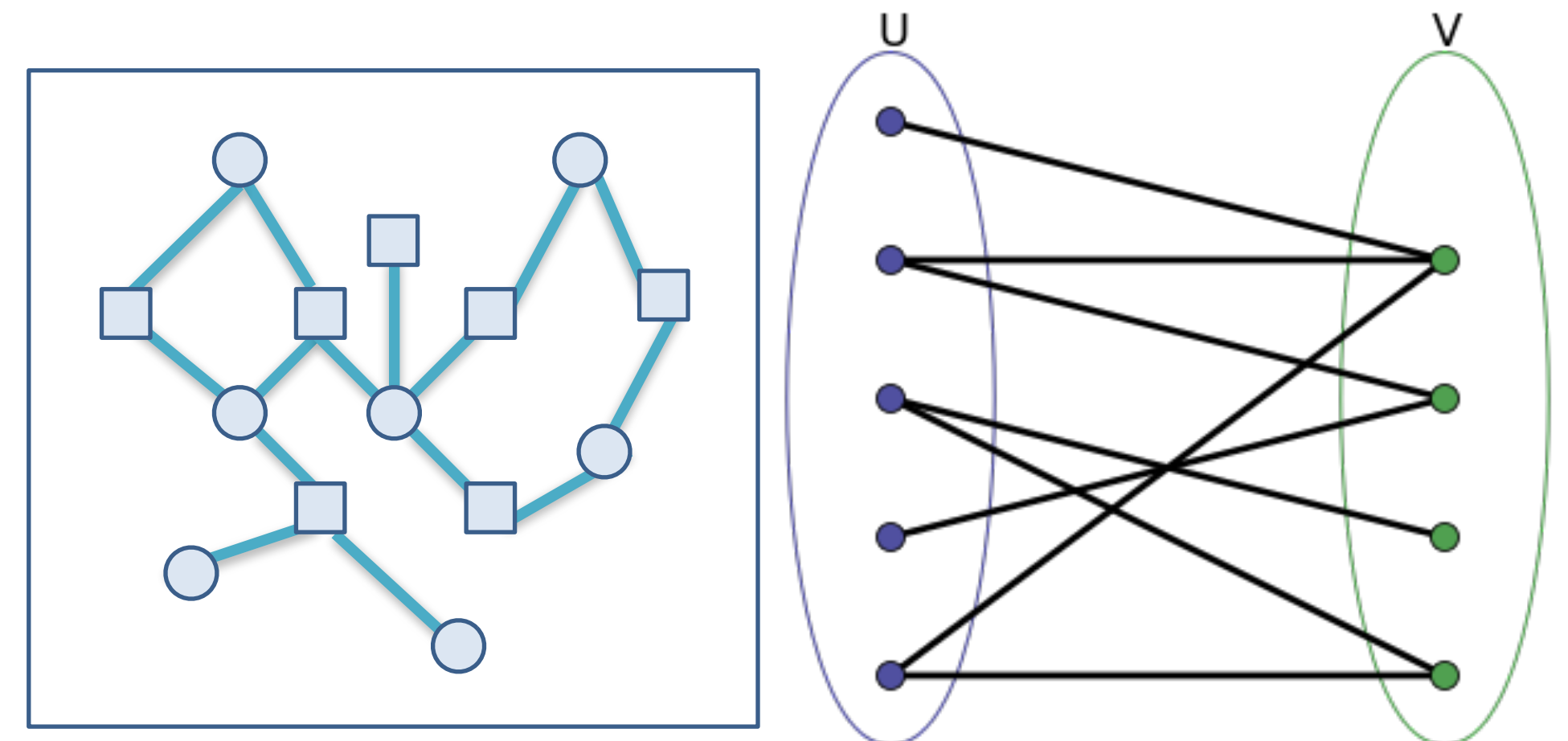
A graph without articulation points.



Biconnected Graph

Bipartite graph

The vertices can be partitioned in two independent sets.



Bipartite Graph

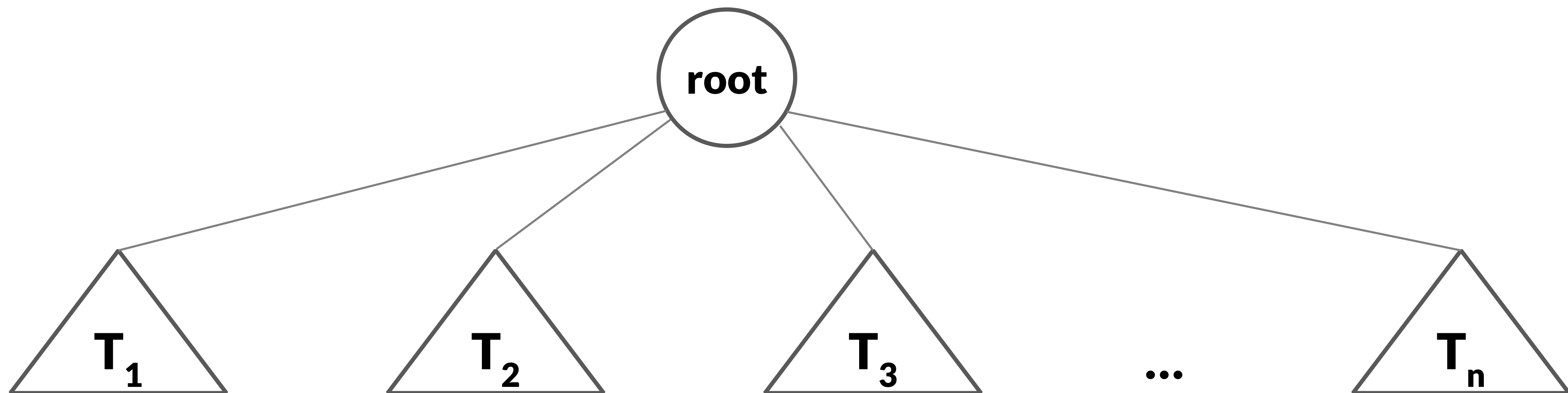
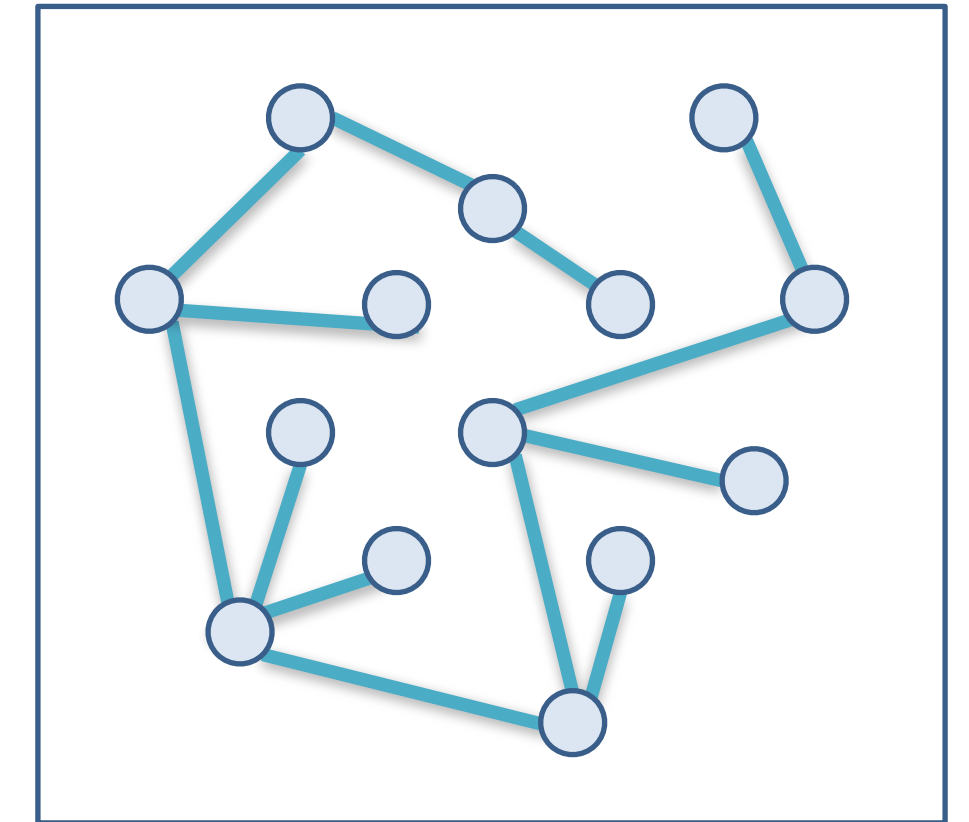
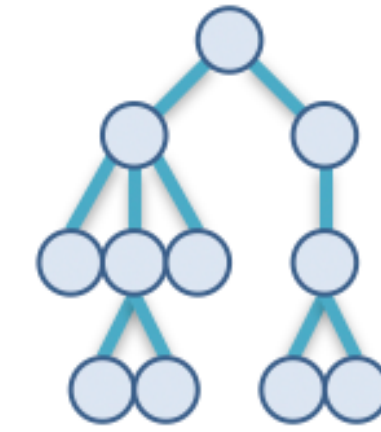
Tree

A graph with no cycles - or:

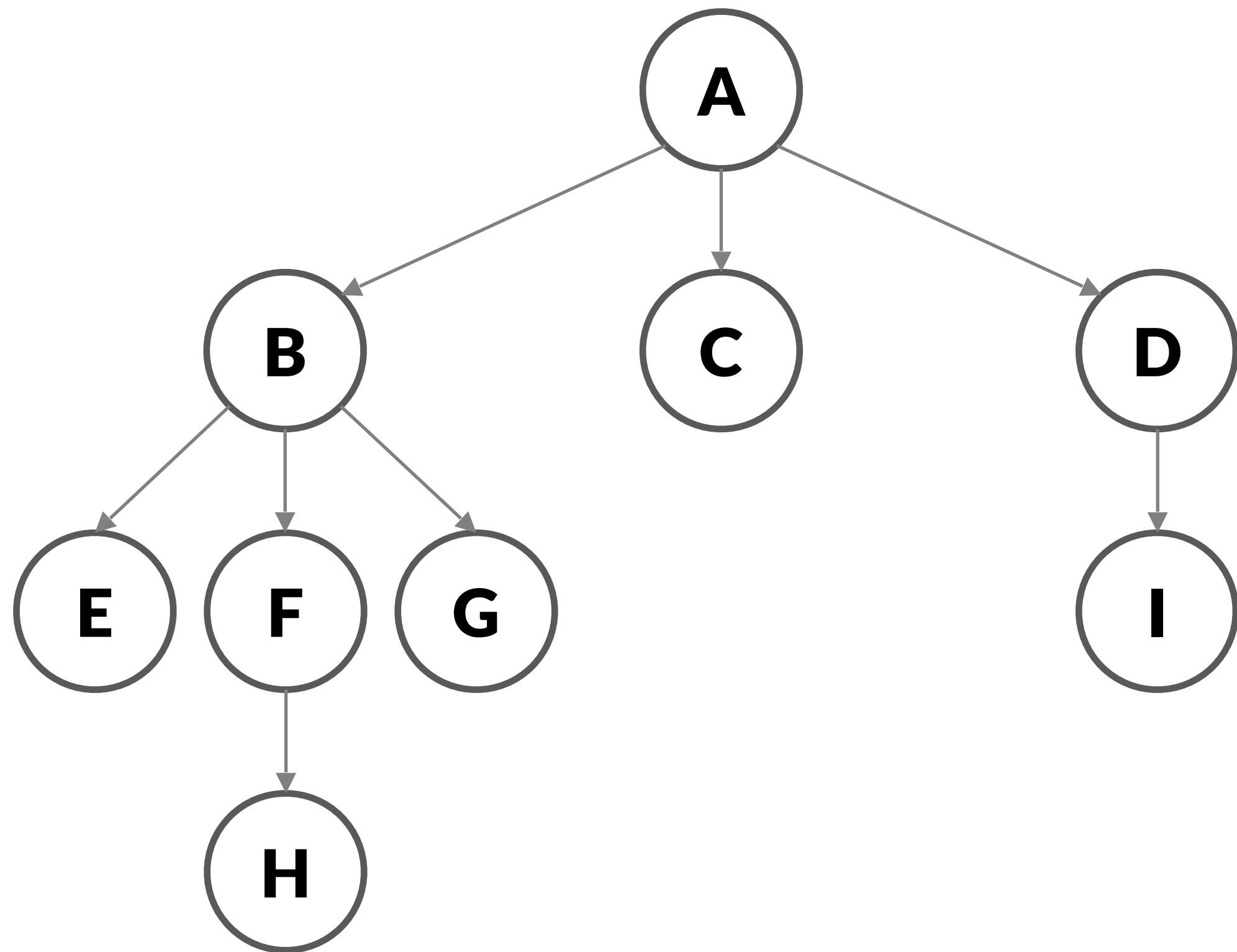
A collection of nodes

contains a root node and 0-n subtrees

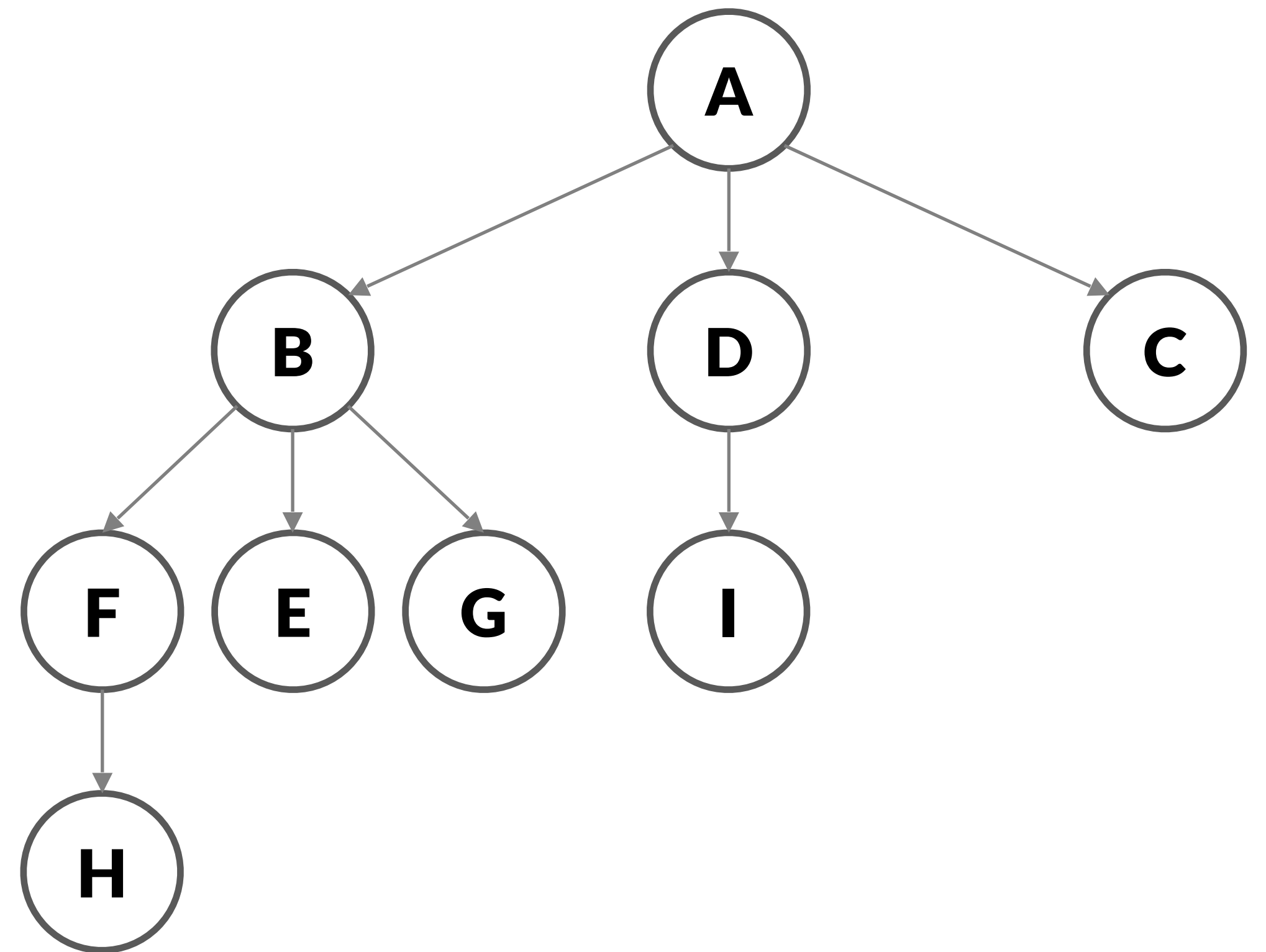
subtrees are connected to root by an edge



Ordered Tree



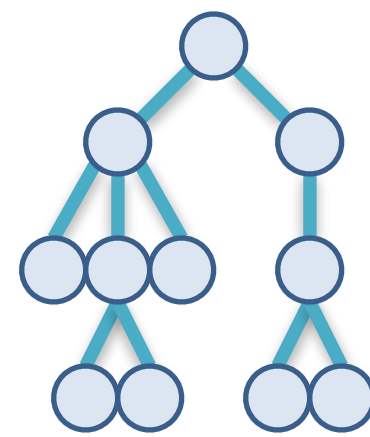
≠



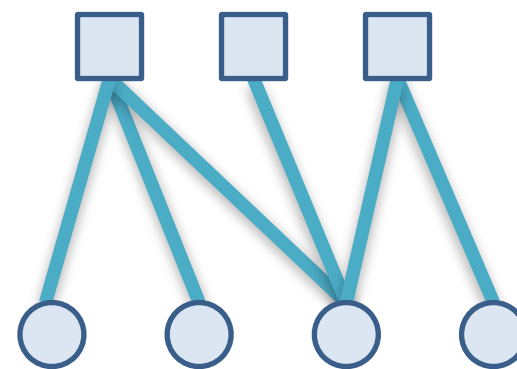
Different Kinds of Graphs

Over 1000 different graph classes

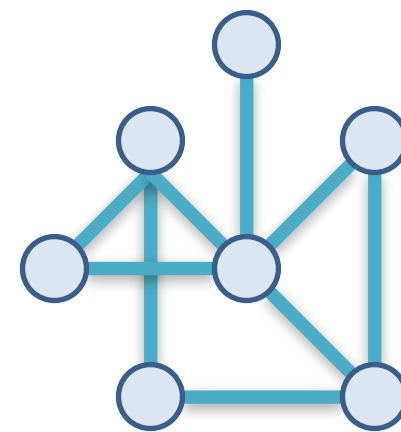
Tree



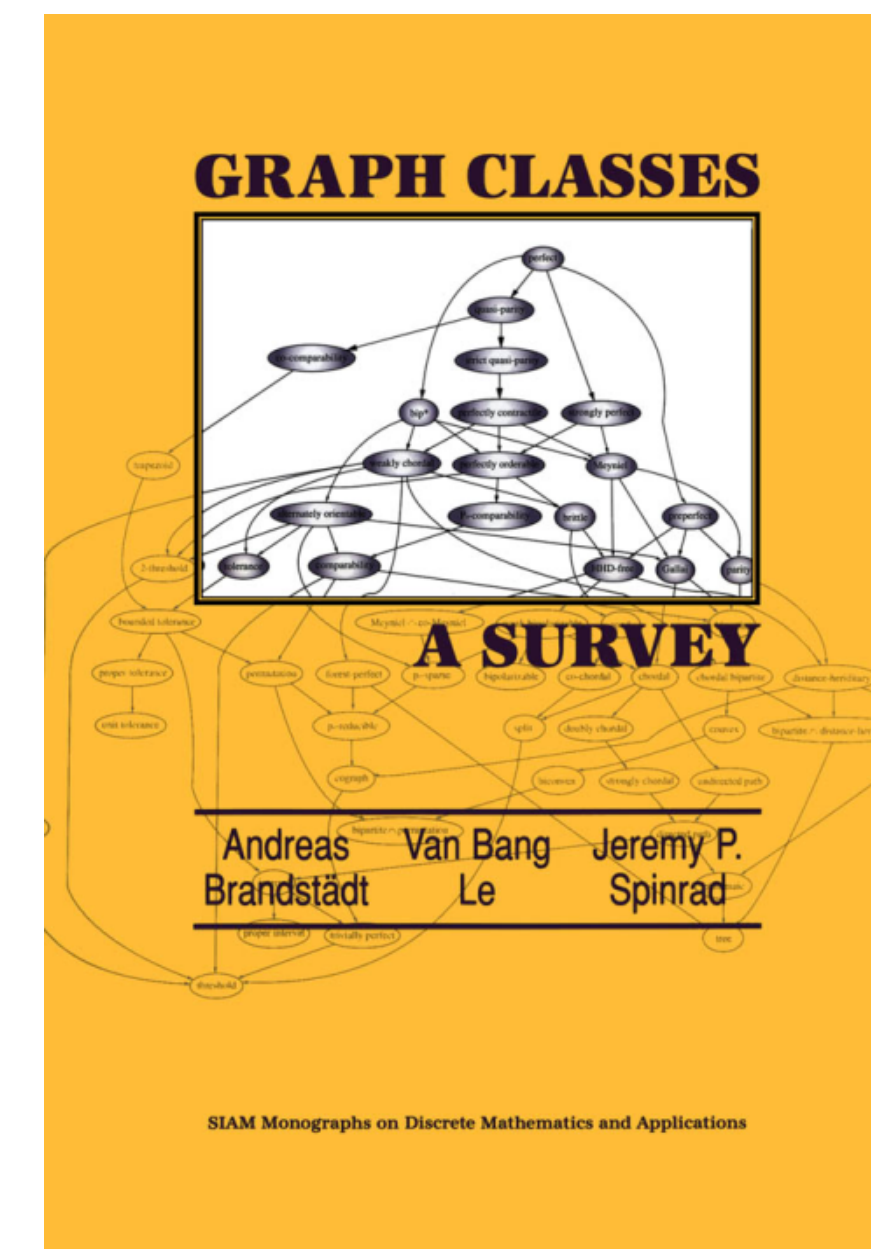
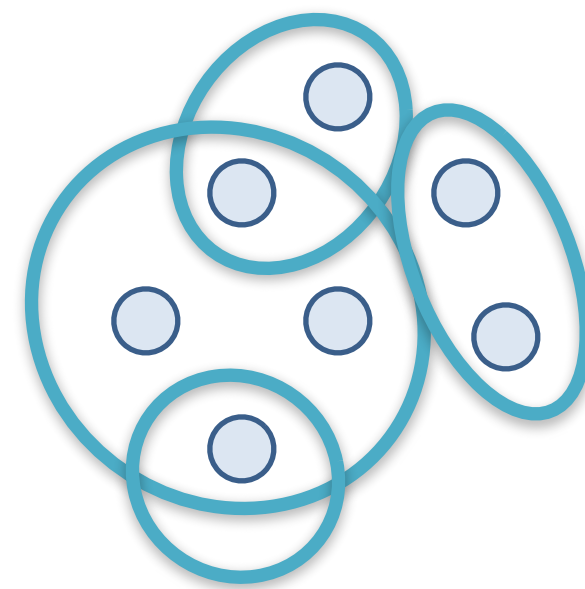
Bipartite Graph



Network



Hypergraph



A. Brandstädt et al. 1999

Degree

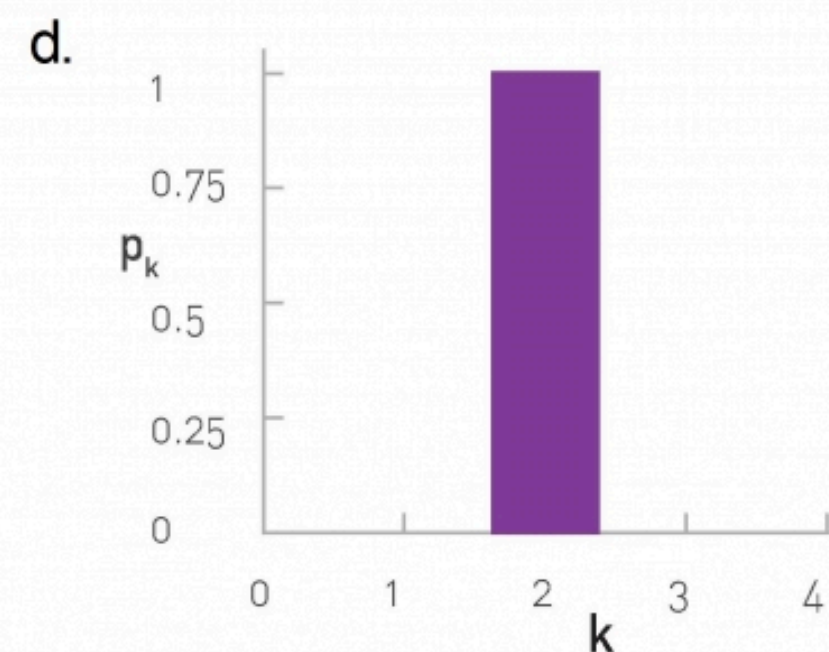
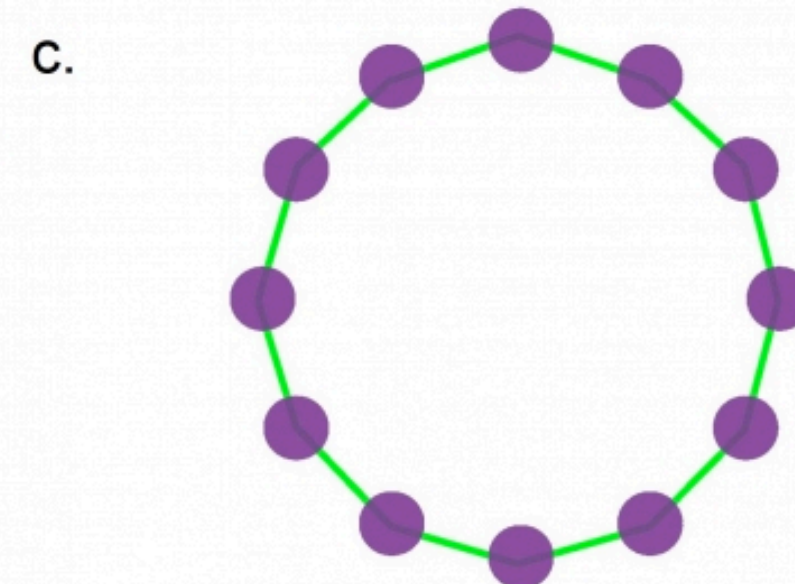
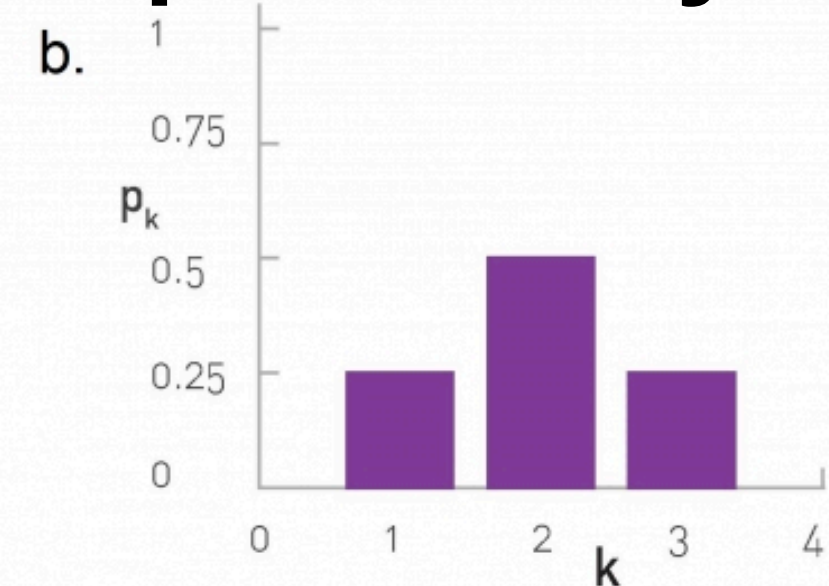
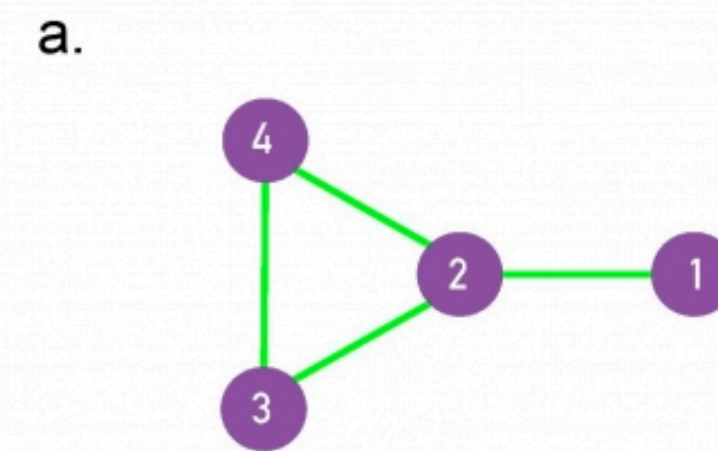
Node degree $\text{deg}(x)$

The number of edges connecting a node. For directed graphs in- and out-degree are considered separately.

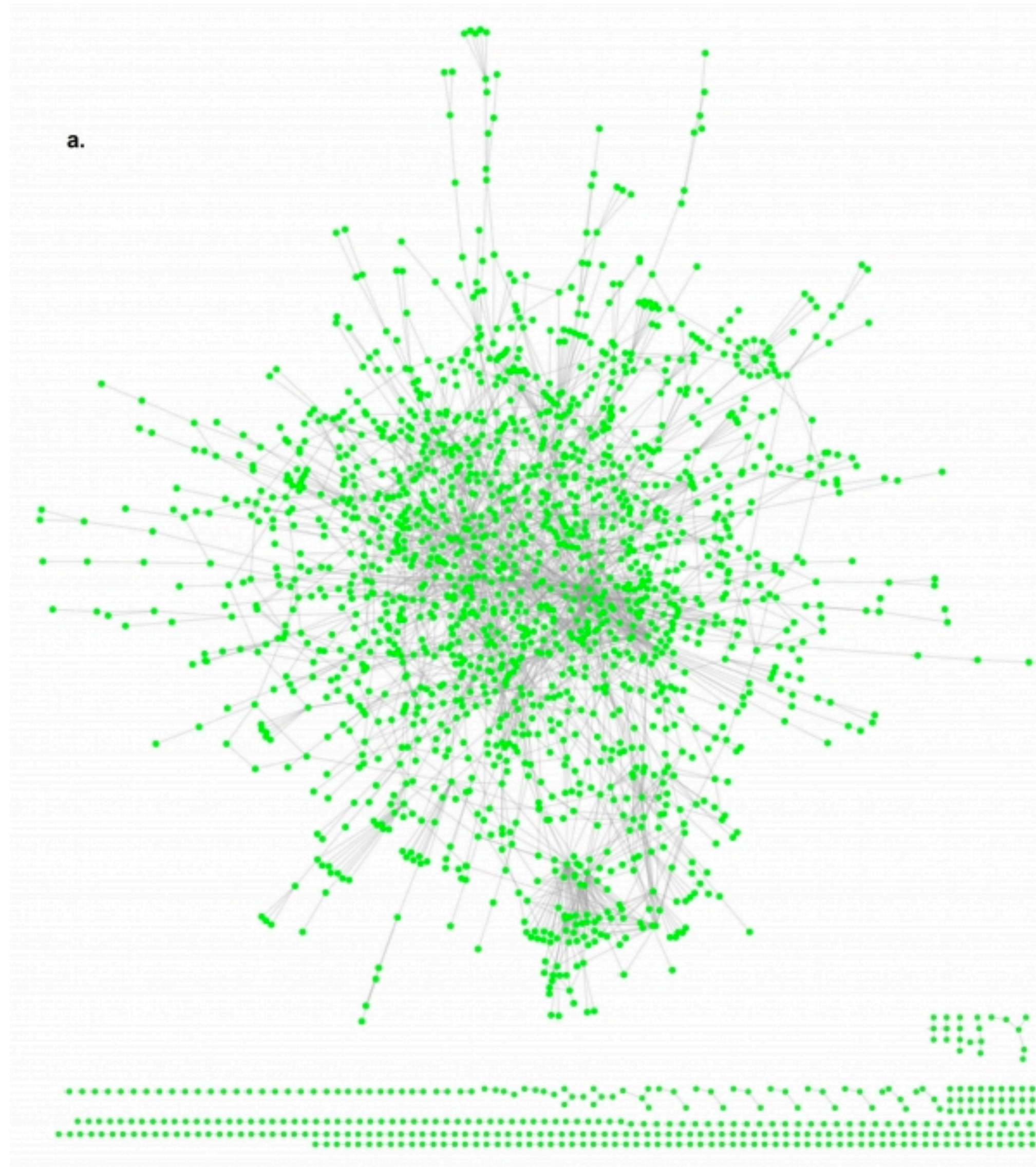
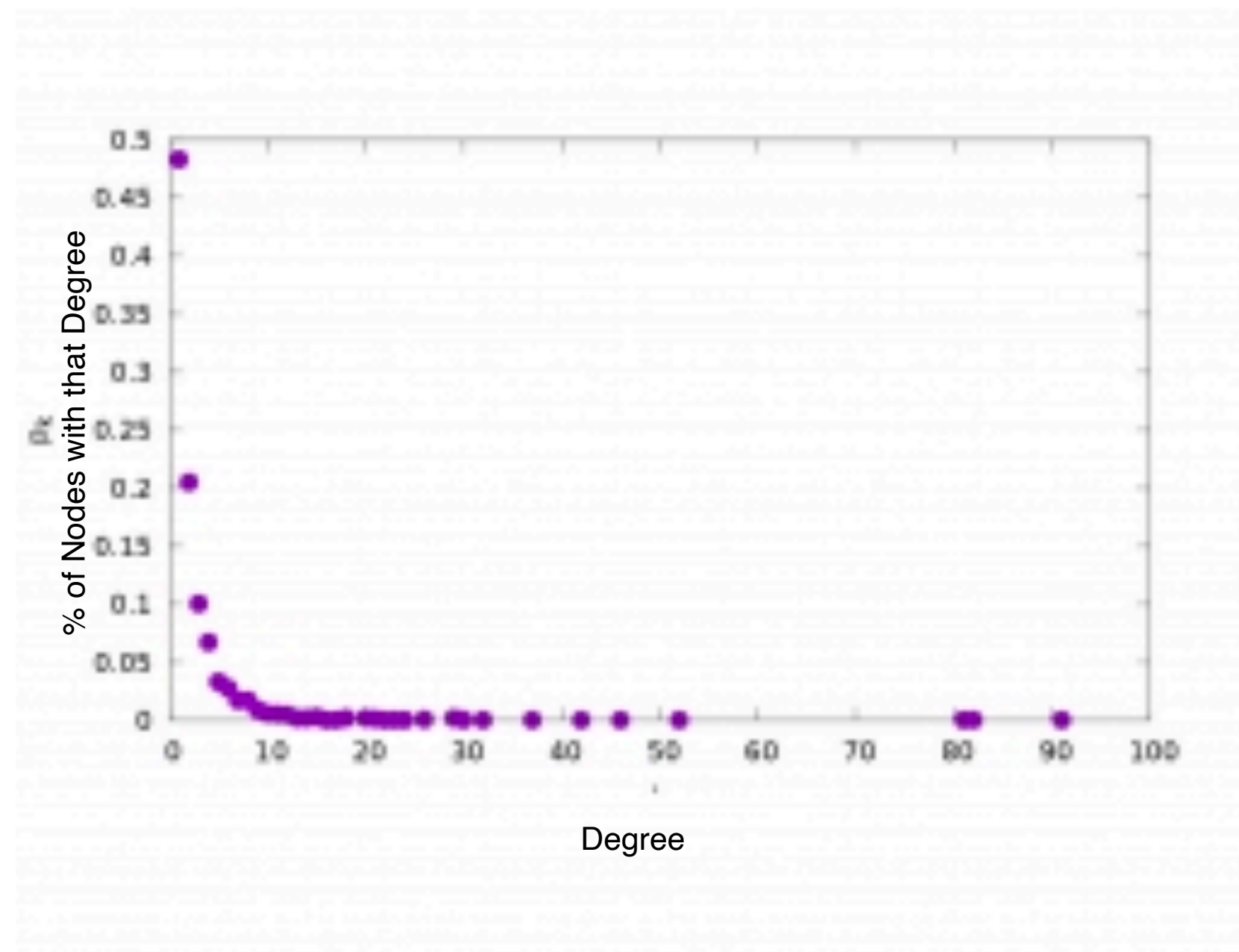
Average degree

$$\langle k \rangle = \frac{1}{N} \sum_{i=1}^N k_i = \frac{2L}{N}$$

Degree distribution

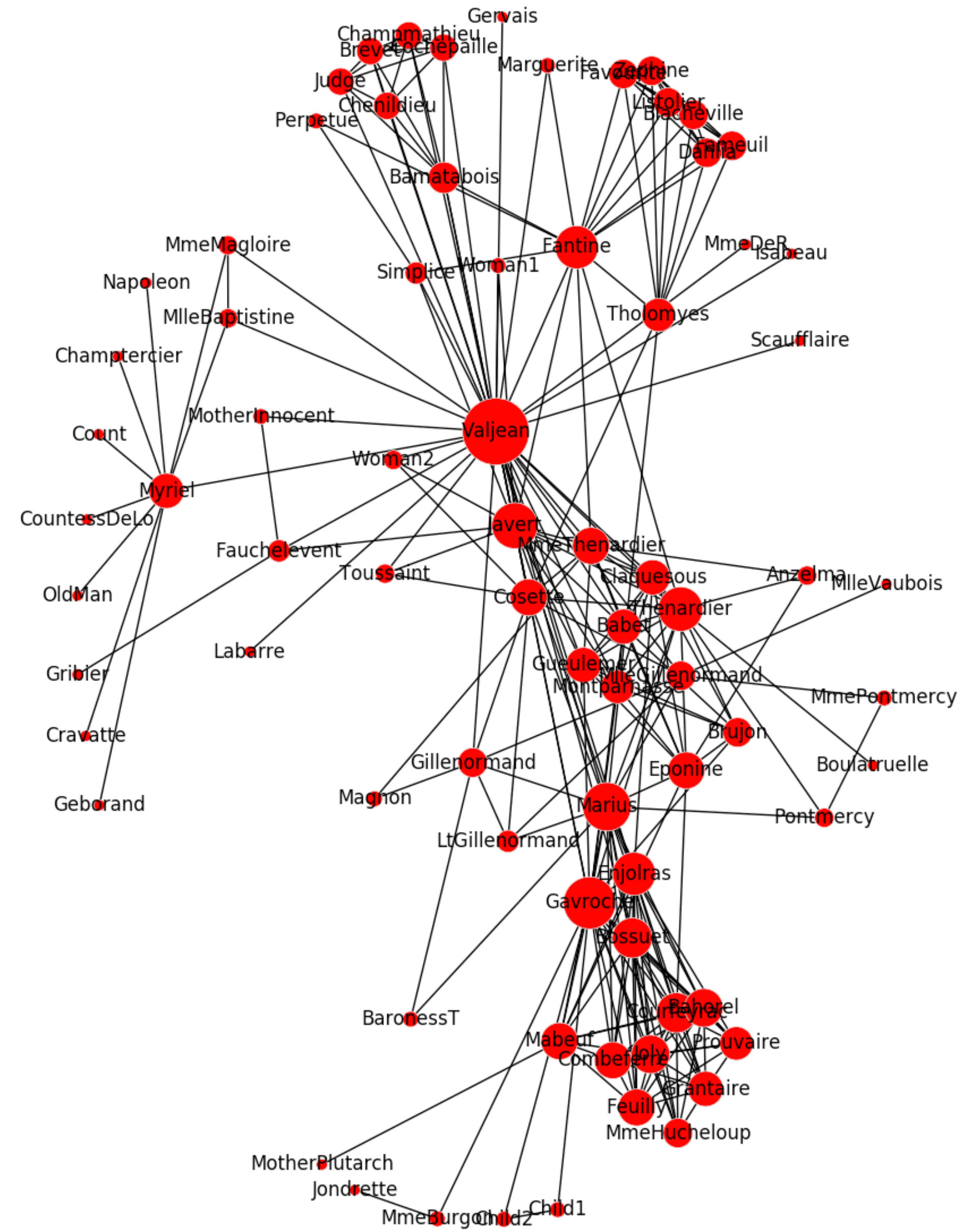


Degree Distribution of a real Network



Degrees

Degree is a measure of local importance



Paths & Distances

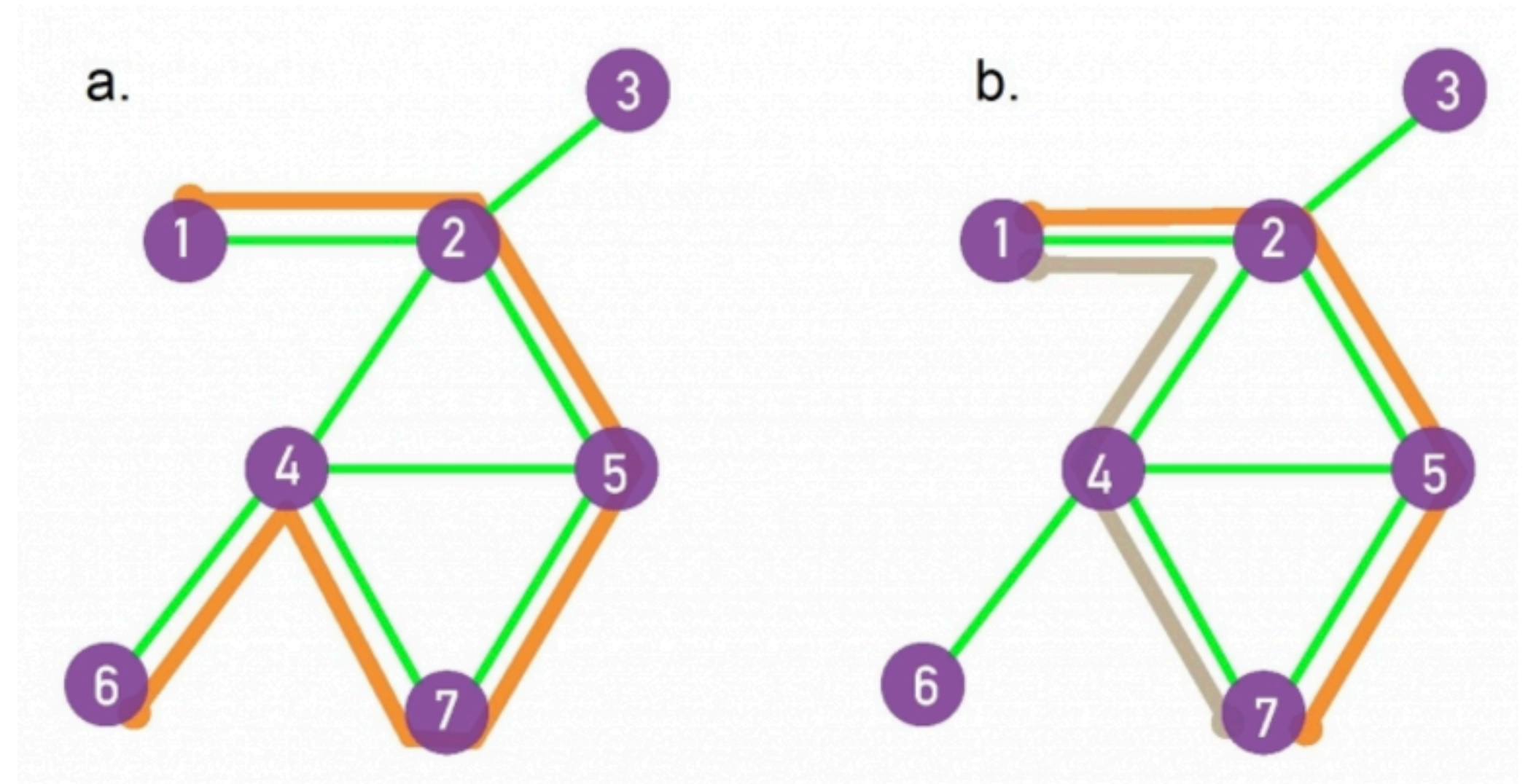
Path is **route along links**

Path length is the **number of links** contained

Shortest paths connects nodes i and j with the smallest number of links

Diameter of graph G

The longest shortest path within G .



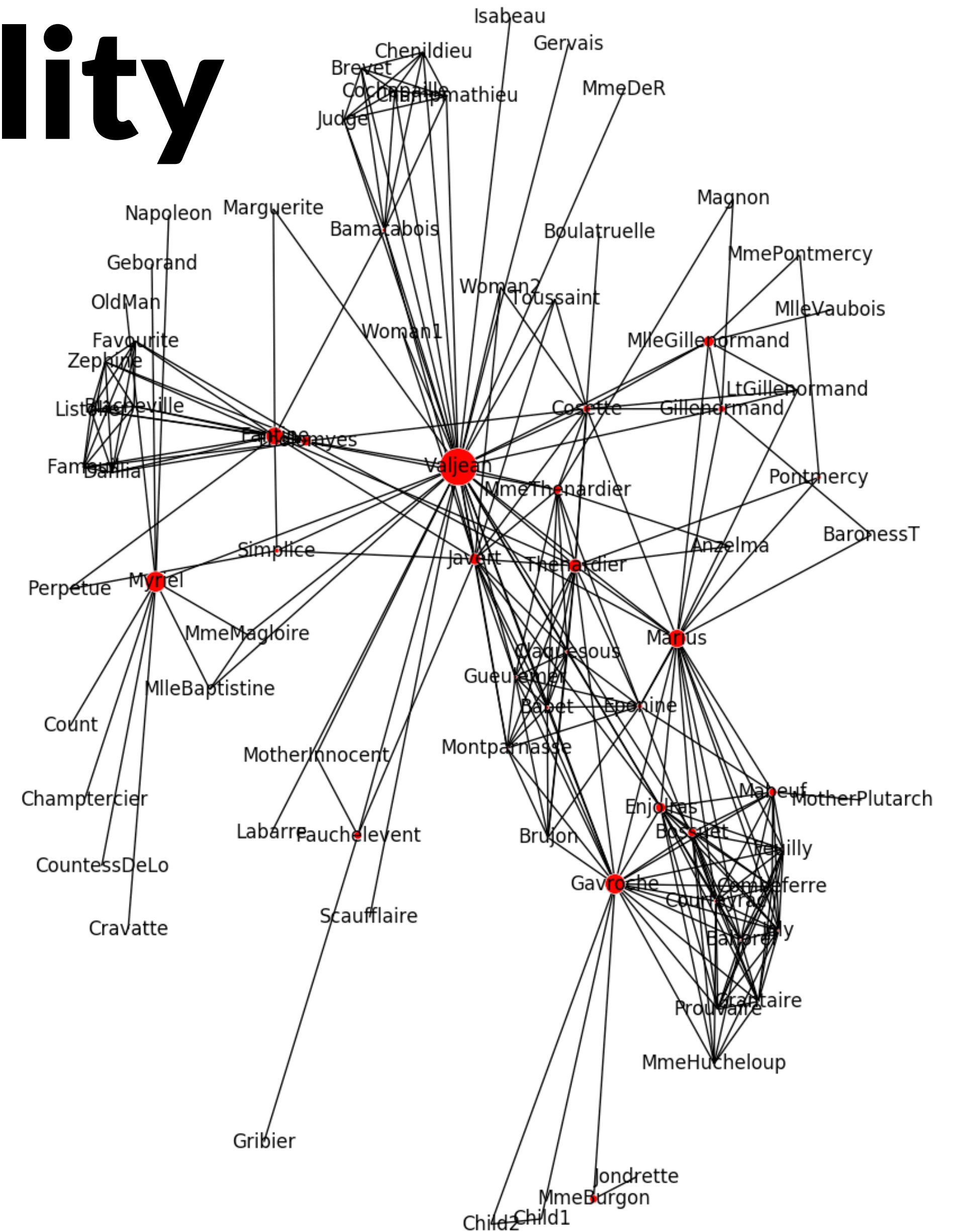
A path from 1 to 6

Shortest paths (two) from 1 to 7.

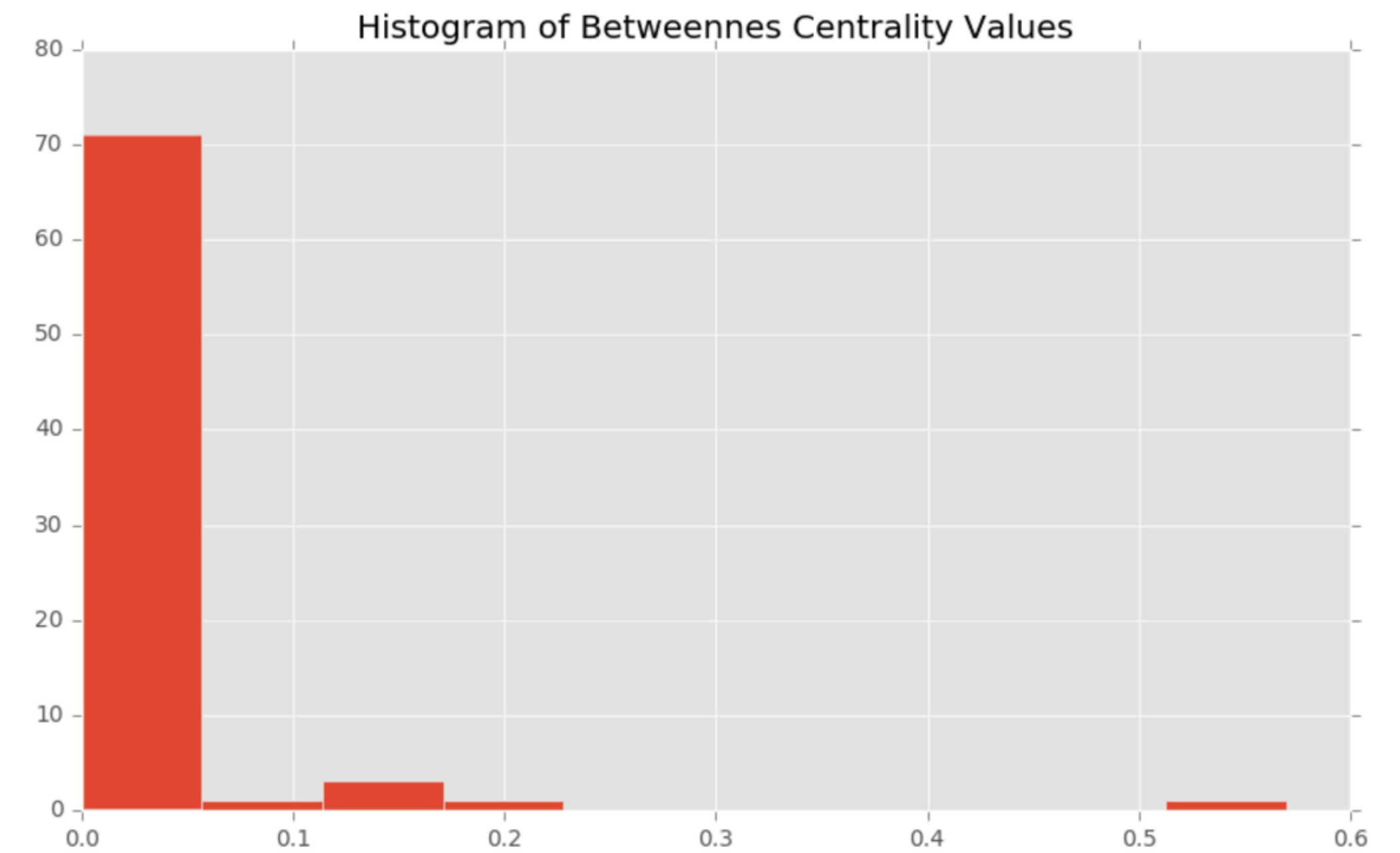
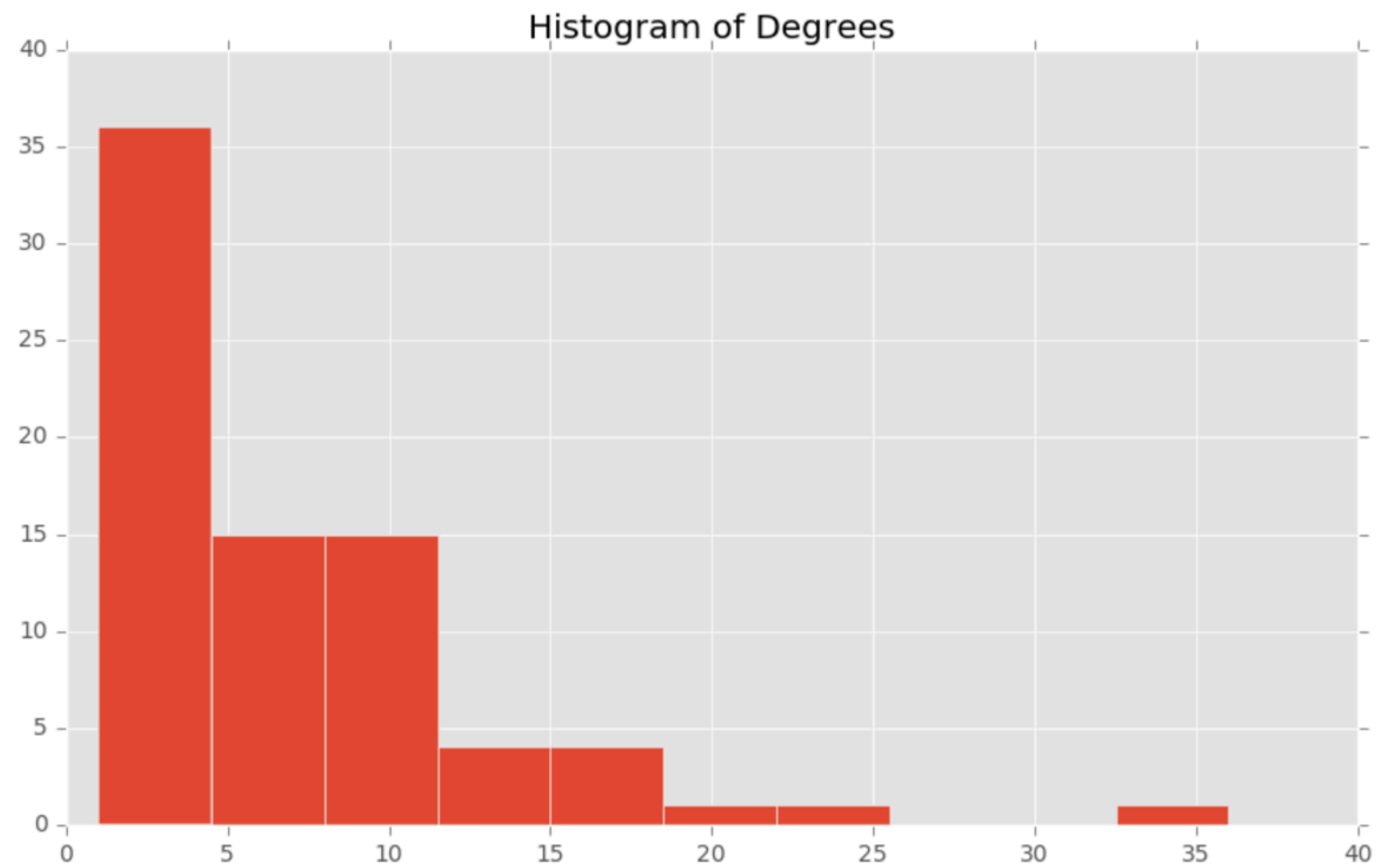
Betweenness Centrality

a measure of how many shortest paths pass through a node

good measure for the overall relevance of a node in a graph

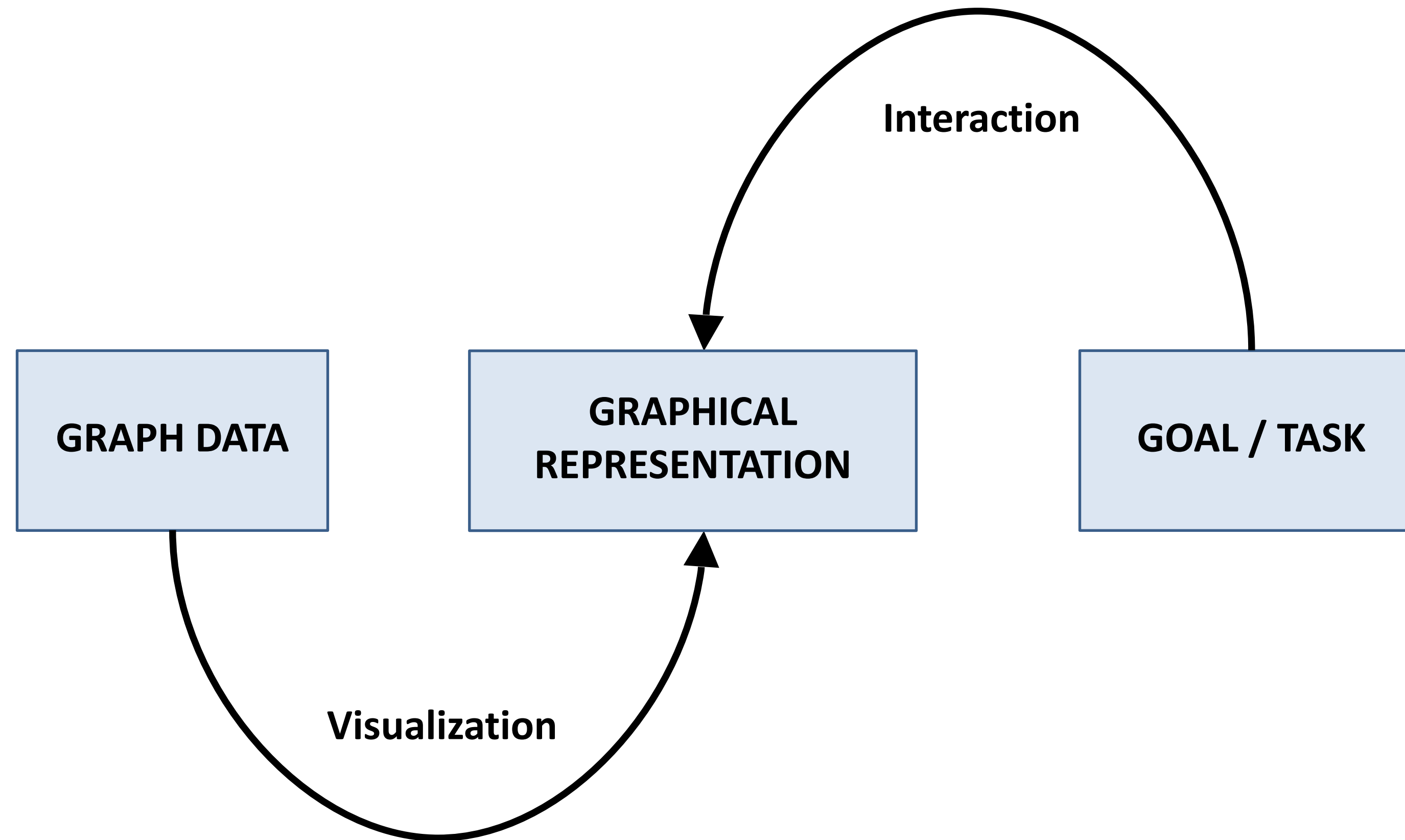


Degree vs BC



Network and Tree Visualization

Setting the Stage



How to decide which **representation** to use for which **type of graph** in order to achieve which kind of **goal**?

Task Taxonomy for Graph Visualization

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ABSTRACT

Our goal is to define a list of tasks for graph visualization that has enough detail and specificity to be useful to: 1) designers who want to improve their system and 2) to evaluators who want to compare graph visualization systems. In this paper, we suggest a list of tasks we believe are commonly encountered while analyzing graph data. We define graph specific objects and demonstrate how all complex tasks could be seen as a series of low-level tasks performed on those objects. We believe that our taxonomy, associated with benchmark datasets and specific tasks, would help evaluators generalize results collected through a series of controlled experiments.

Categories and Subject Descriptors

H.5.2 [Information Interfaces and Presentation]: User Interfaces – Graphical user interfaces (GUI)

user studies of graph visualization techniques and extracted the tasks used in those studies.

After making those two lists, we considered the set of low-level Visual Analytics tasks proposed by Amar *et al.* [2]. These tasks were extracted from a corpus of questions about tabular data. We realized that our tasks all seem to be compound tasks made up of Amar *et al.*'s primitive tasks applied to the graph objects. When some tasks could not be represented with those tasks and objects, we added either an object or a low-level task. In this paper, we demonstrate how all complex tasks could be seen as a series of low-level tasks performed on those objects.

2. GRAPH-SPECIFIC OBJECTS

A graph consists of two types of primitive elements, nodes and links. A subgraph of a graph G is a graph whose nodes and links are subsets of G . There are several meaningful subgraphs such as

Different Kinds of Tasks/Goals

Two principal types of tasks: **attribute-based (ABT)** and **topology-based (TBT)**

Localize – find a single or multiple nodes/edges with a given property

- ABT: Find the edge(s) with the maximum edge weight.
- TBT: Find all adjacent nodes of a given node.

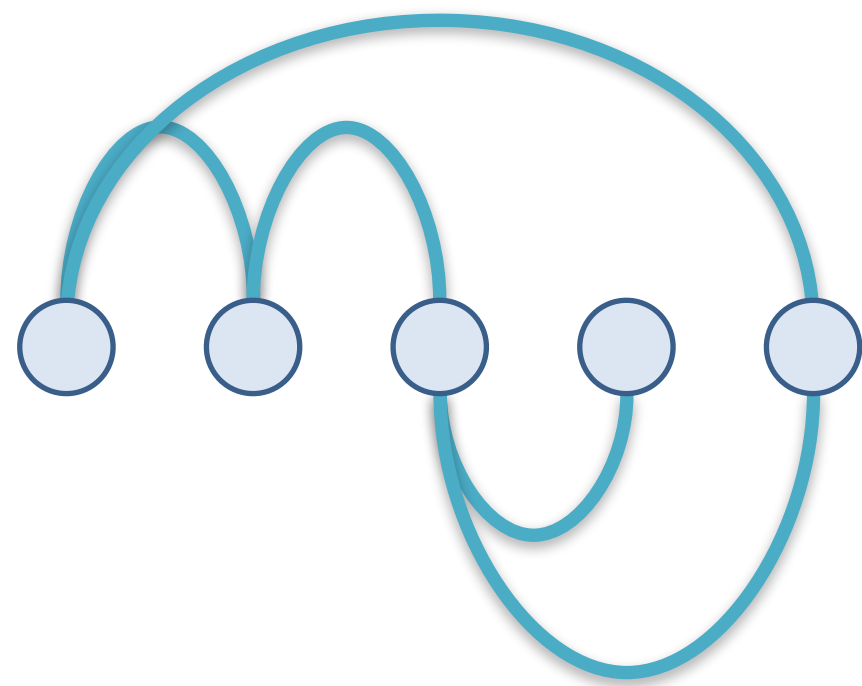
Find neighbors nodes

Identify Clusters / Communities

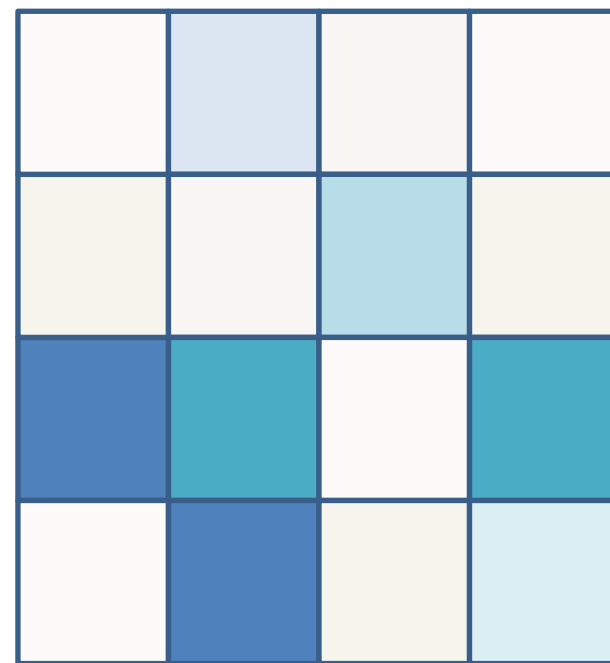
Find Paths

....

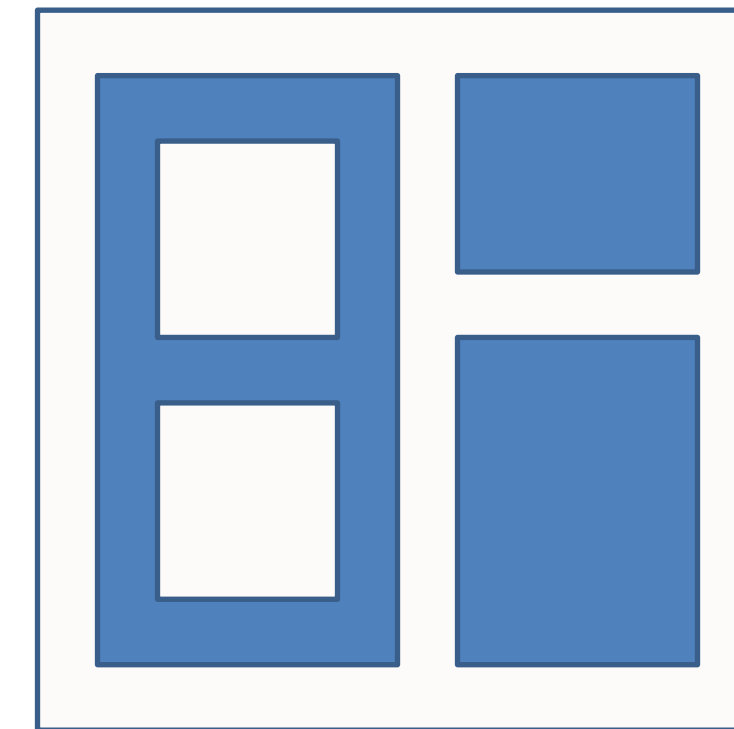
Three Types of Graph Representations



Explicit
(Node-Link)



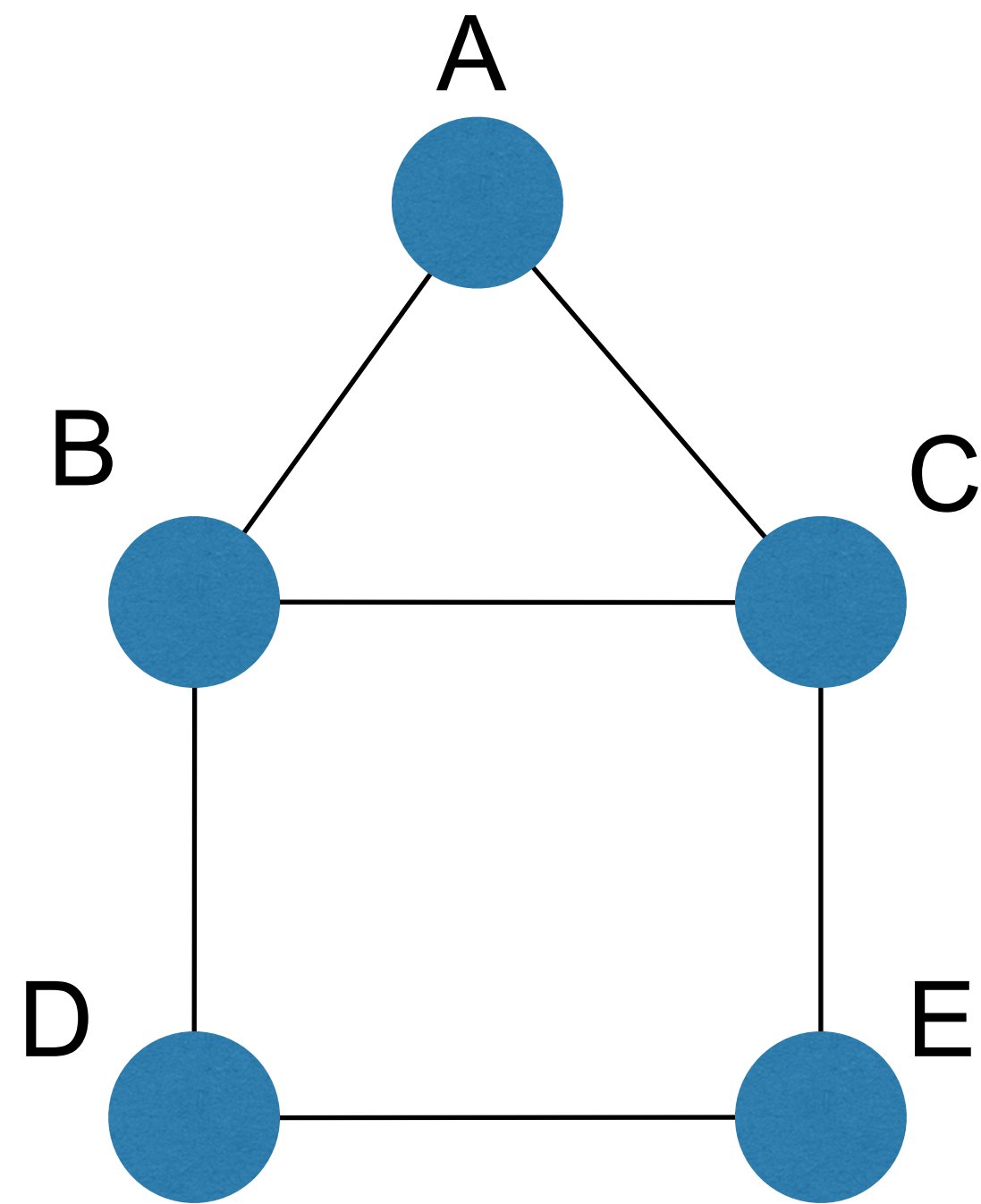
Matrix



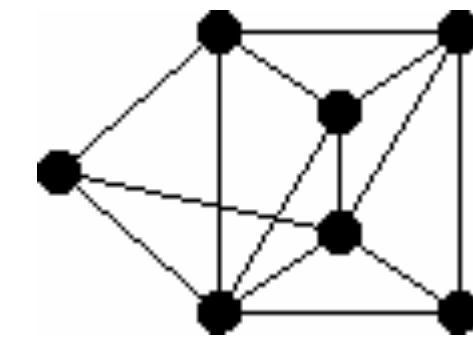
Implicit

Explicit Graph Representations

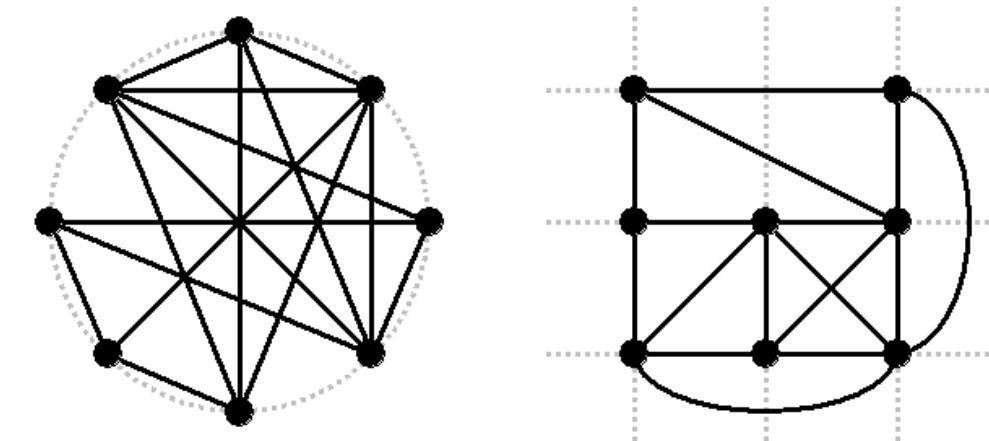
Node-link diagrams: vertex = point, edge = line/arc



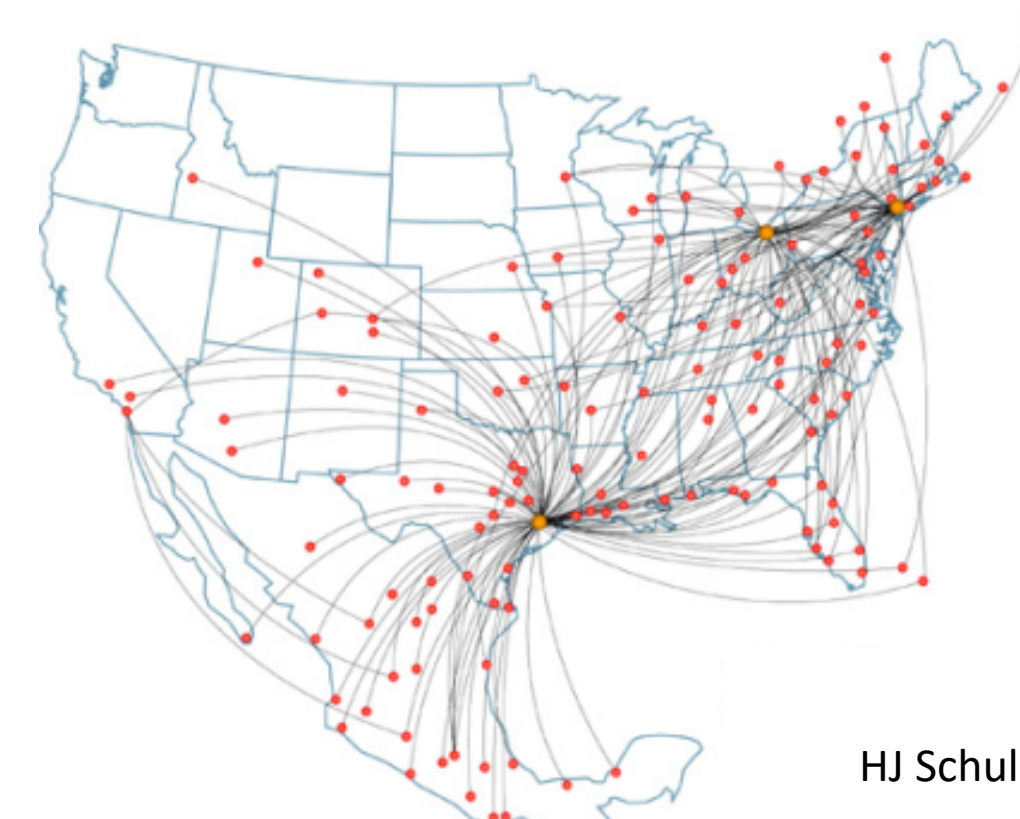
Free



Styled



Fixed



Criteria for Good Node-Link Layout

Minimized **edge crossings**

Minimized **distance** of neighboring nodes

Minimized **drawing area**

Uniform edge **length**

Minimized edge **bends**

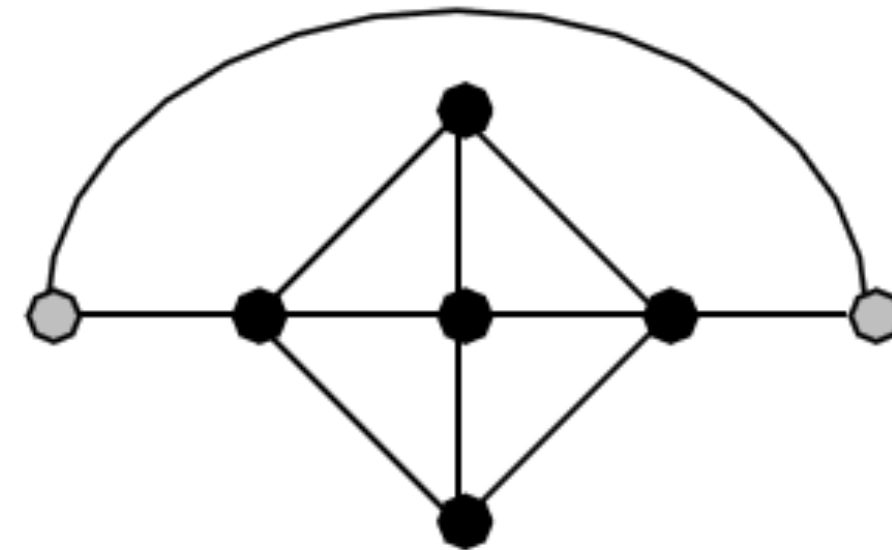
Maximized **angular distance** between different edges

Aspect ratio about 1 (not too long and not too wide)

Symmetry: similar graph structures should look similar

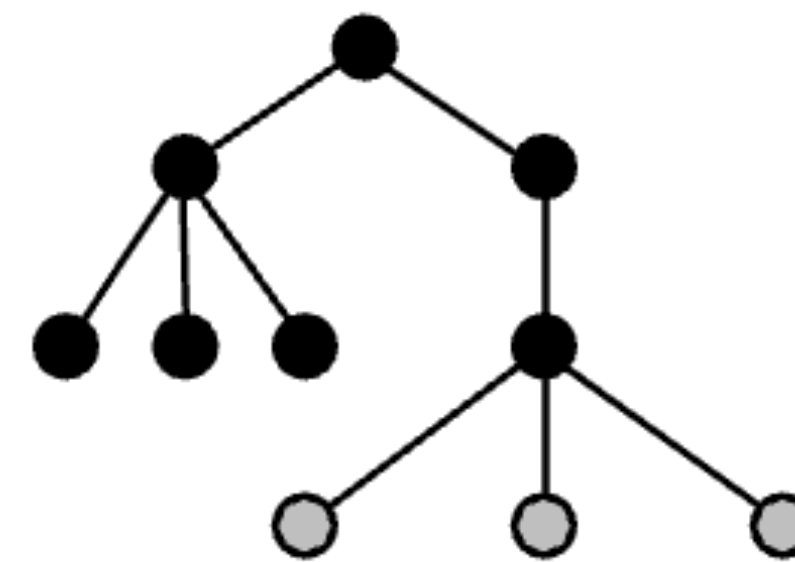
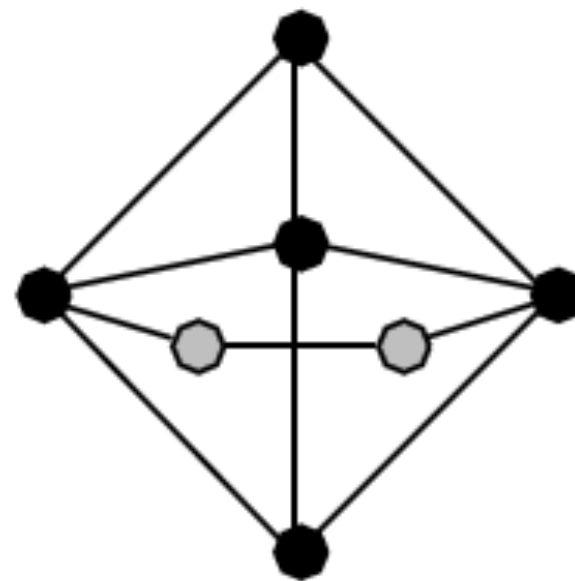
Conflicting Criteria

Minimum number
of edge crossings



vs.

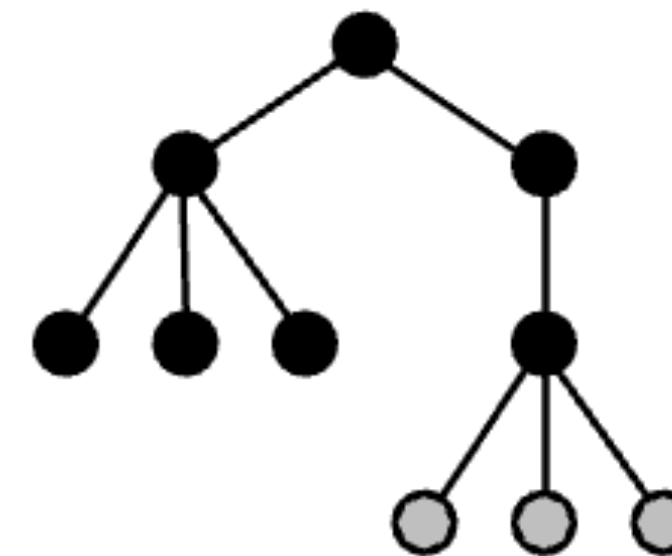
Uniform edge
length



Space utilization

vs.

Symmetry



Explicit Layouts

Layout approach: formulate the layout problem as an optimization problem

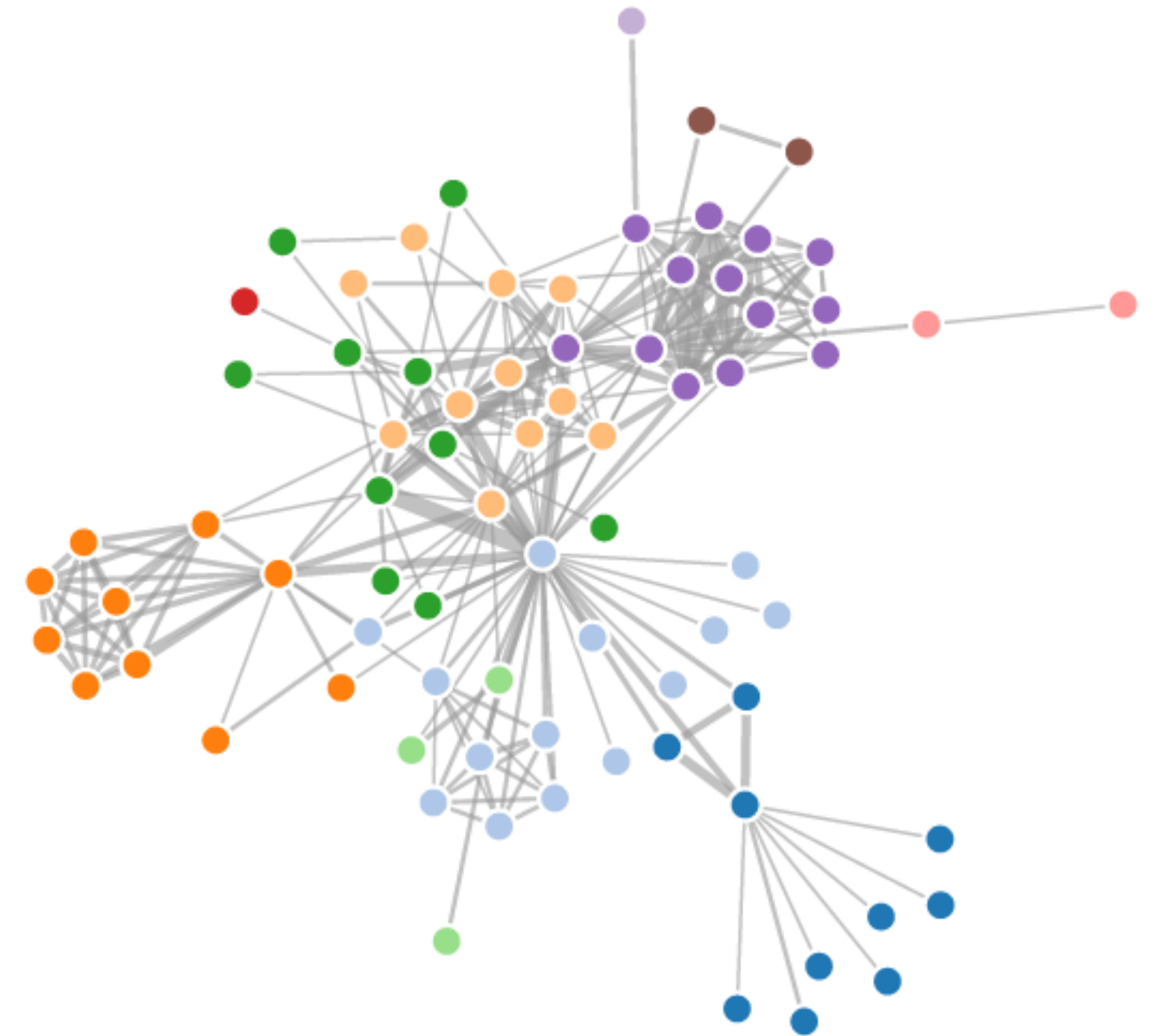
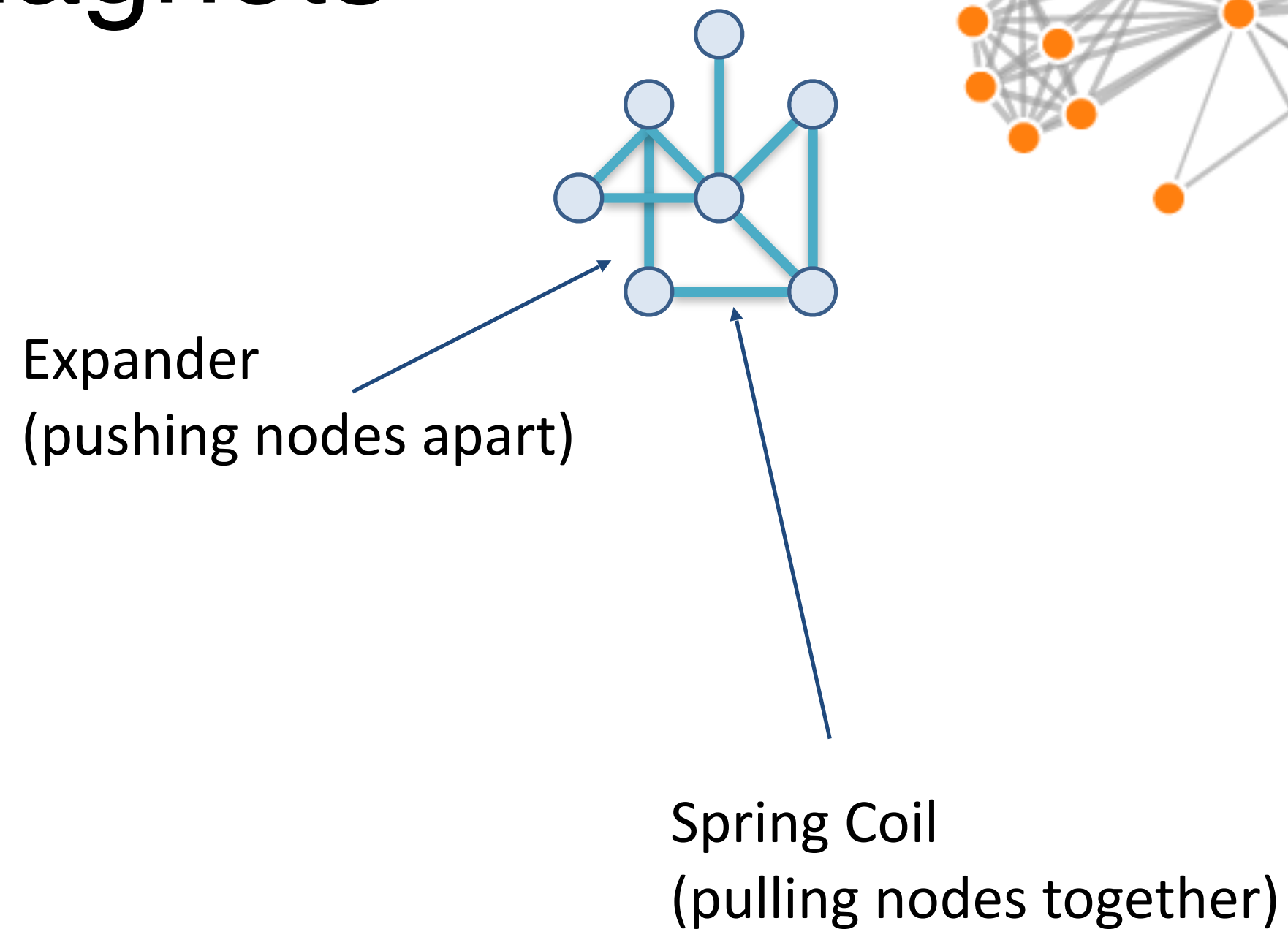
1. Conversion of the layout criteria into a weighted cost function:

$$F(\text{layout}) = a * |\text{edge crossings}| + \dots + f * |\text{used drawing space}|$$

2. Use a standard optimization technique (e.g., simulated annealing) to find a layout that minimizes the cost function

Force Directed Layouts

Physics model:
edges = springs,
vertices = repulsive magnets



Algorithm

Place Vertices in random locations

While not equilibrium

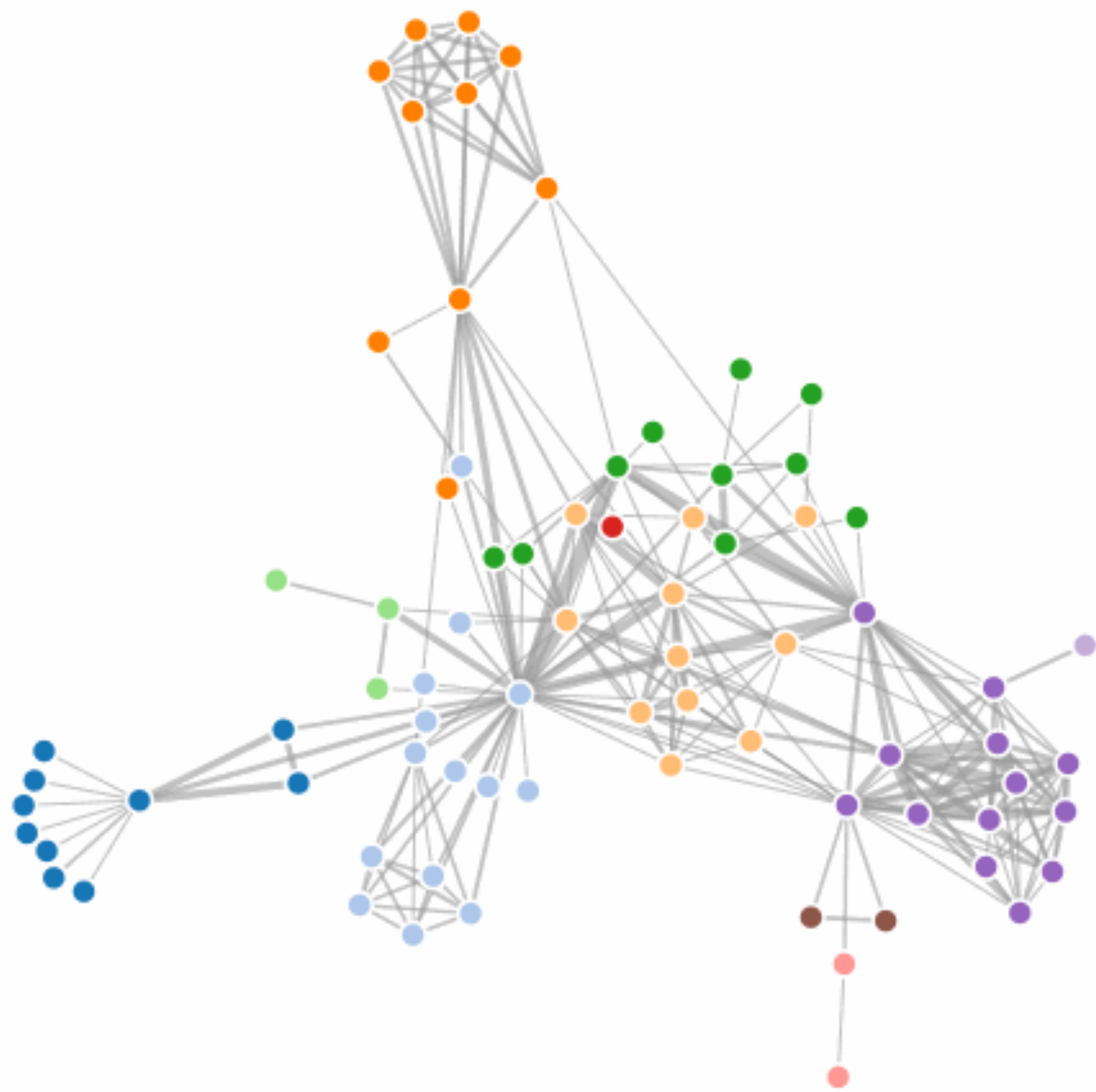
- calculate force on vertex

- sum of

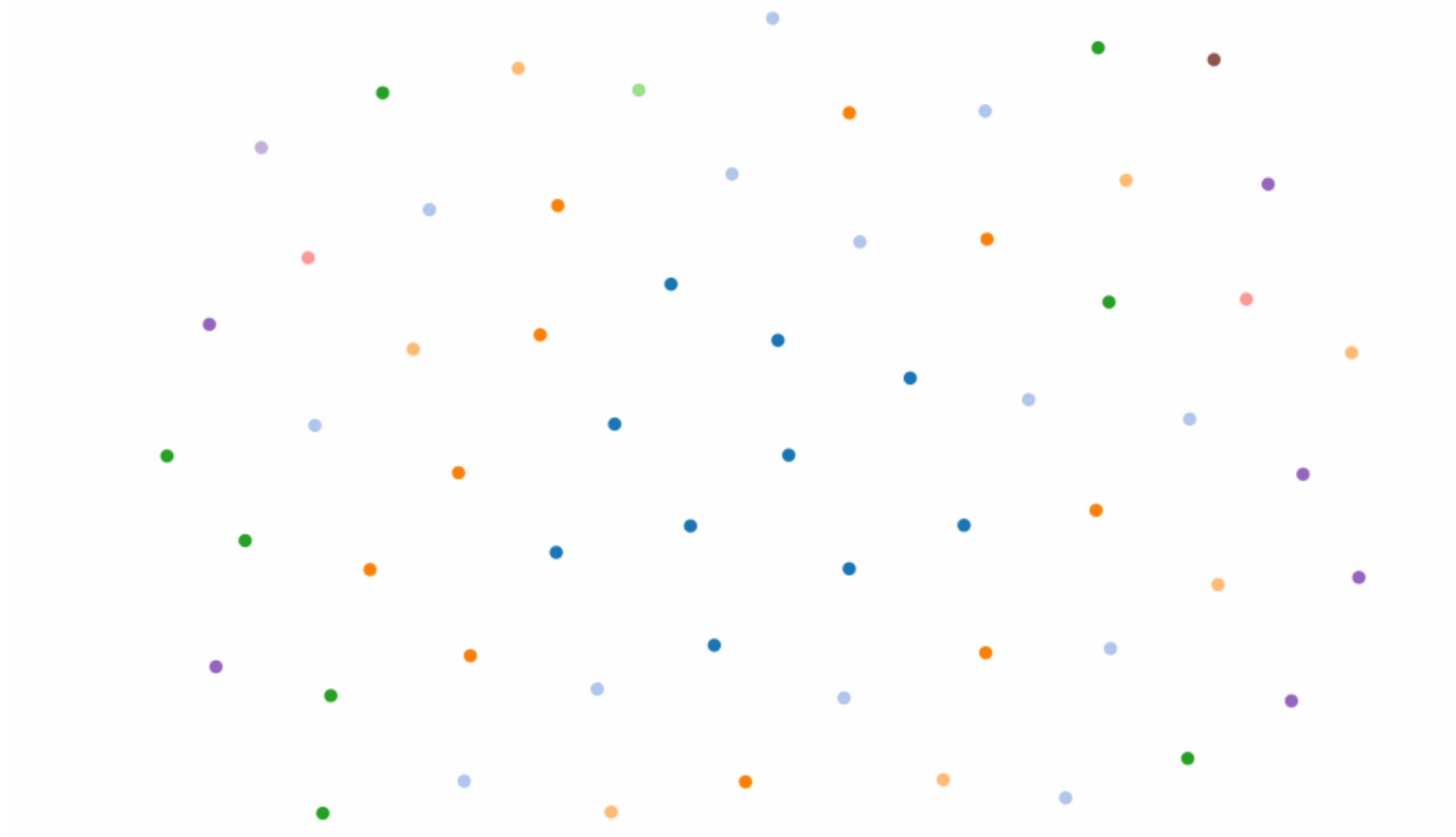
- pairwise repulsion of all nodes (n^2 operations)

- attraction between connected nodes

- move vertex by $c \cdot \text{force on vertex}$



What happens when there are no links?



Properties

Generally good layout

Uniform edge length

Clusters commonly visible

Not deterministic

Computationally expensive: $O(n^3)$

n^2 in every step, it takes about n cycles to reach equilibrium

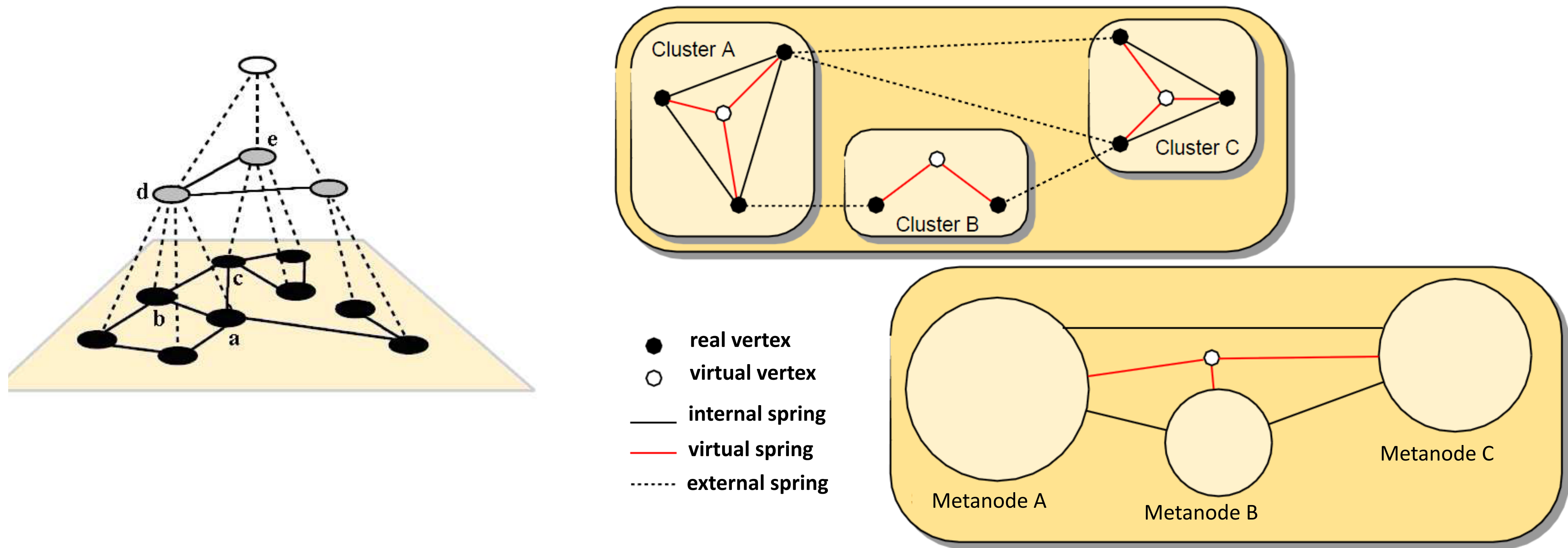
Limit (interactive): ~ 1000 nodes

in practice: damping, center of gravity



Giant Hairball

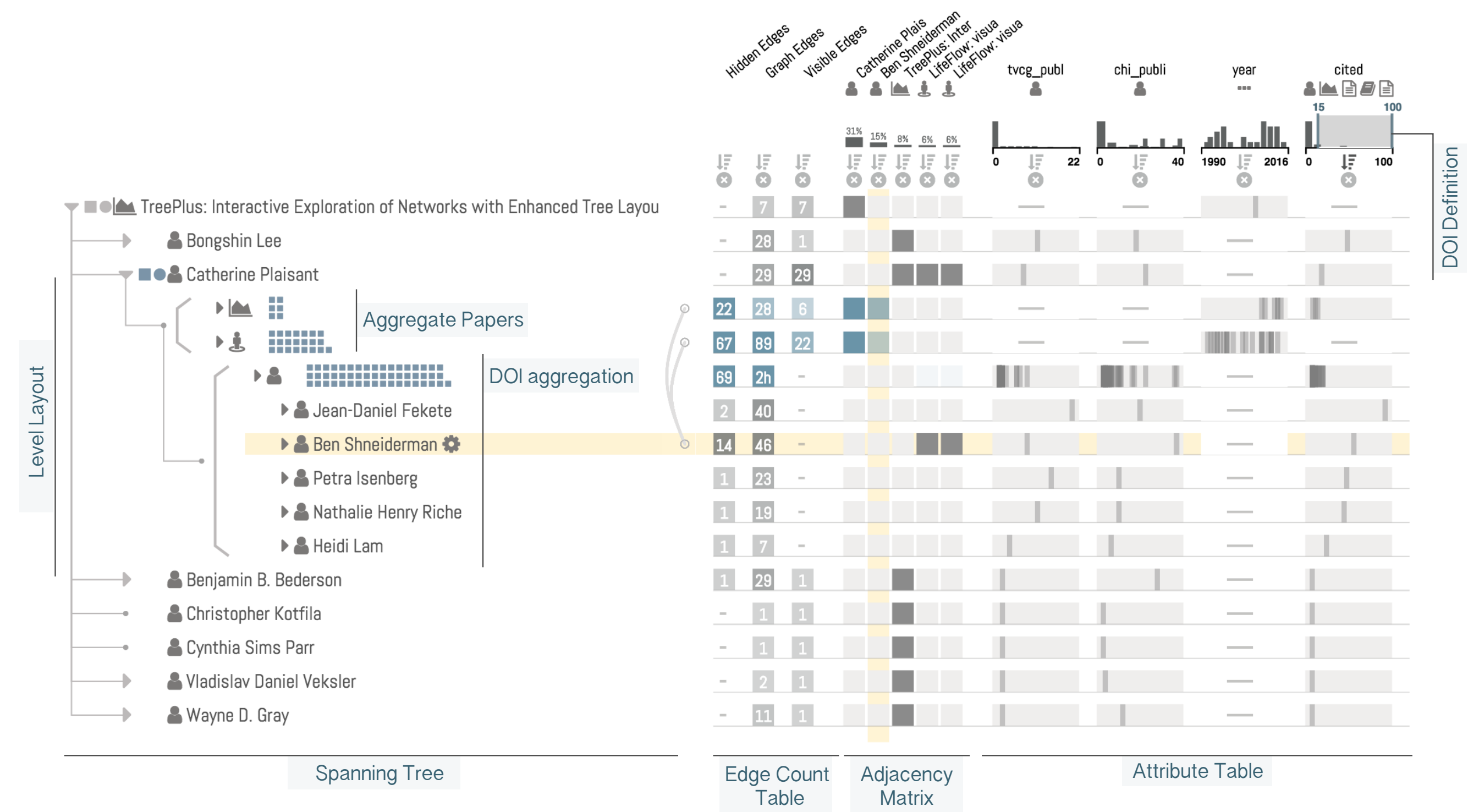
Address Computational Scalability: Multilevel Approaches



Alternative Approach: Query first, Expand on Demand

What do you want to know from a network?

Rarely is an overview helpful.

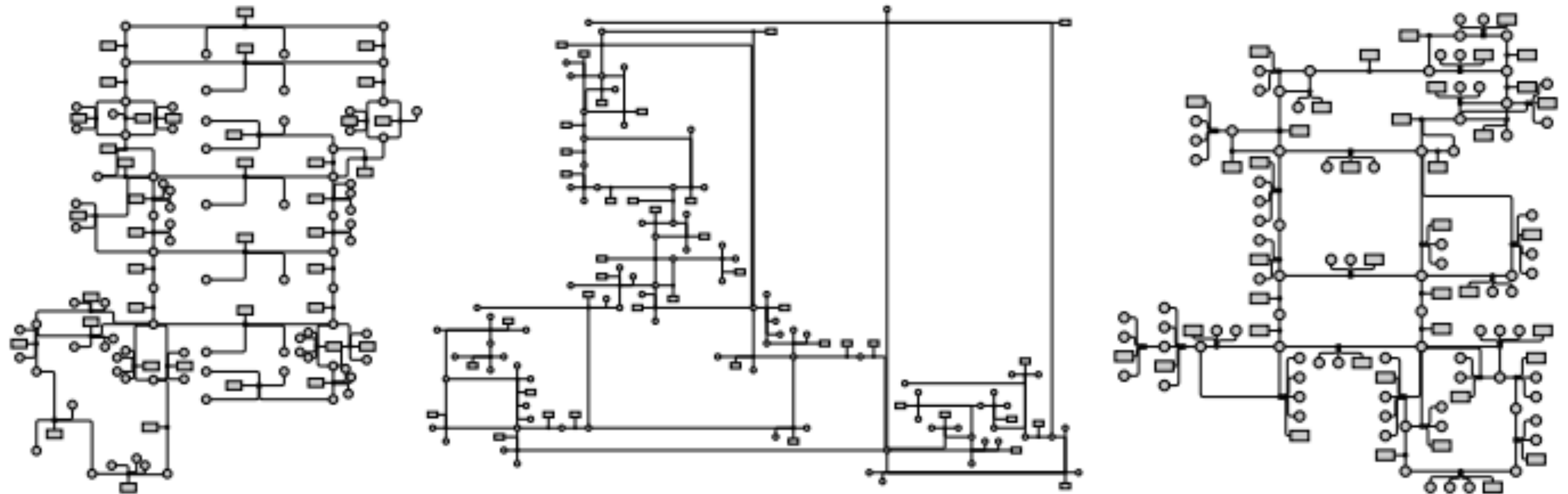


HOLA: Human-like Orthogonal Layout

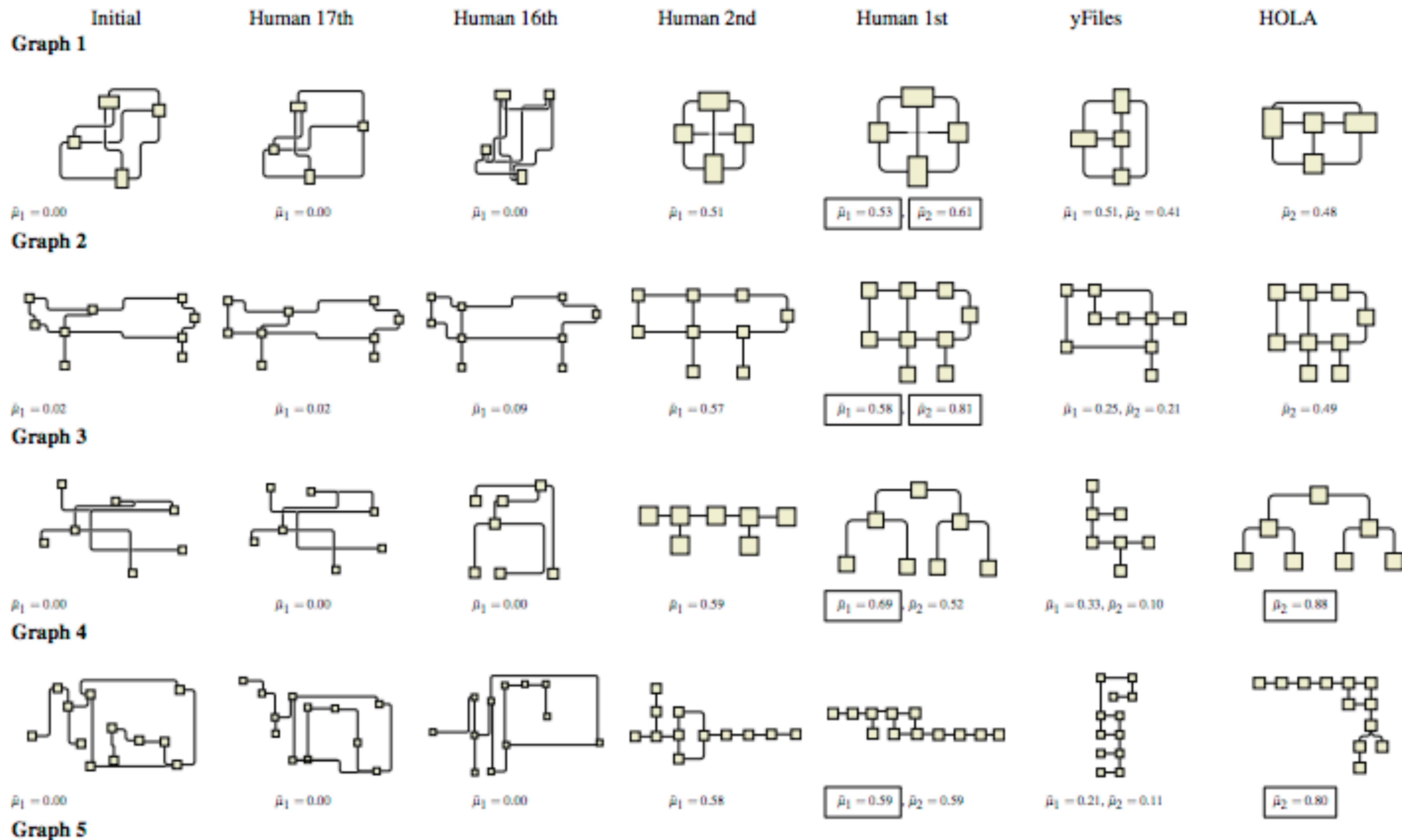
Study how humans lay-out a graph

Try to emulate layout

Left: human, middle: conventional algo, right new algo



[Kieffer et al, InfoVis 2015]



Graphs in 3D

Why, why not visualize graphs in 3D?

Why, why not use AR/VR?

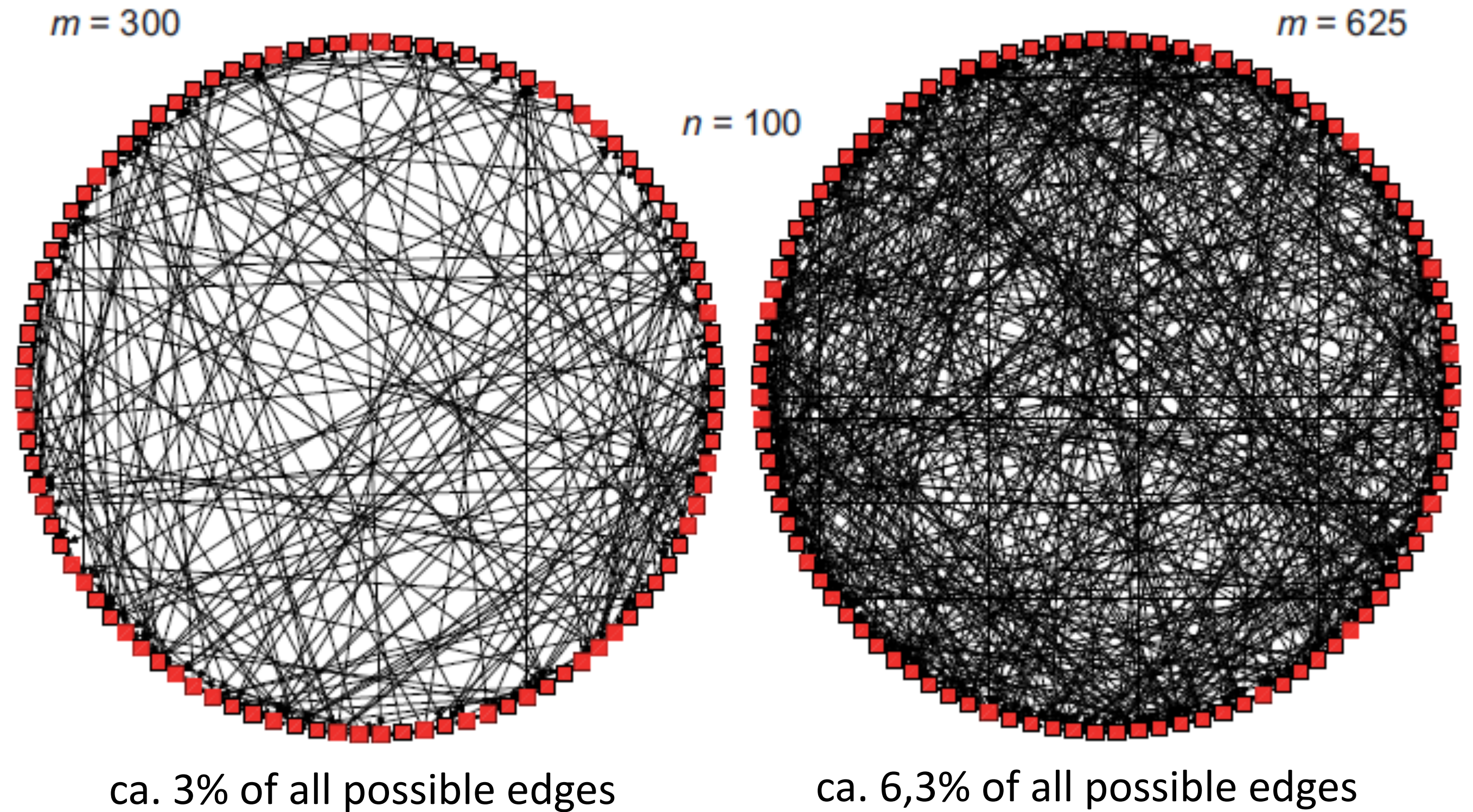


Styled / Restricted Layouts

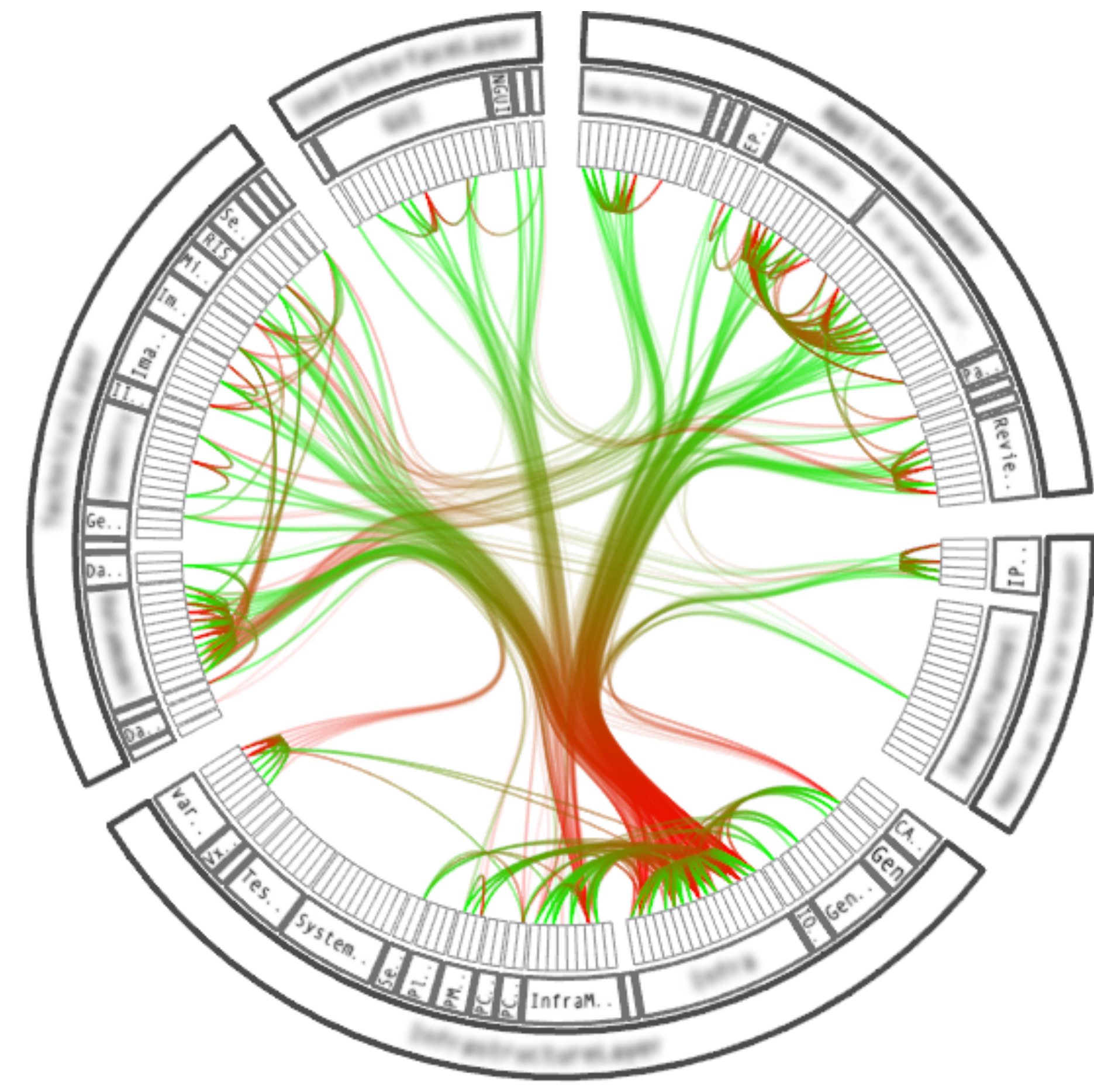
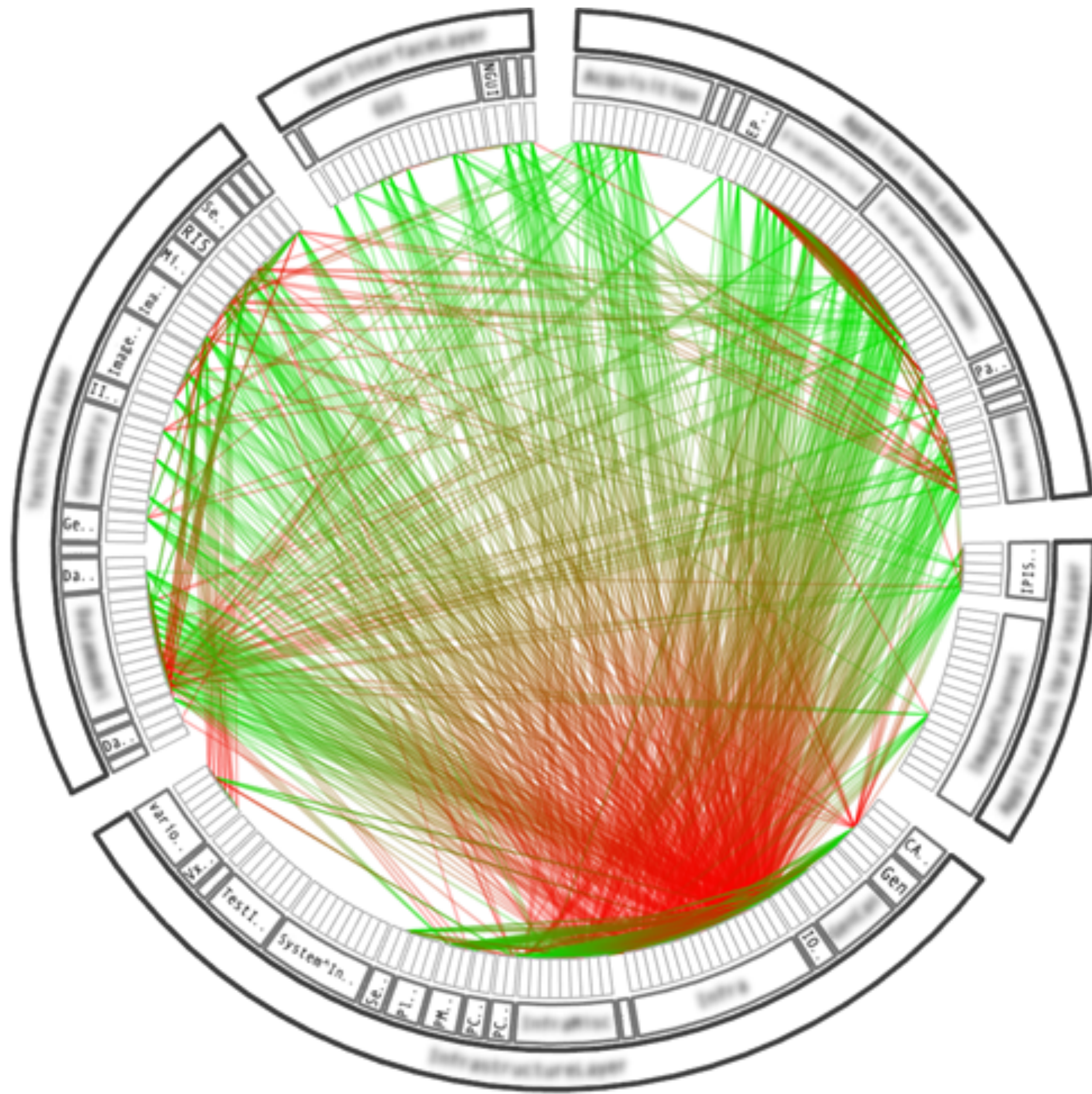
Circular Layout

Node ordering

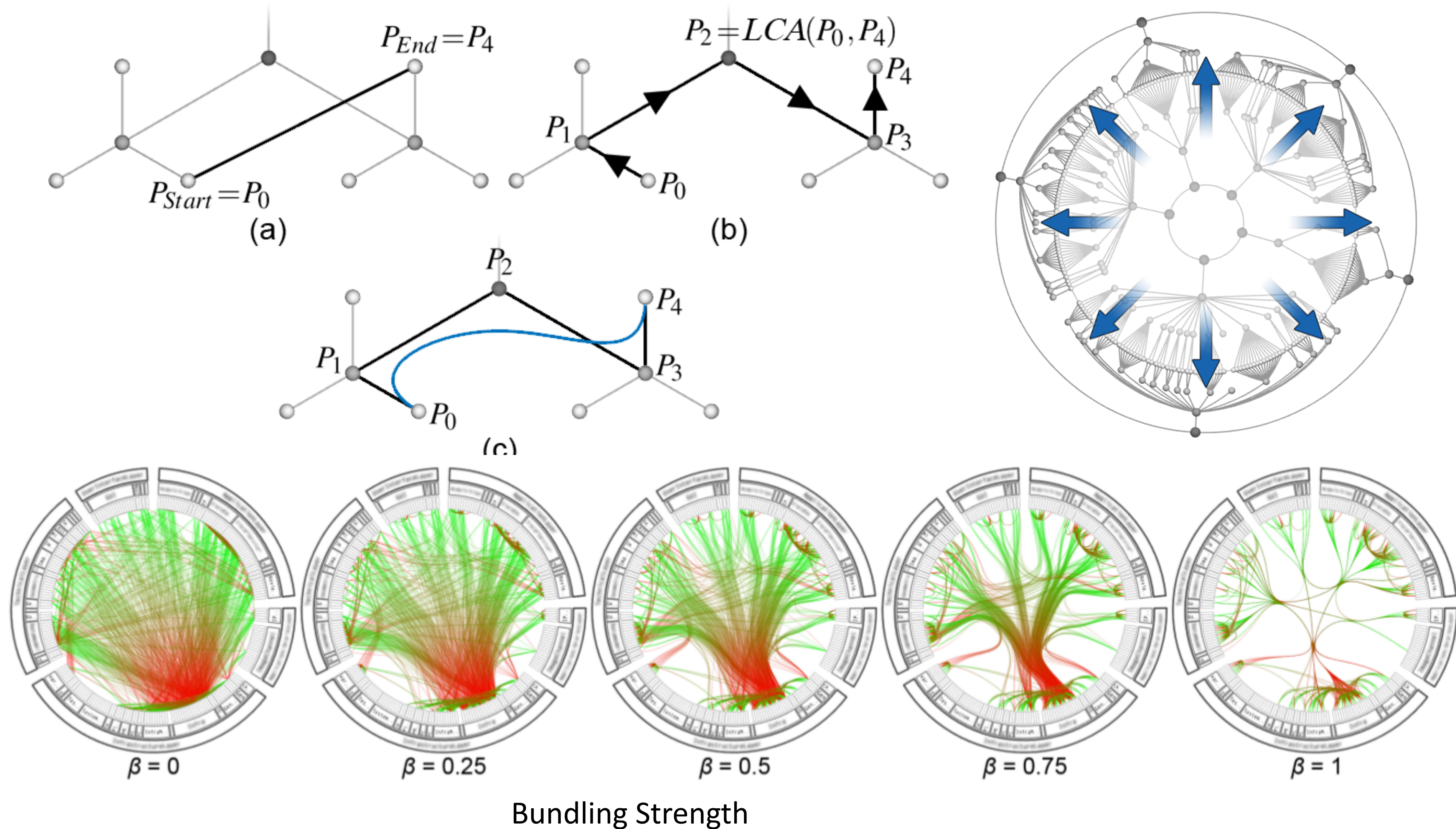
Edge Clutter



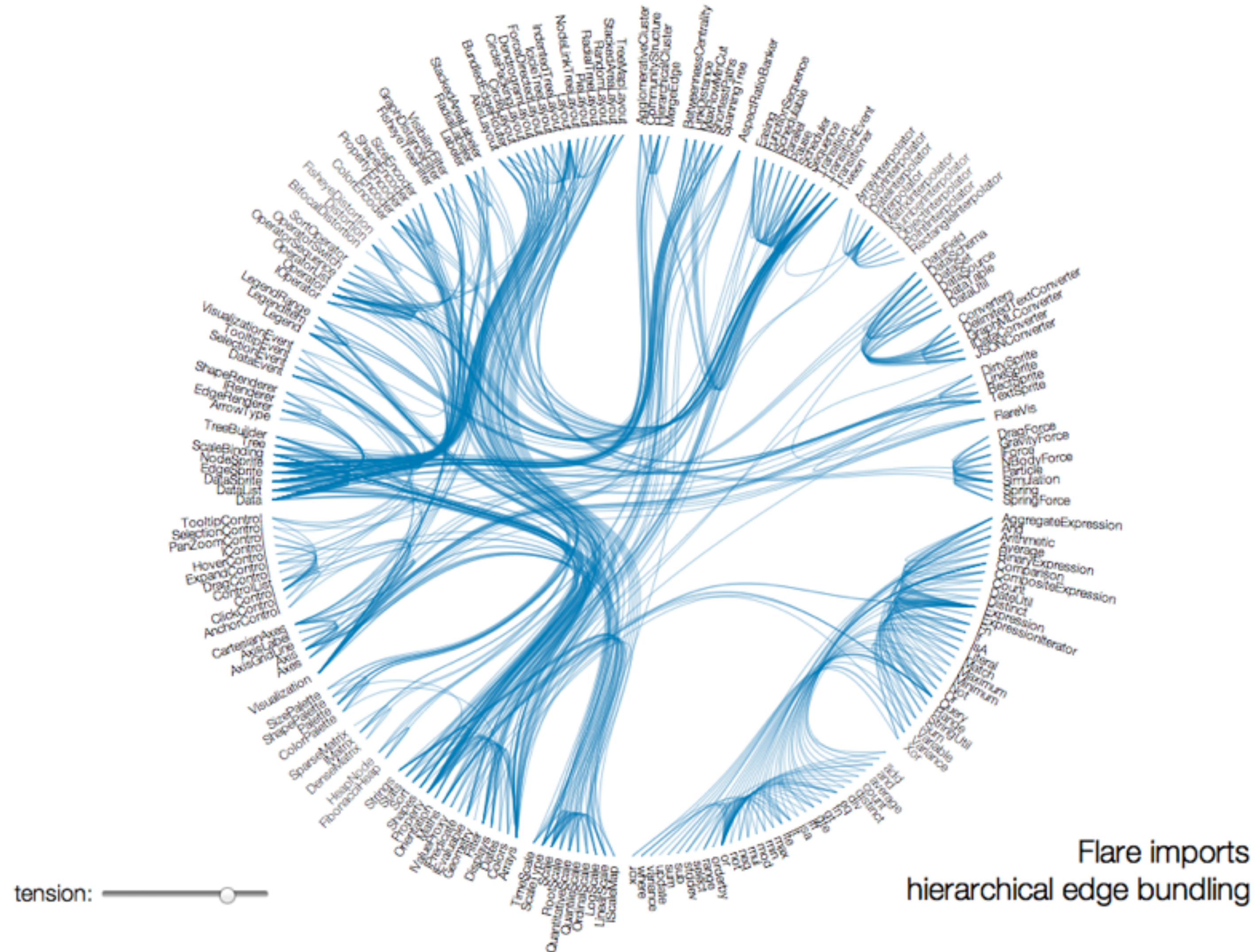
Reduce Clutter: Edge Bundling



Hierarchical Edge Bundling



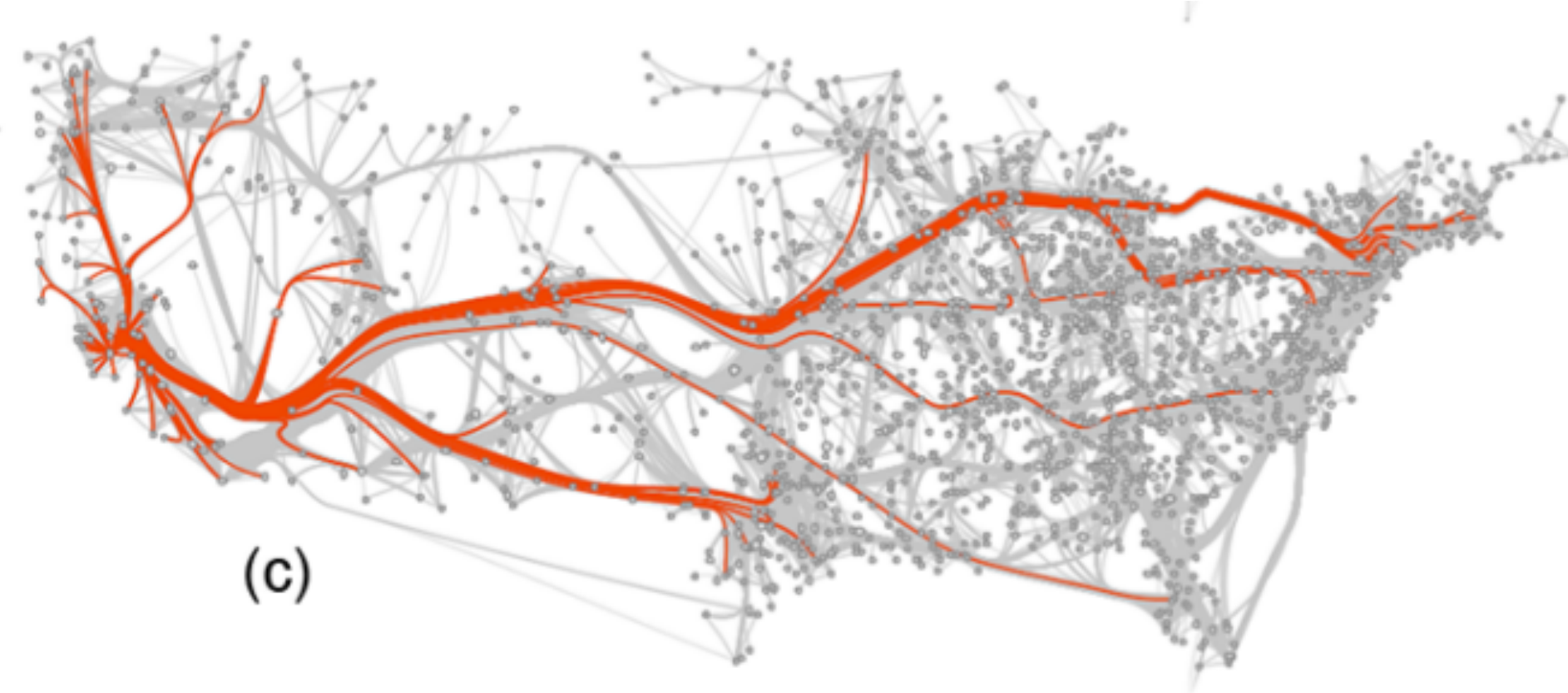
Bundling Strength



Fixed Layouts

Can't vary position of nodes

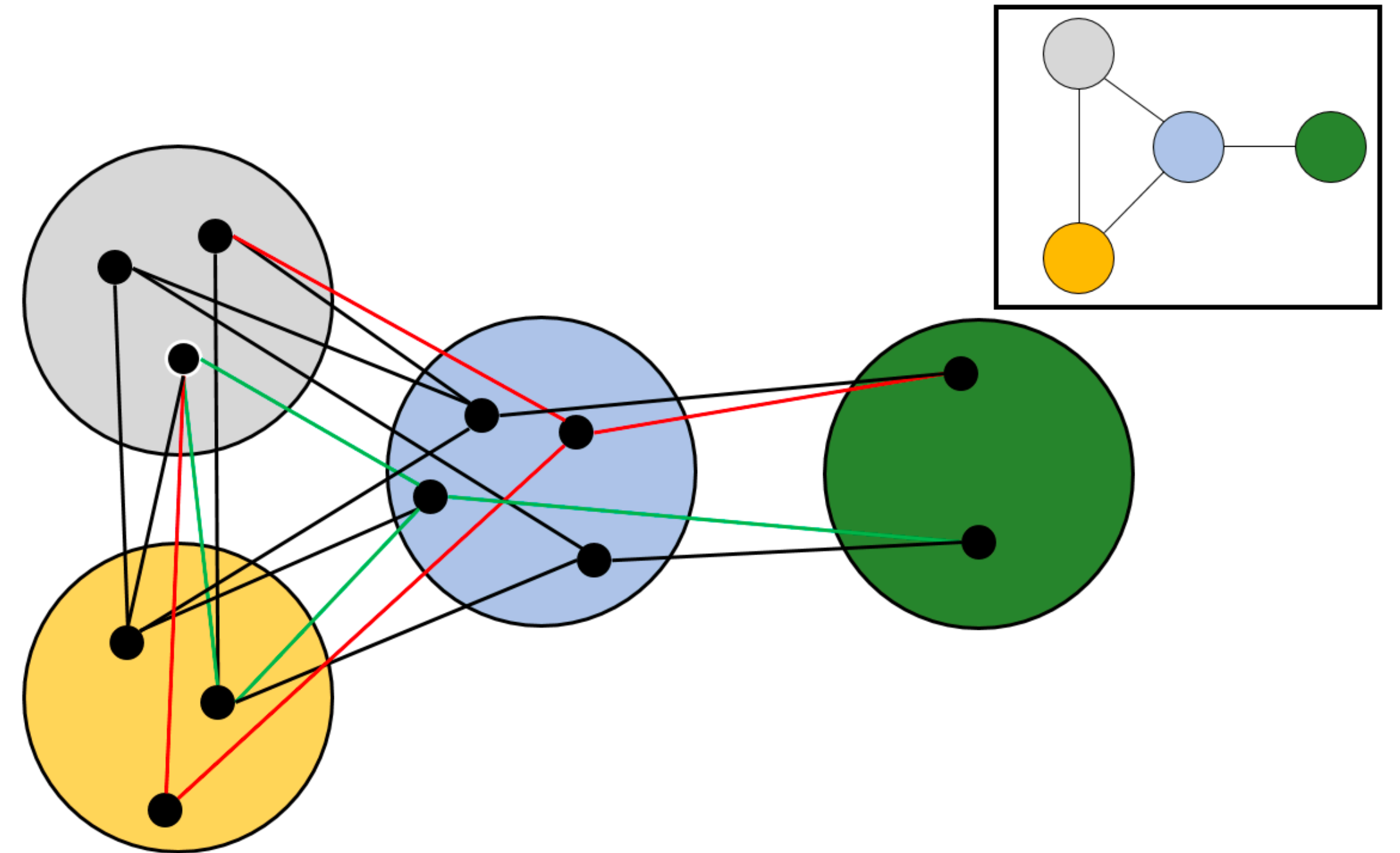
Edge routing important



Supernodes / Aggregation

Supernodes: aggregate of nodes

manual or algorithmic
clustering



Aggregation



<https://youtu.be/E1PVTitj7h0?t=57>

Explicit Representations

Pros:

- able to depict all graph classes

- can be customized by weighing the layout constraints

- very well suited for TBTs, if also a suitable layout is chosen

Cons:

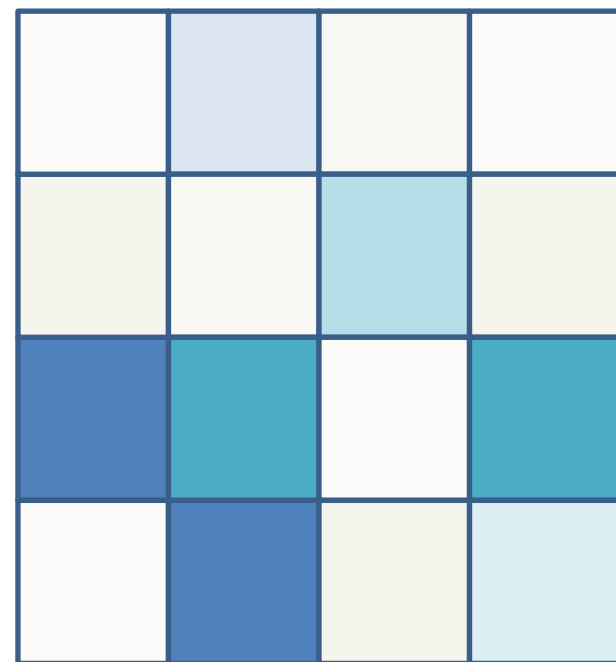
- computation of an optimal graph layout is in NP

- (even just achieving minimal edge crossings is already in NP)

- even heuristics are still slow/complex (e.g., naïve spring embedder is in $O(n^3)$)

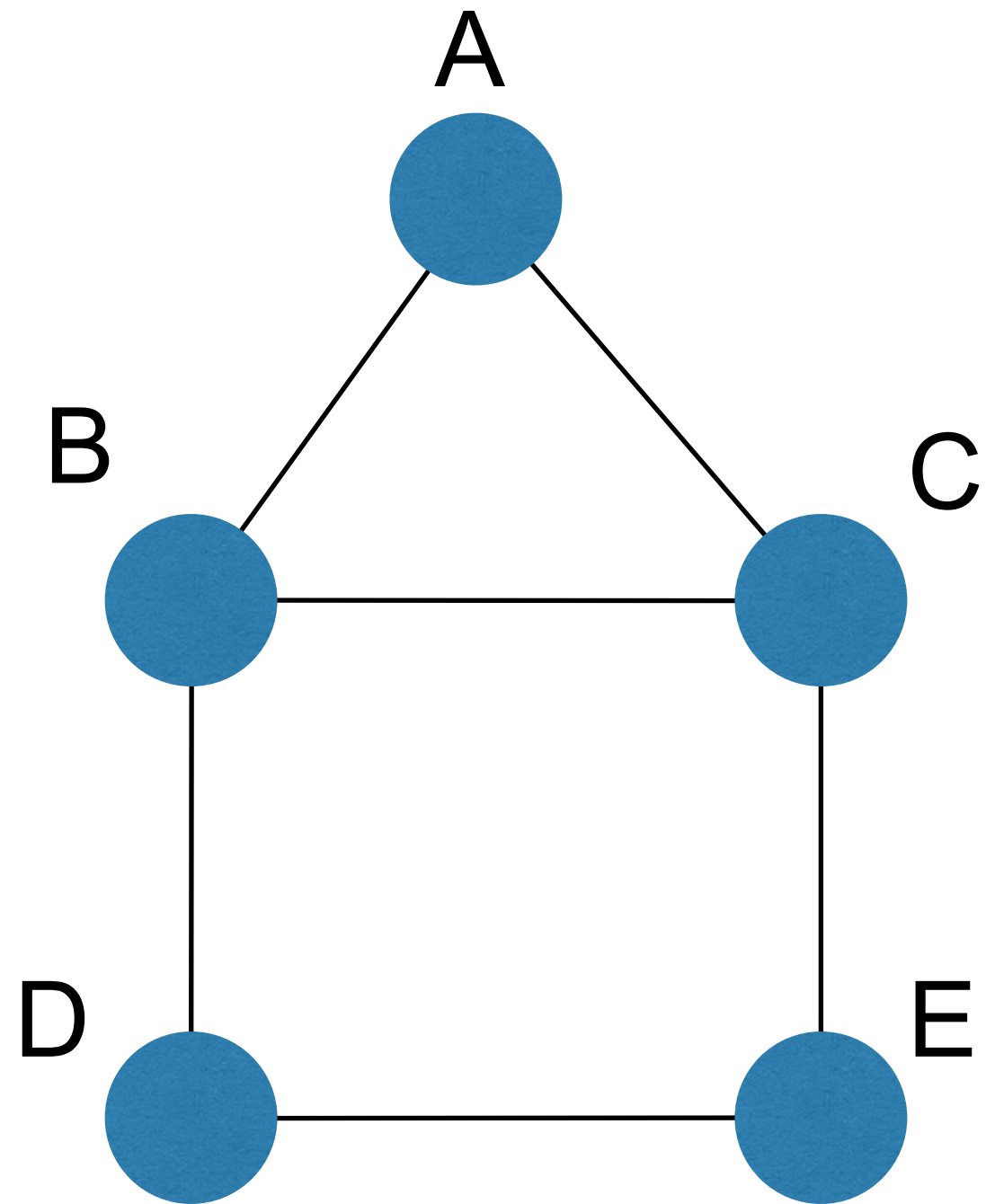
- has a tendency to clutter (edge clutter, “hairball”)

Matrix Representations



Matrix Representations

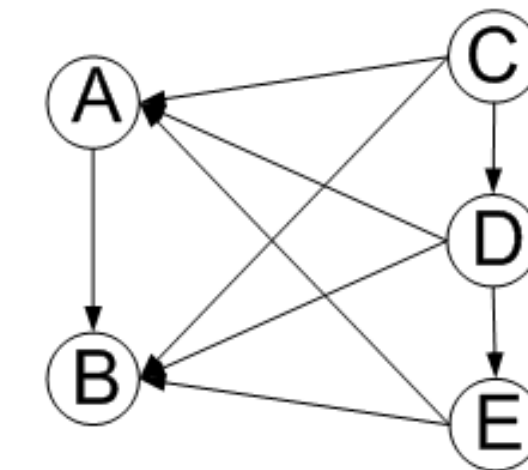
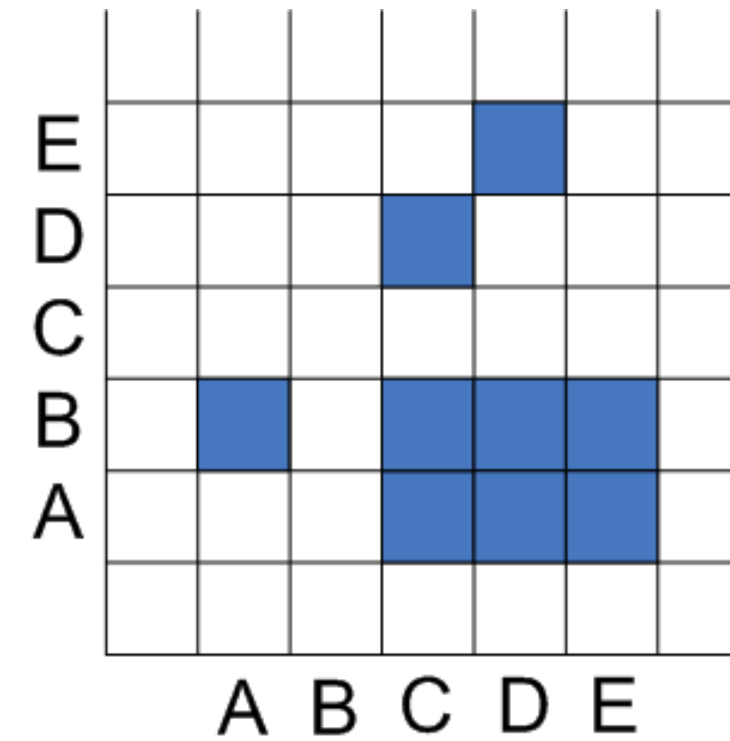
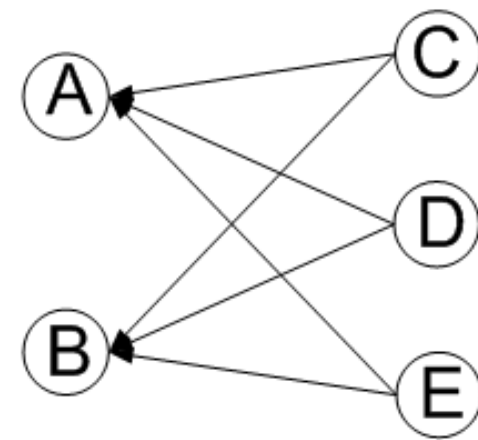
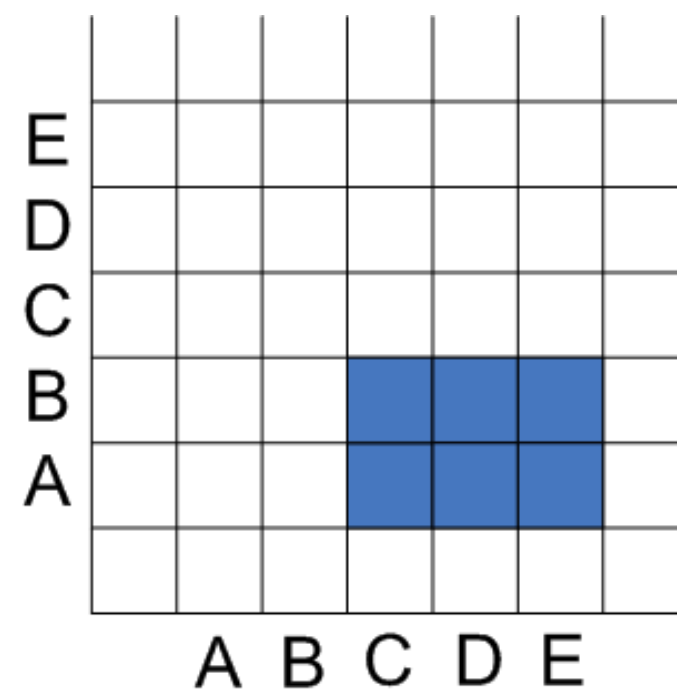
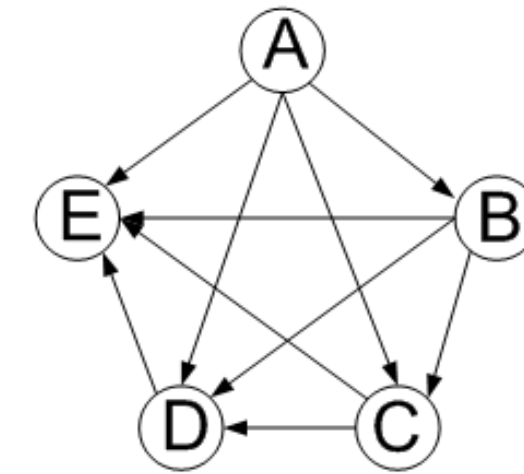
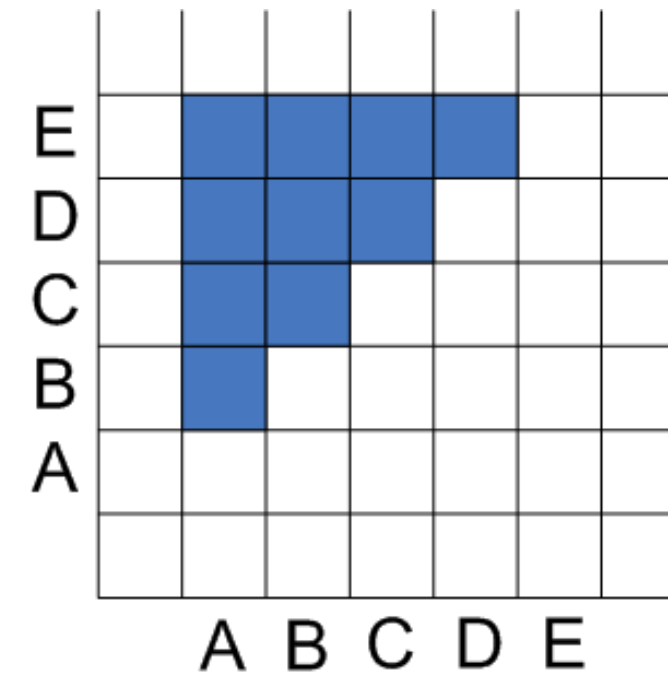
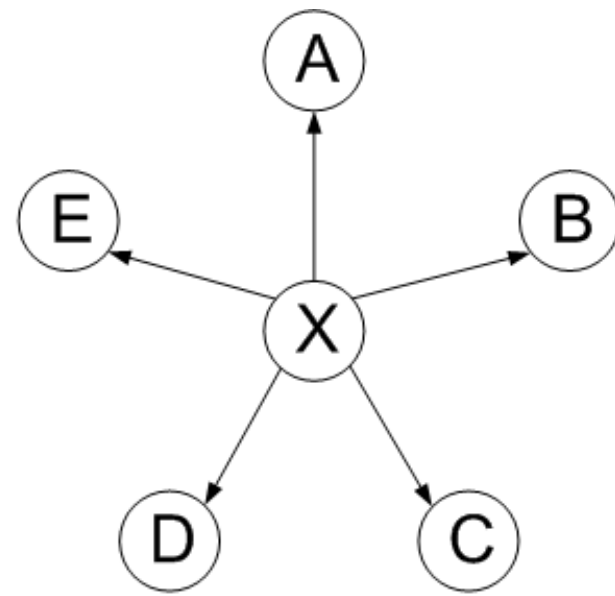
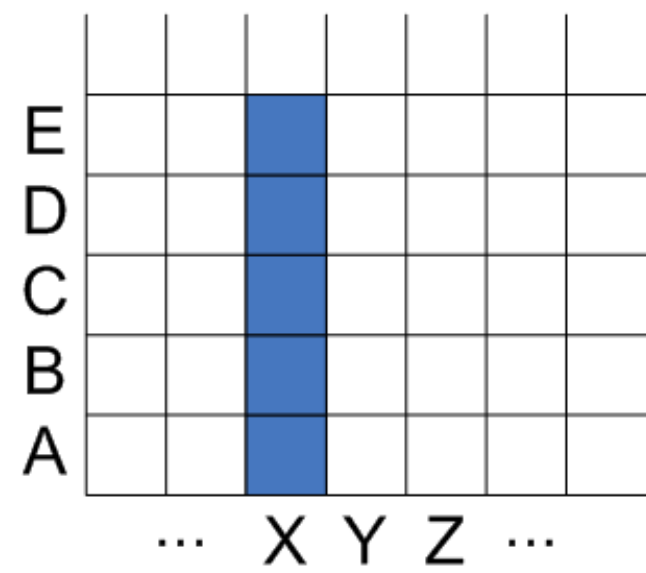
Instead of node link diagram, use adjacency matrix



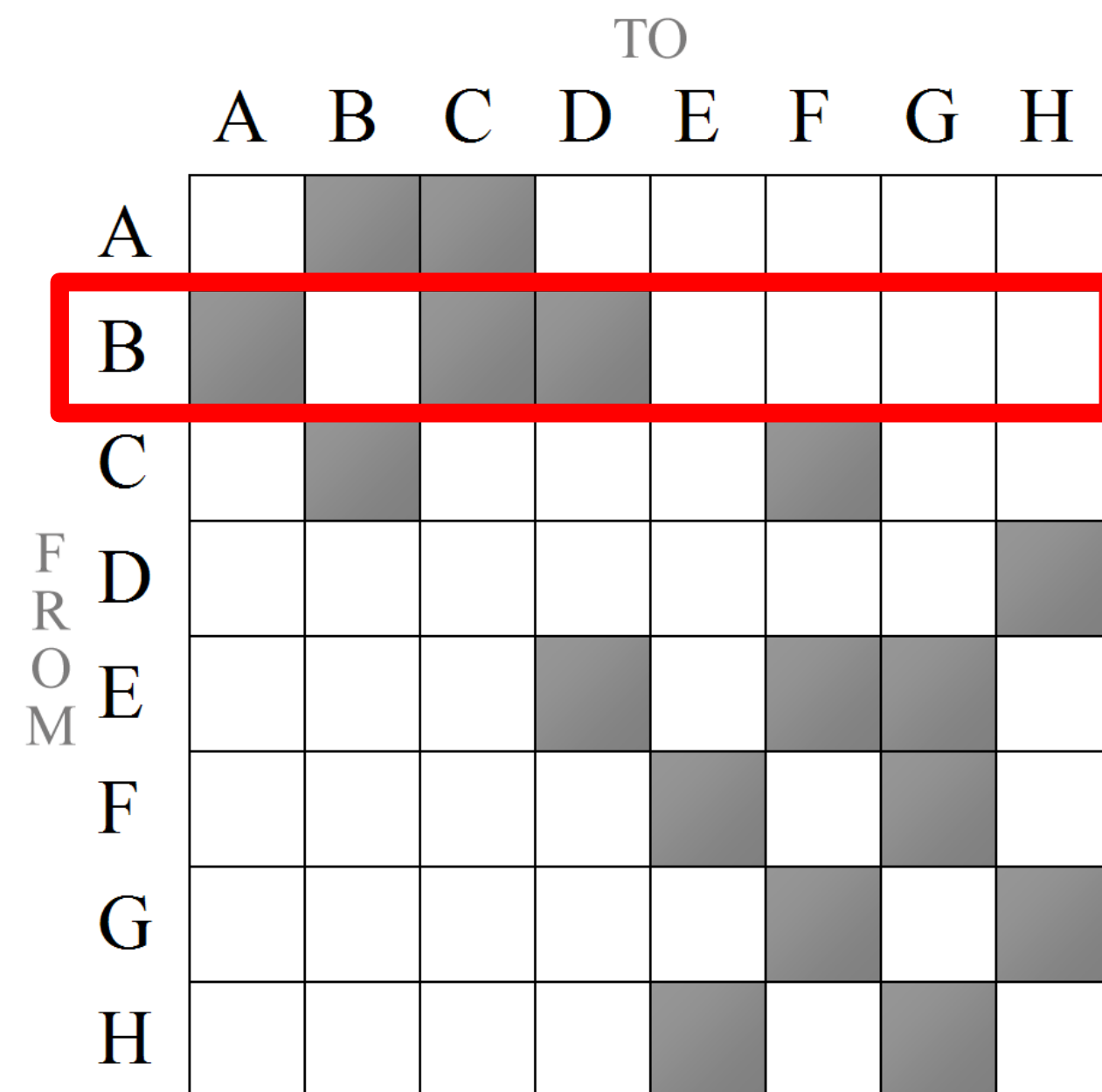
	A	B	C	D	E
A		■	■		
B	■		■	■	
C	■	■			■
D		■			■
E			■	■	

Matrix Representations

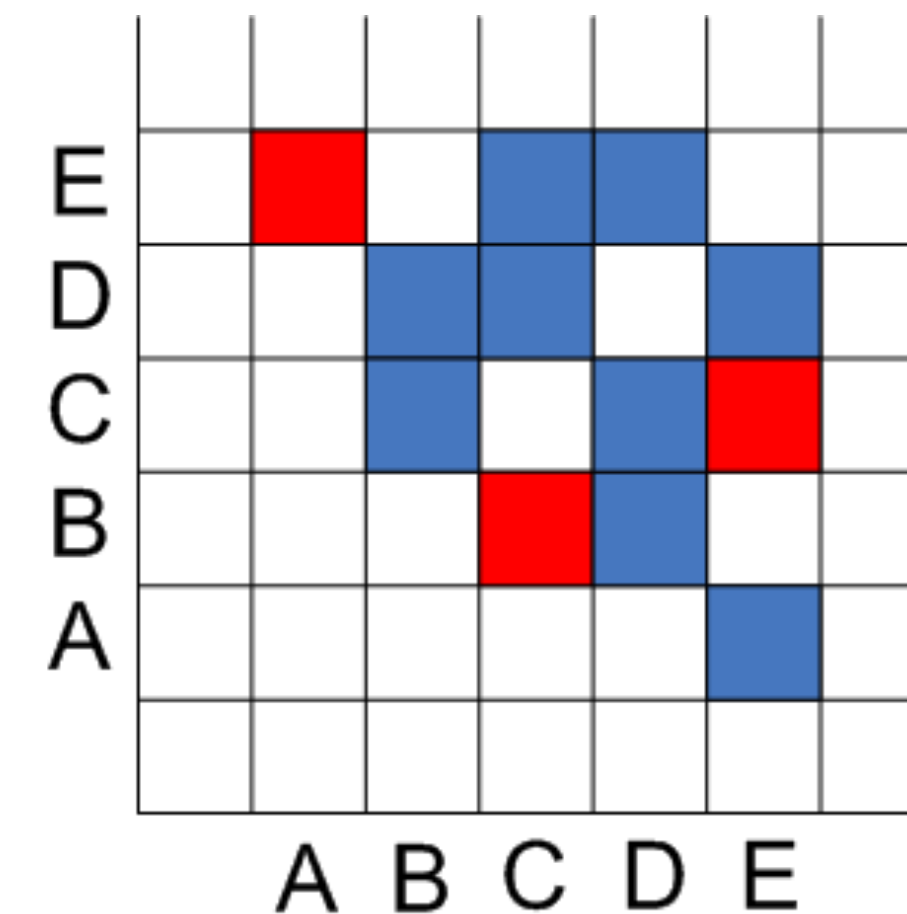
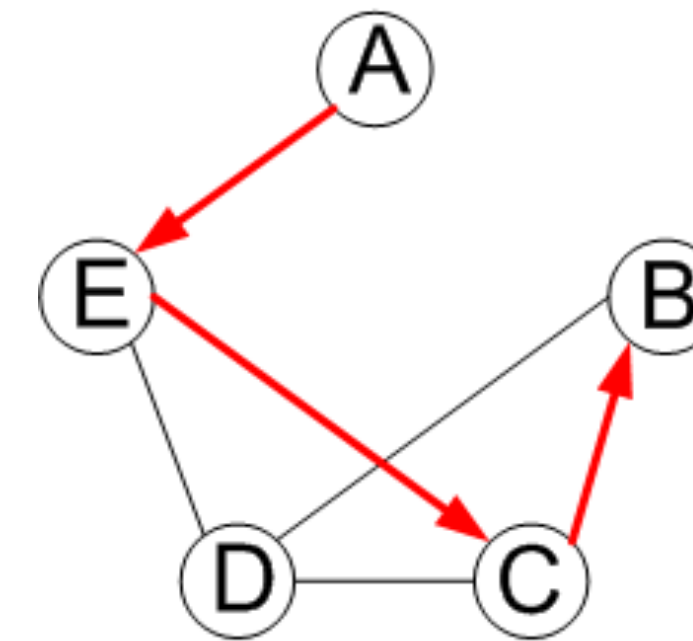
Examples:



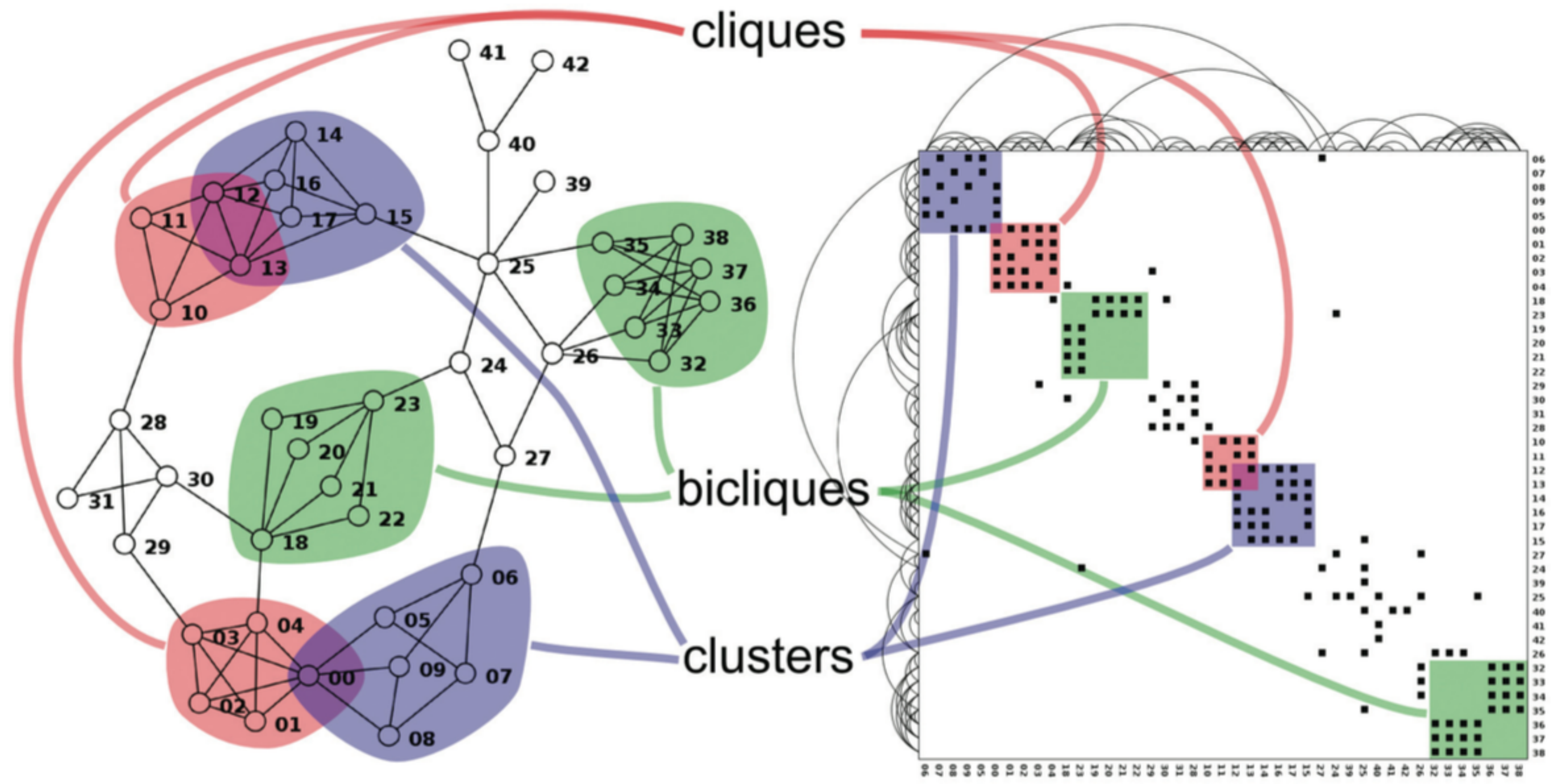
Matrix Representations



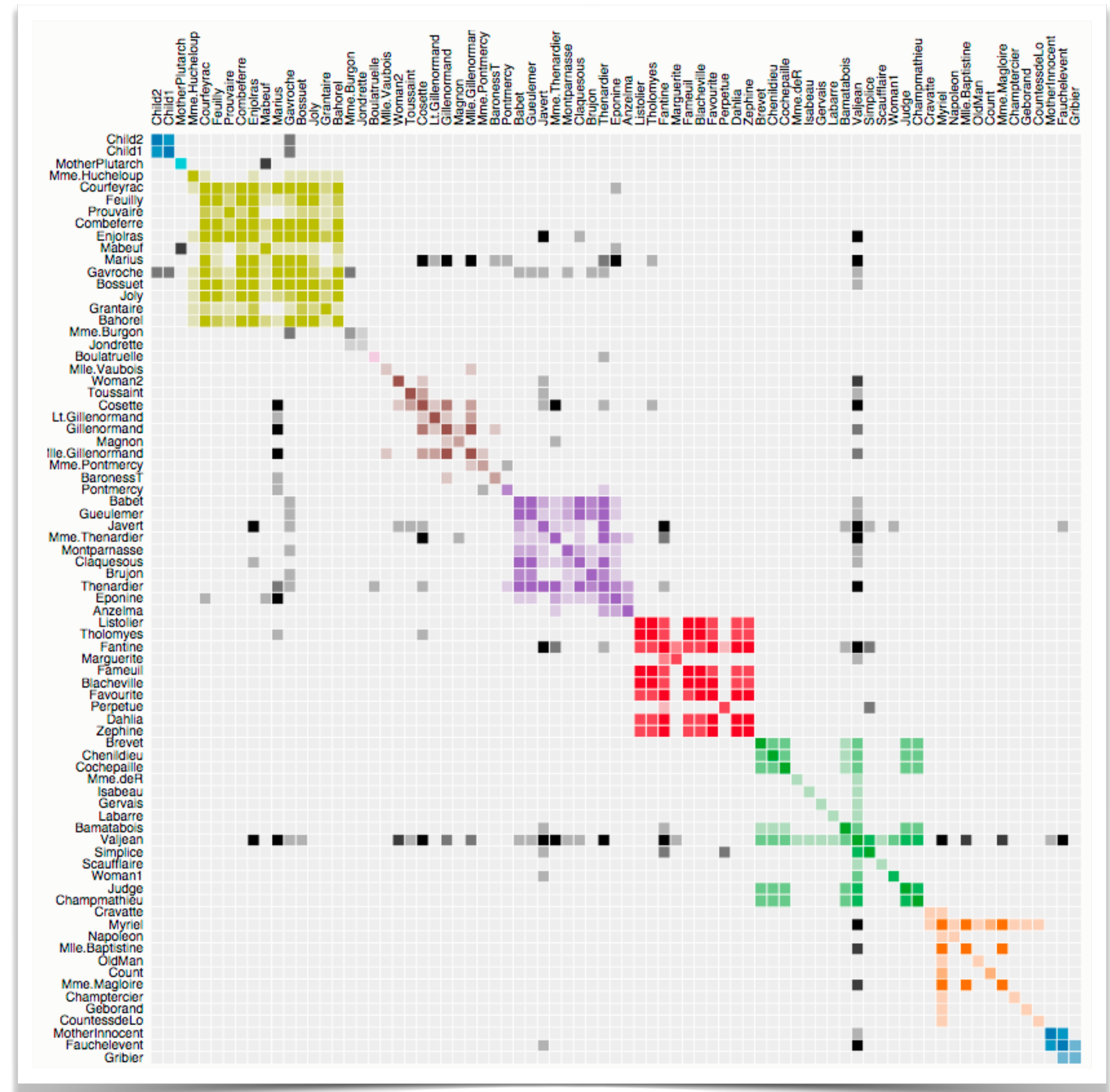
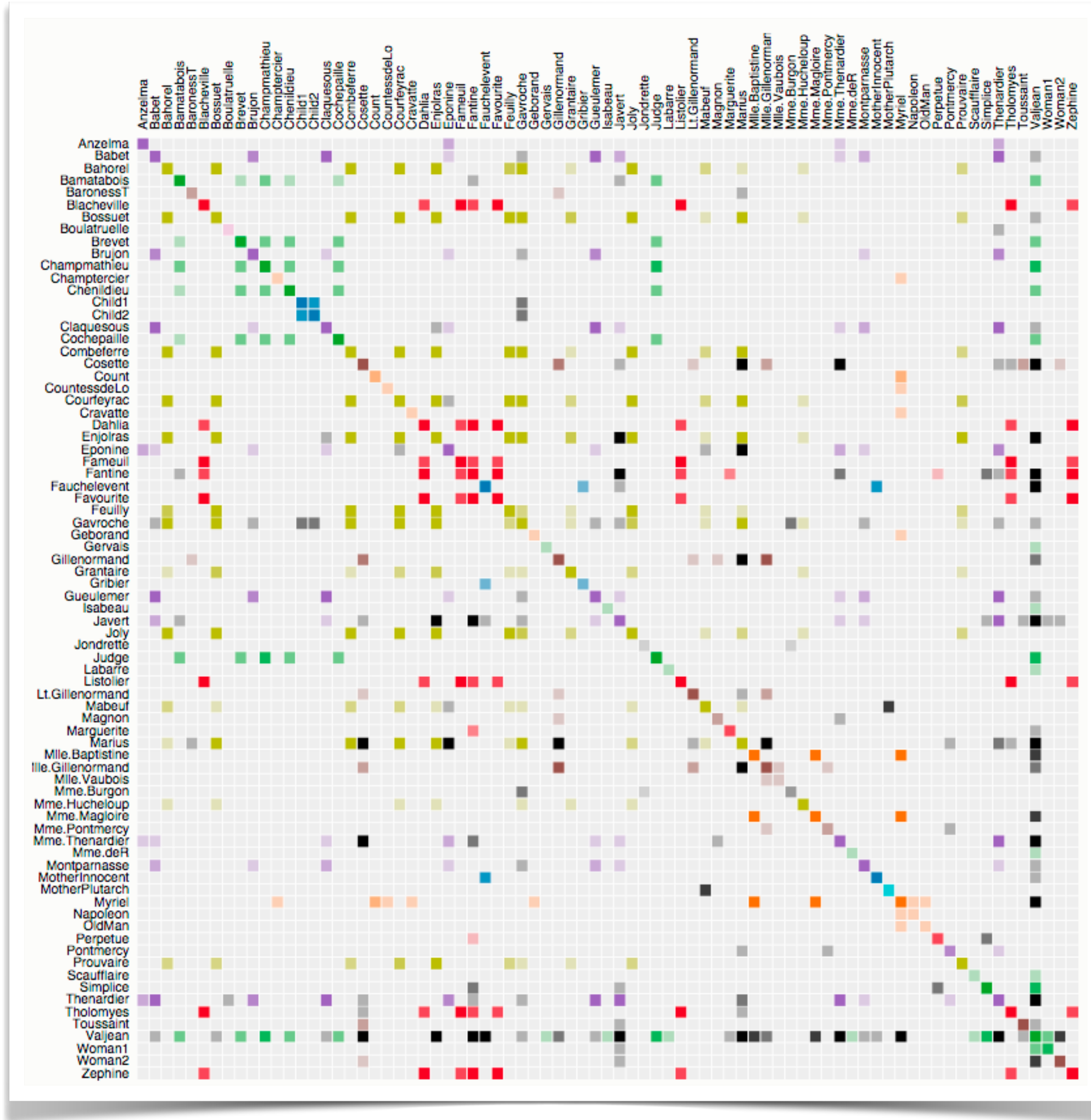
Well suited for
neighborhood-related TBTs



Not suited for
path-related TBTs



Order Critical!



Matrix Representations

Pros:

can represent **all graph classes** except for hypergraphs

puts **focus on the edge set**, not so much on the node set

simple grid -> **no elaborate layout** or rendering needed

well suited for **ABT on edges** via coloring of the matrix cells

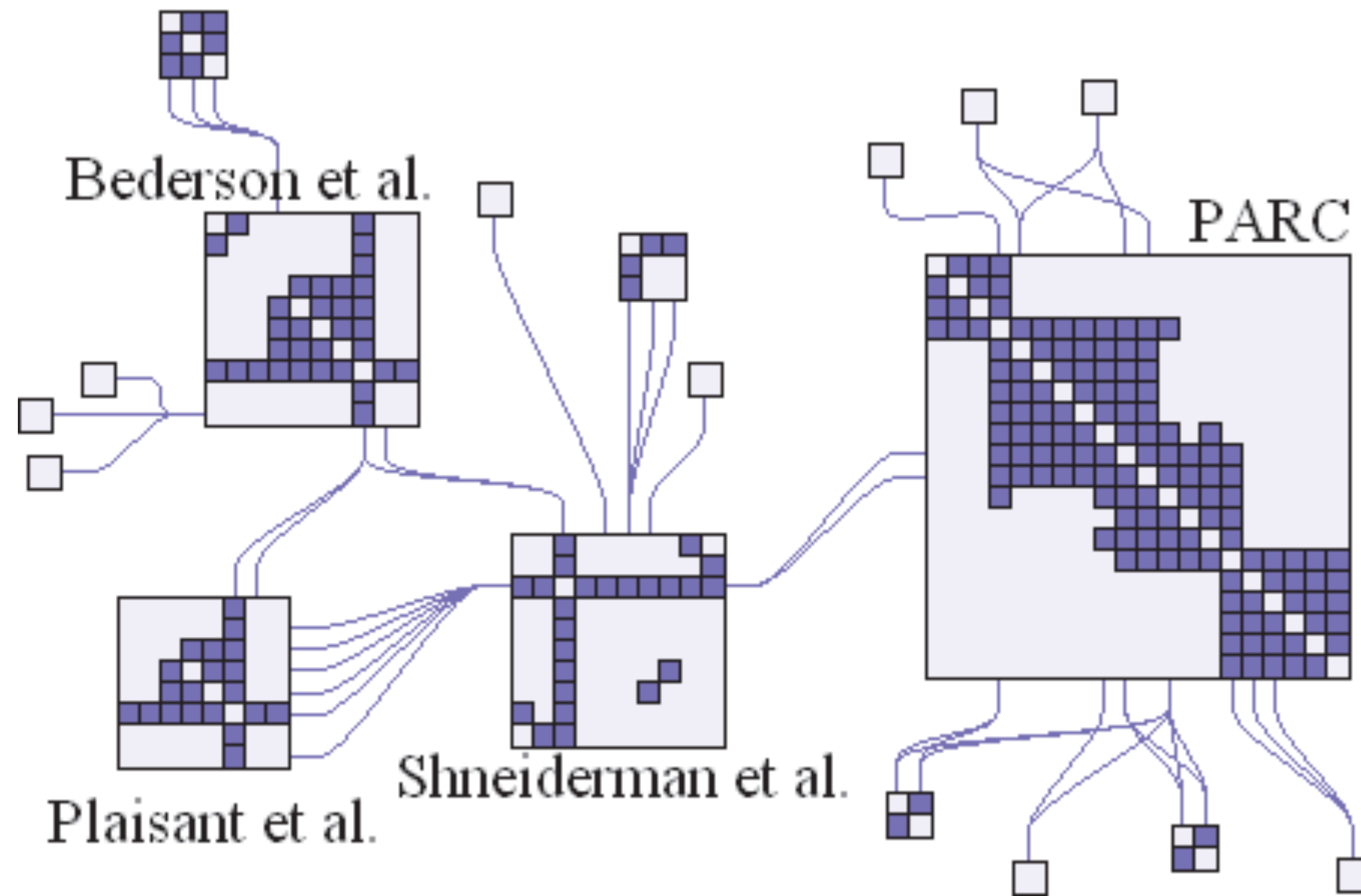
well suited for **neighborhood-related TBTs** via traversing rows/columns

Cons:

quadratic screen space requirement (any possible edge takes up space)

not suited for path-related TBTs

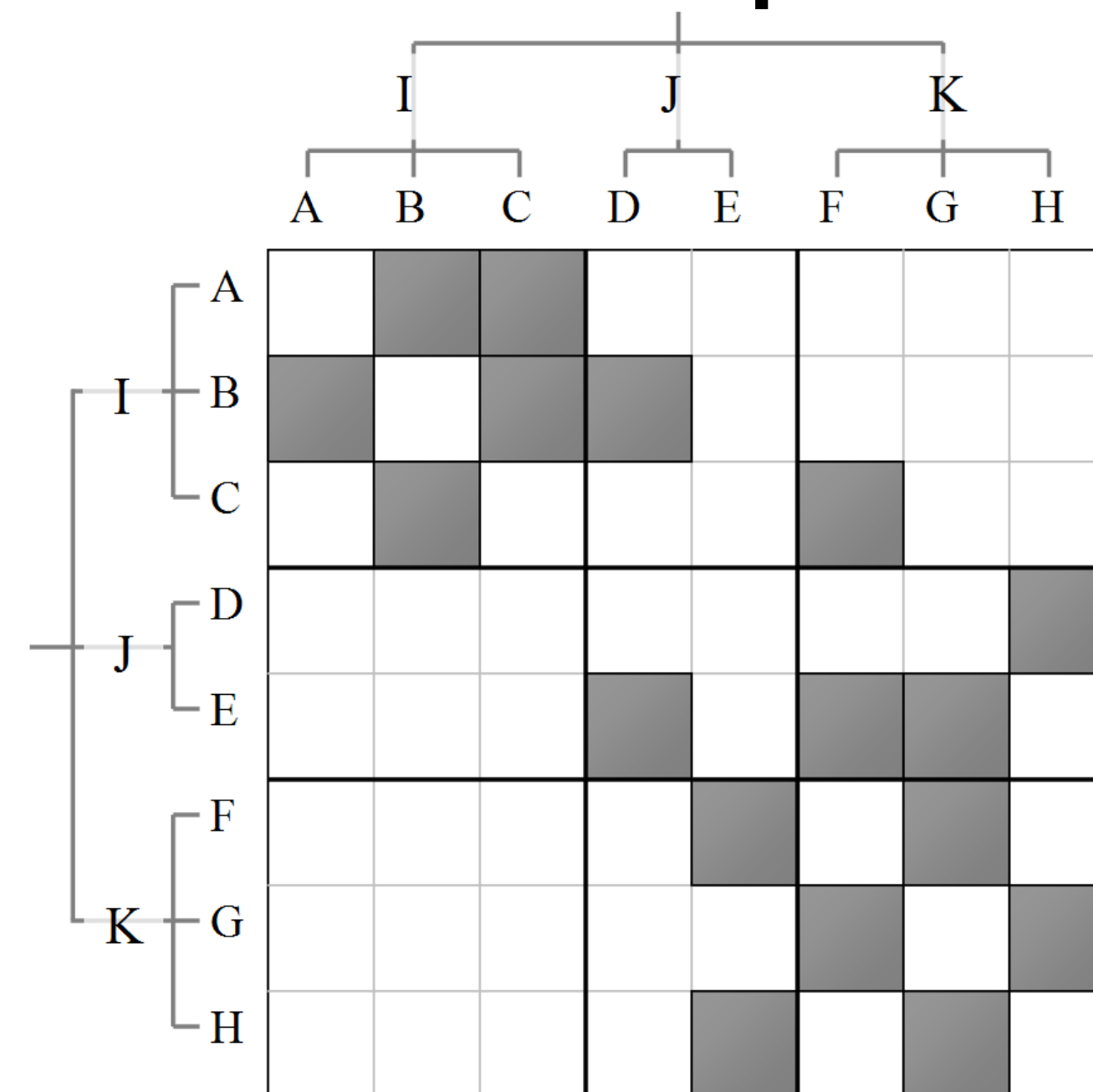
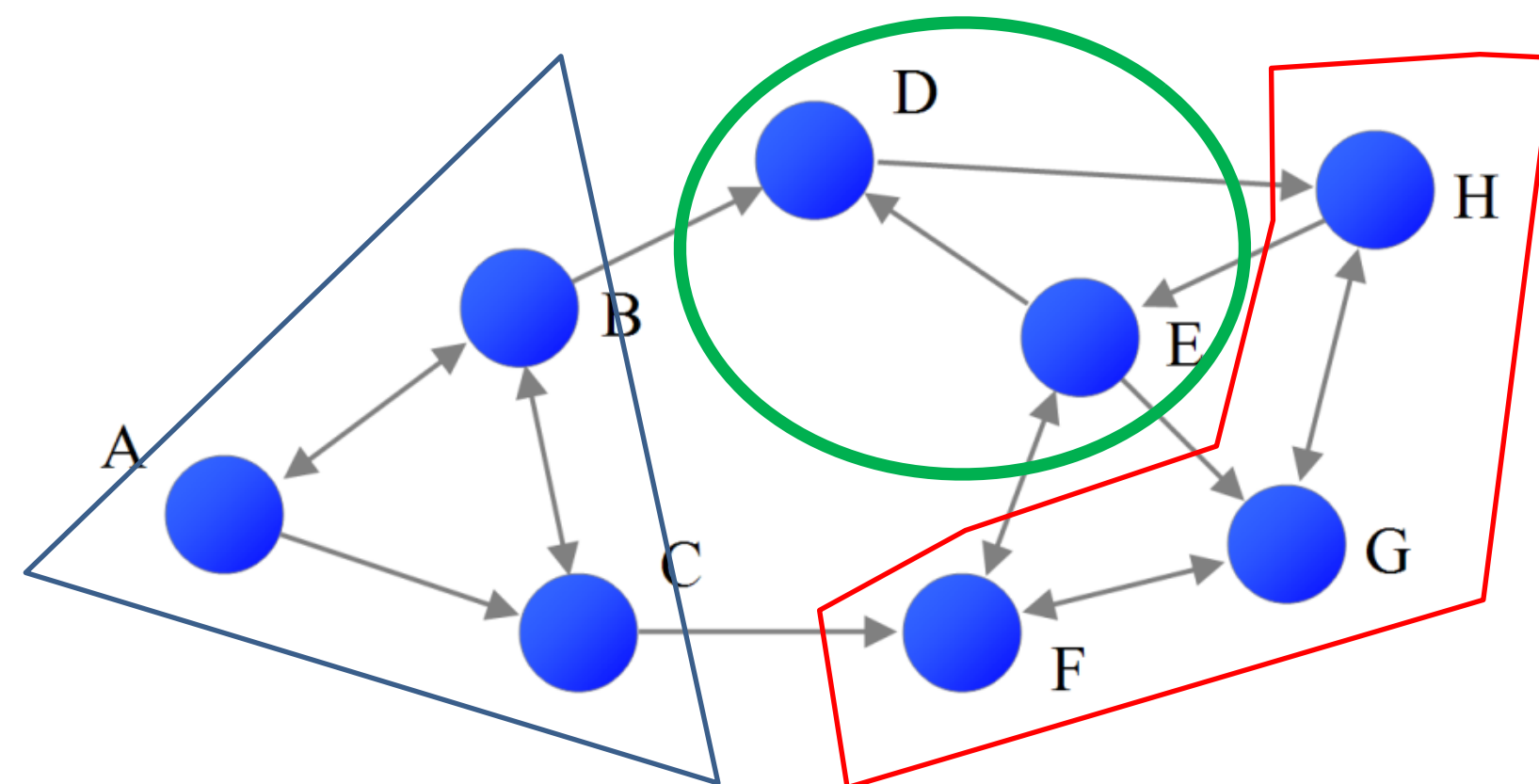
Hybrid Explicit/Matrix



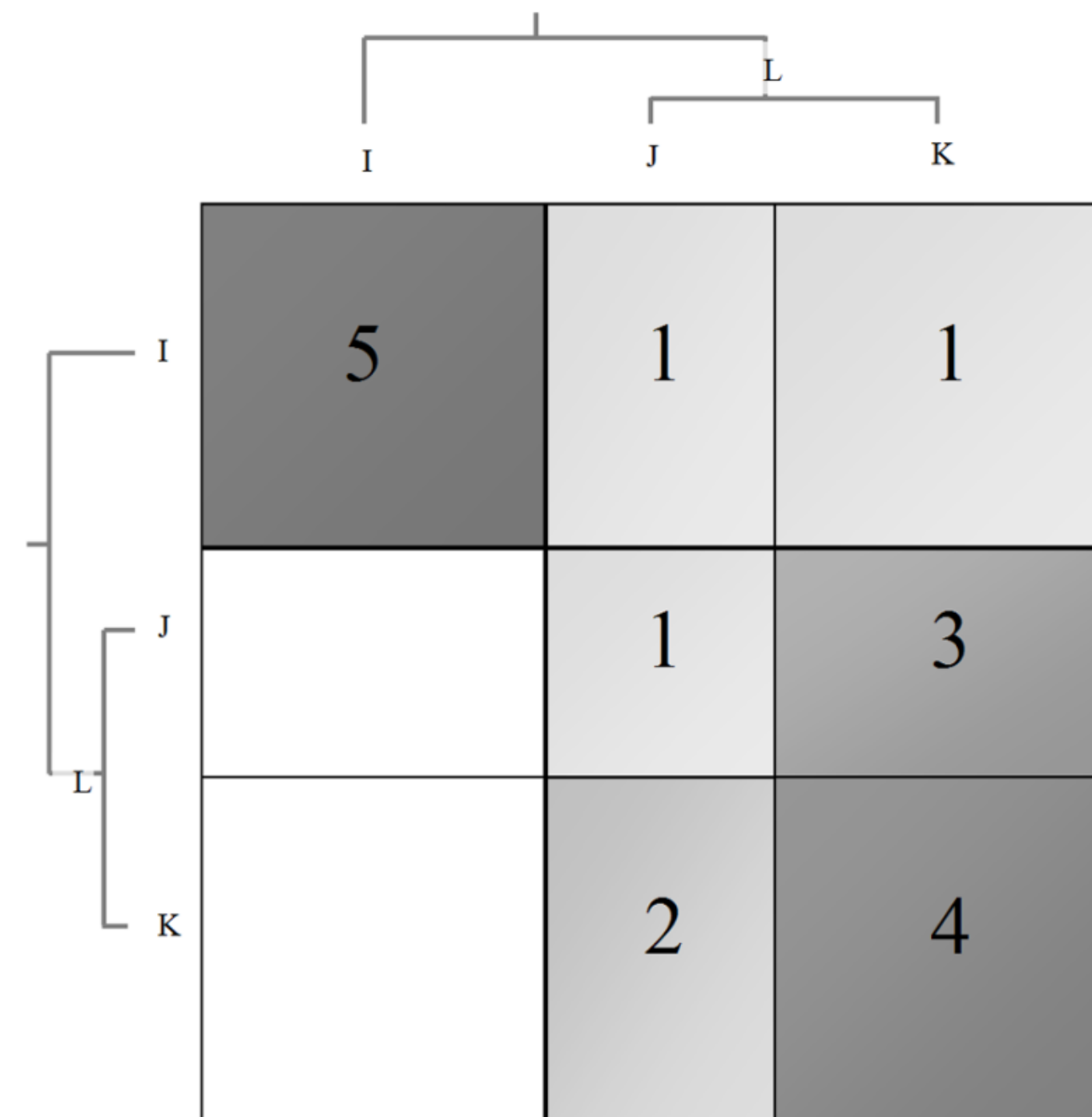
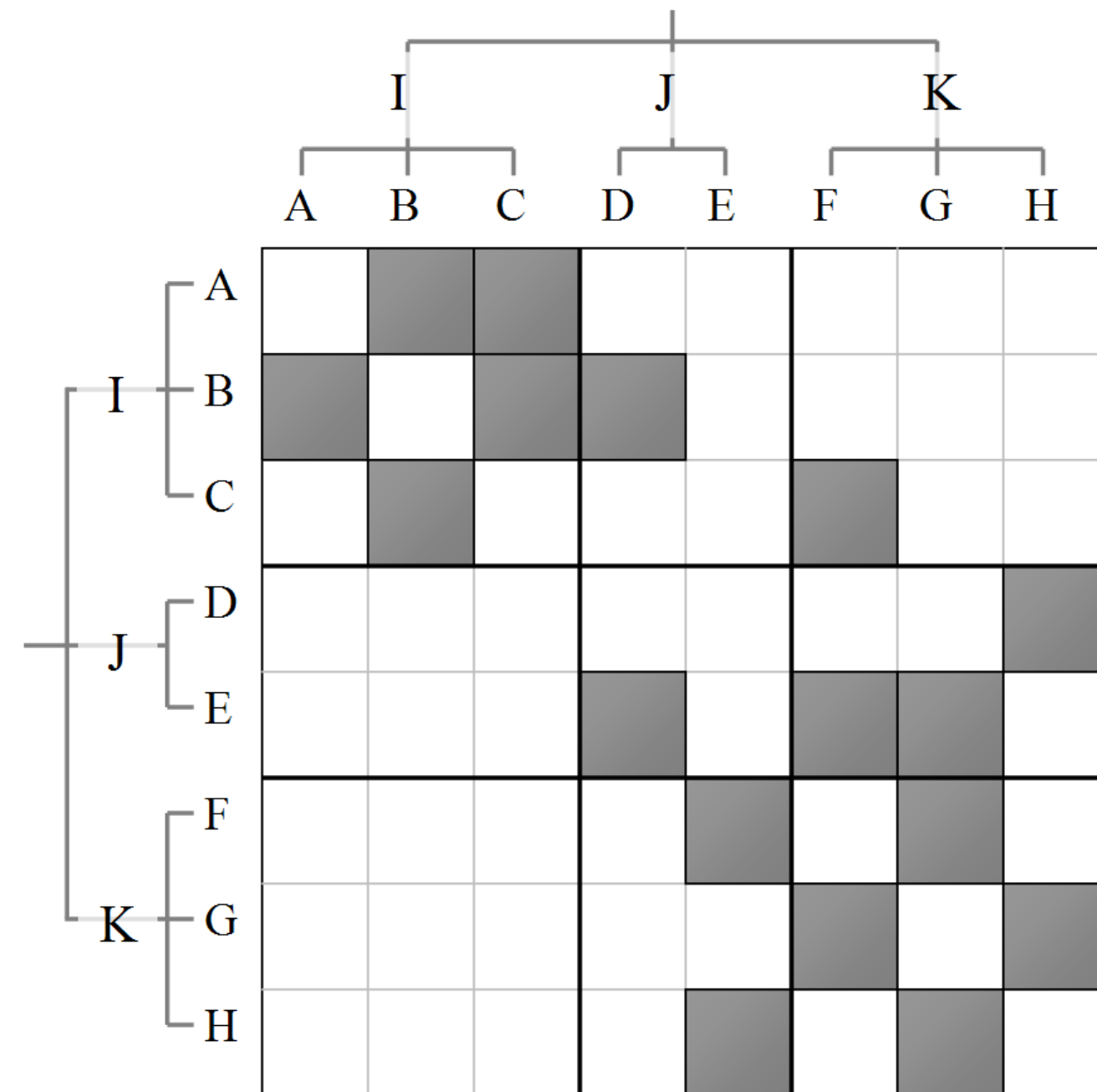
Matrix Representations

Problem: used screen real estate is quadratic in the number of nodes

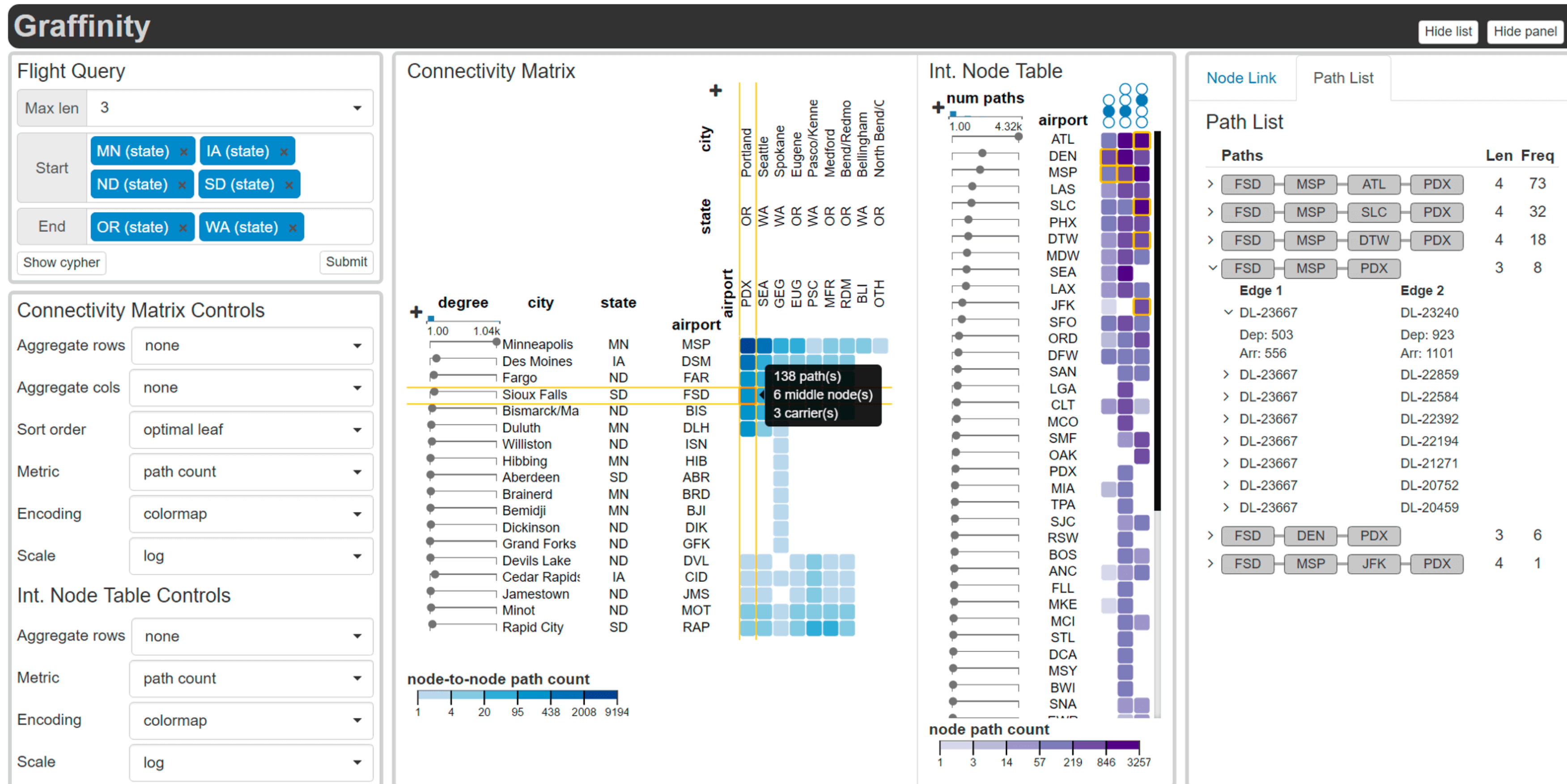
Solution approach: hierarchization of the representation



Matrix Representations



Higher-Order Connectivity



Trees

Tree-Exercise

Tree Exercise

Here is part of a directory structure used for the material for this class and the relative file size.

datavis-17/

lectures/

Intro.key (110 MB)

perception/

Perception.key (113 MB)

Blindness.mov (15MB)

Data.key (12 MB)

Graphs.key (180 MB)

exams/

Exam1-solution.doc (5MB)

Exam1.doc (1MB)

exercise/

Graph.doc (3MB)

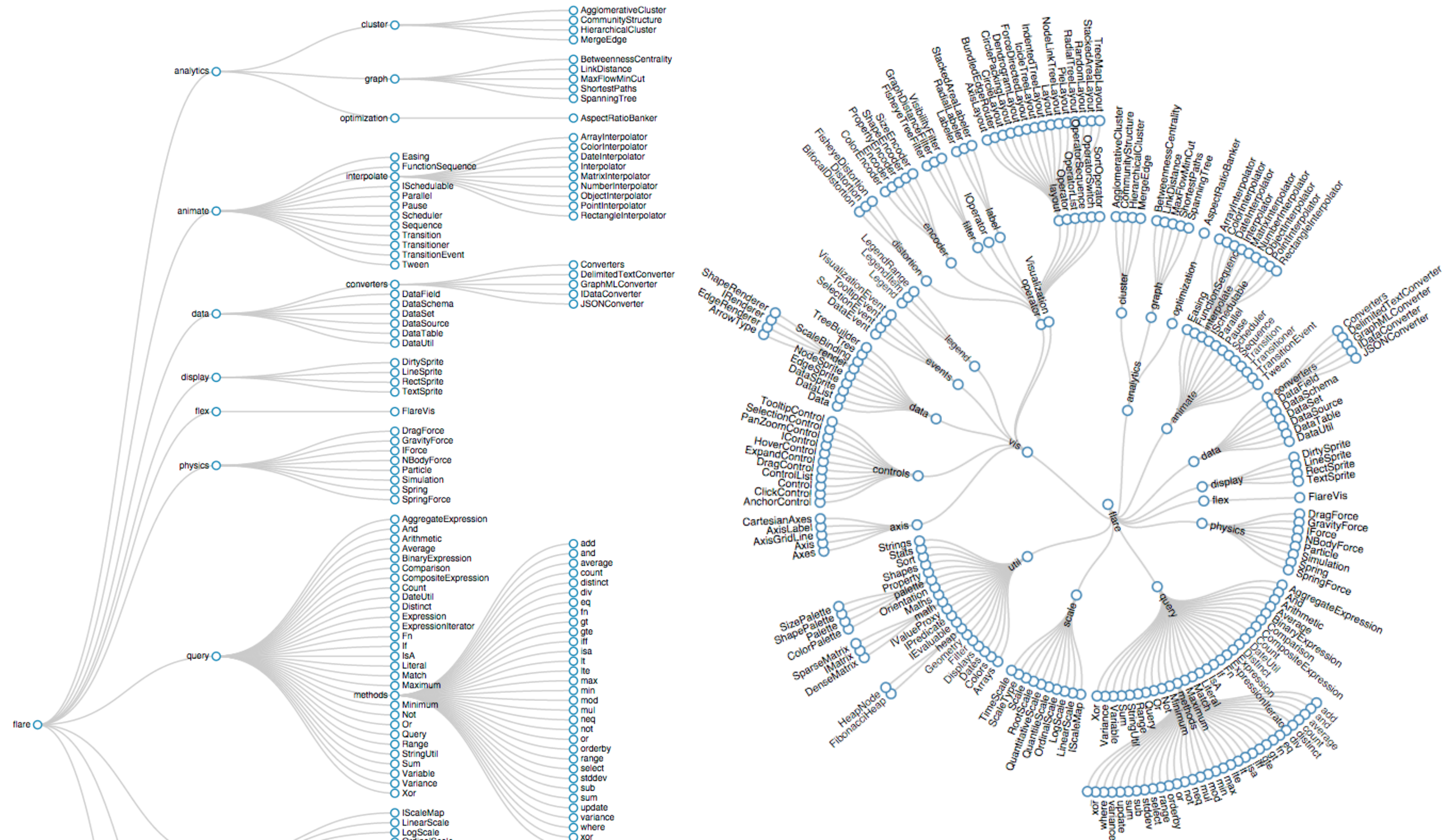
Graph-video.doc (210MB)

Sketch two different visualizations that show both, the directory structure and the size of the directories and the contained files.

Explicit Tree Visualization

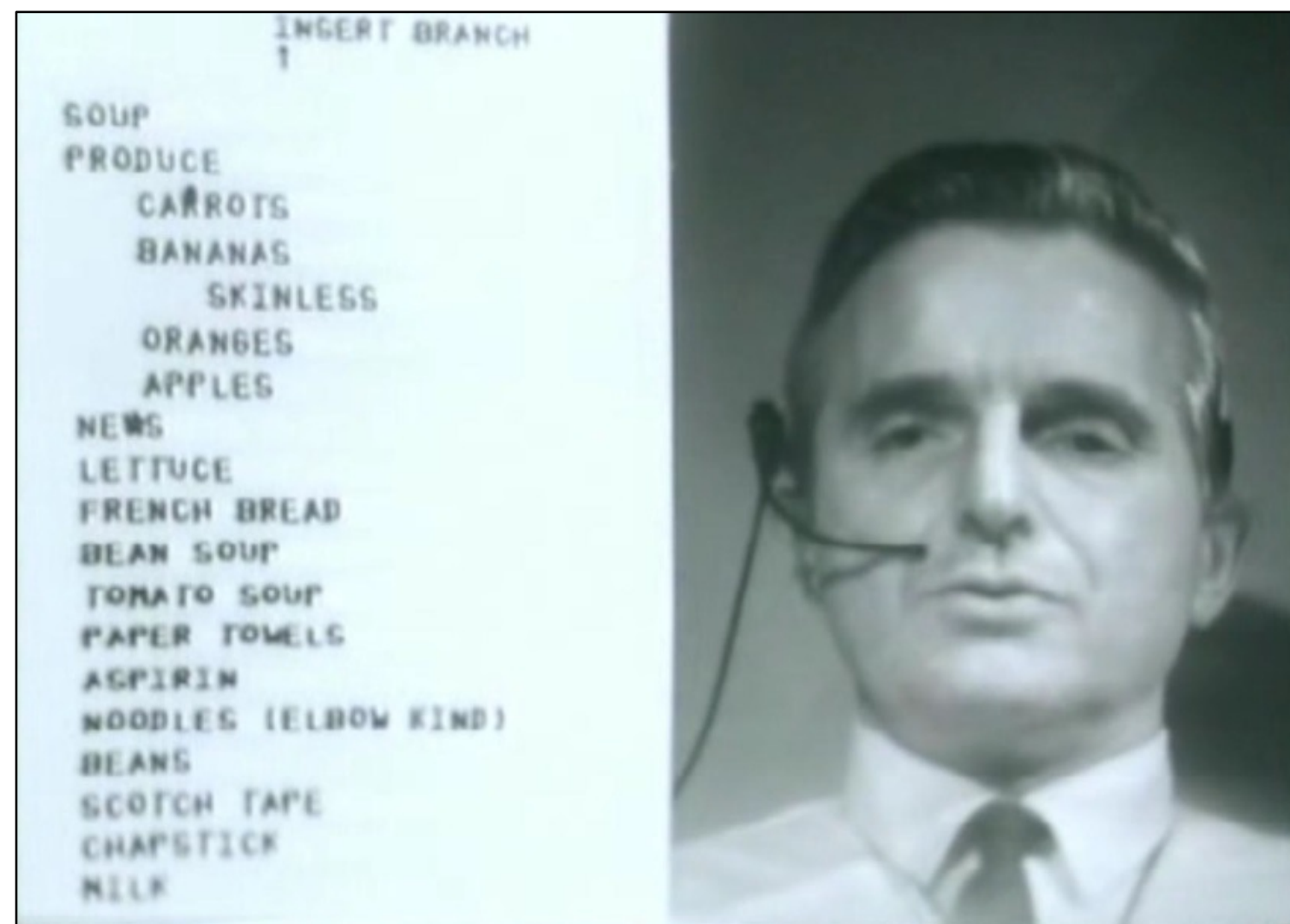
Reingold–
Tilford layout

<http://billmill.org/pymag-trees/>

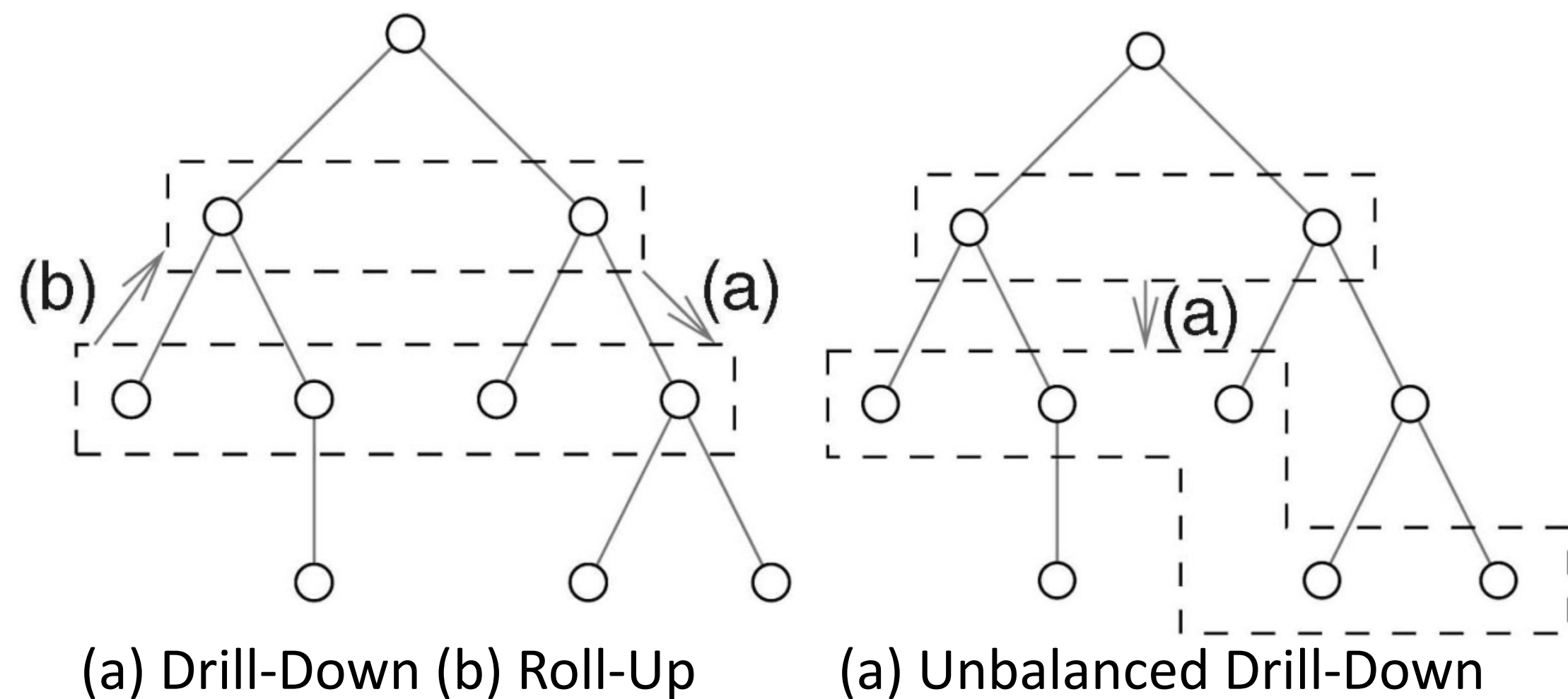


Manipulating Aggregation Levels

First interactive tree manipulation



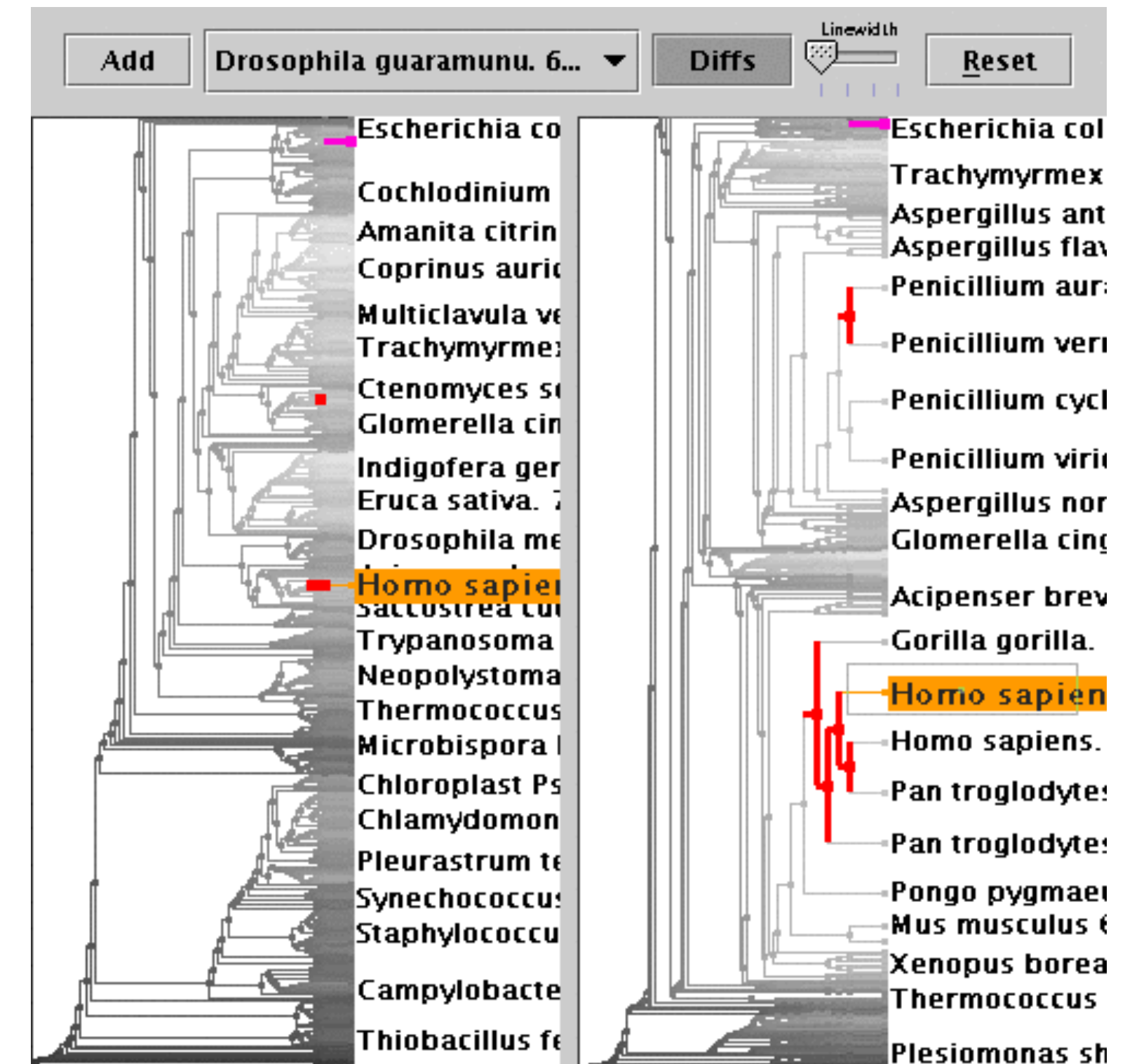
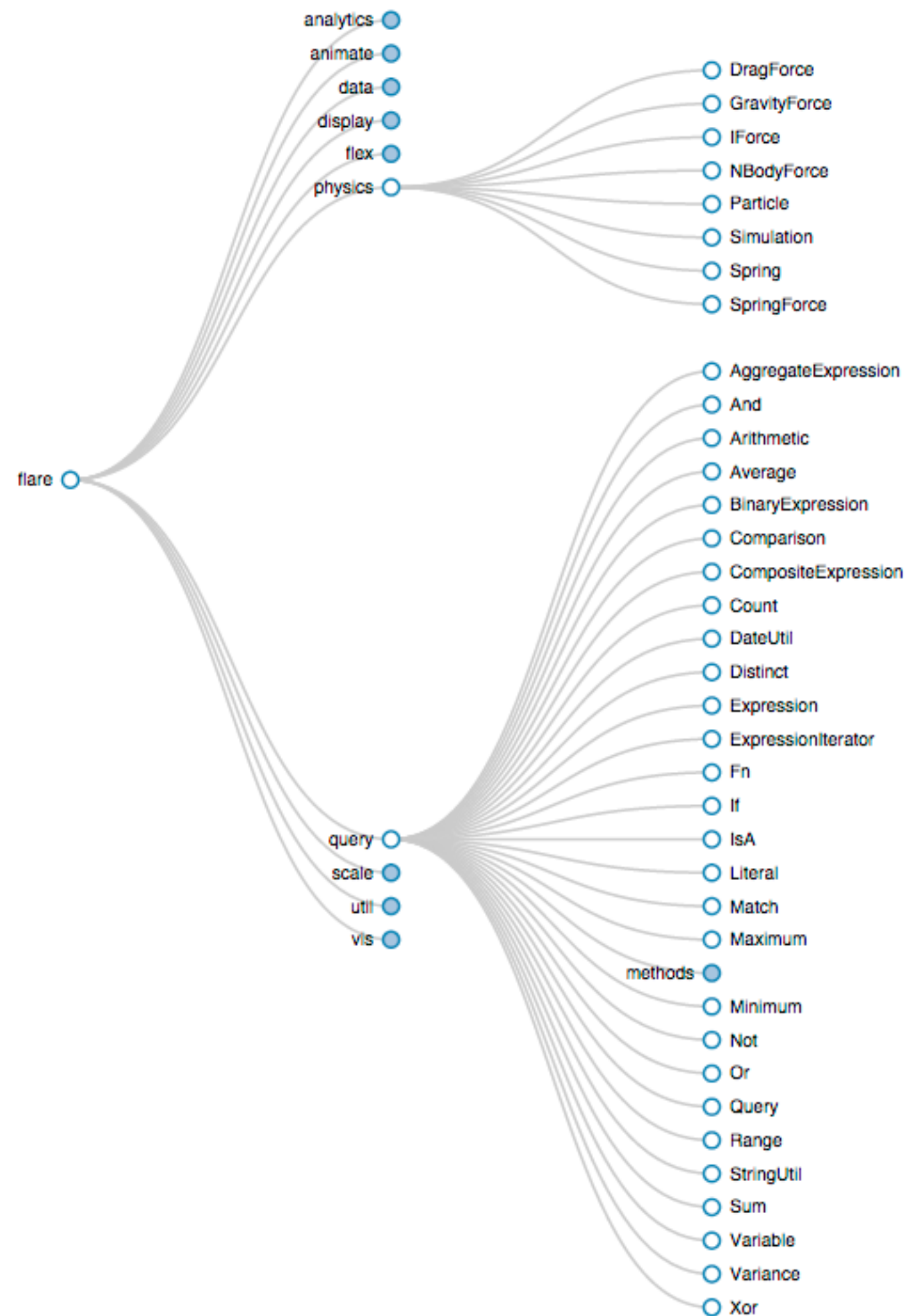
Douglas Engelbart 1968 - <http://www.1968demo.org>



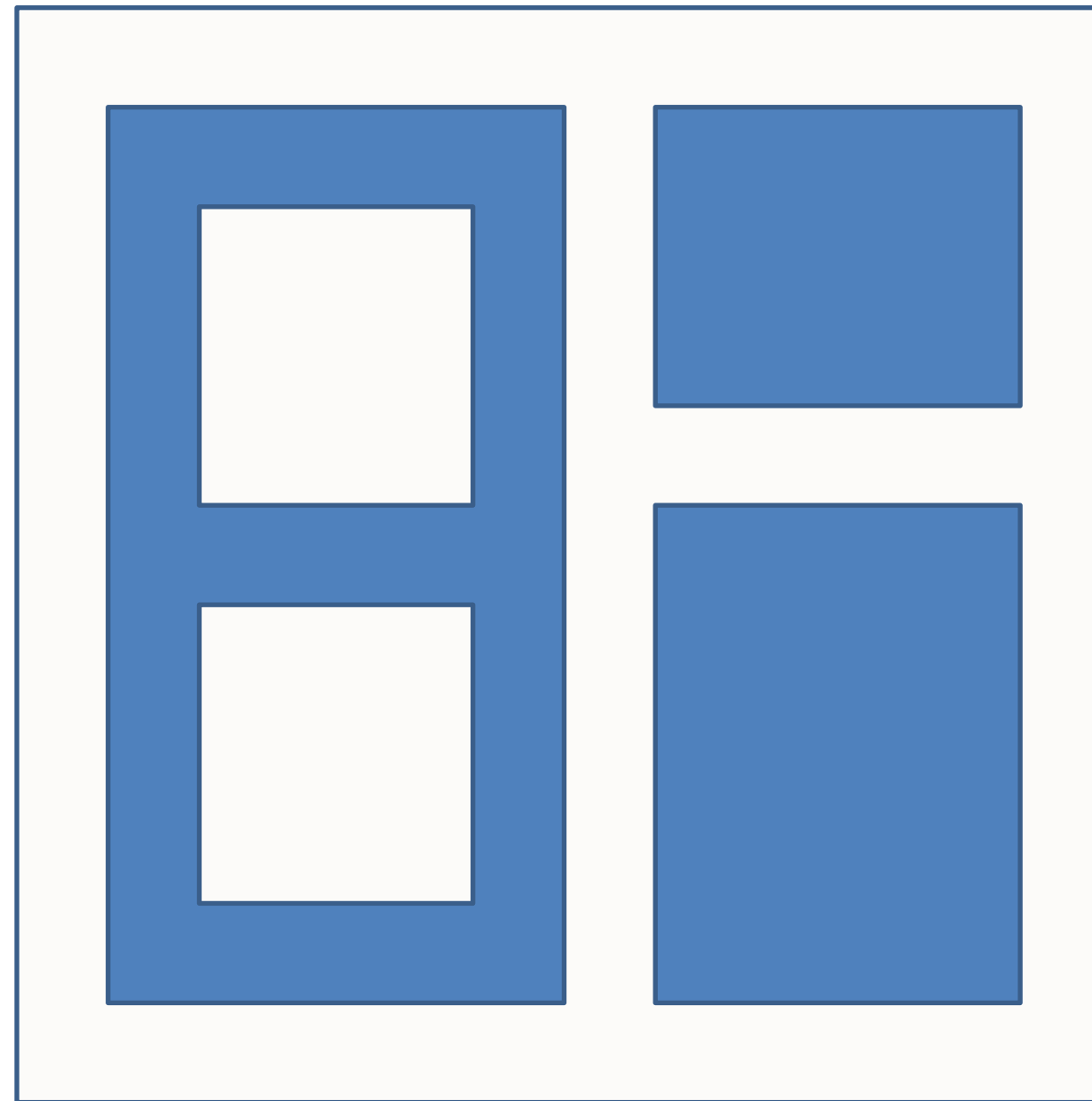
“The mother of all demos“

<https://www.youtube.com/watch?v=yJDv-zdhzMY>

Tree Interaction, Tree Comparison

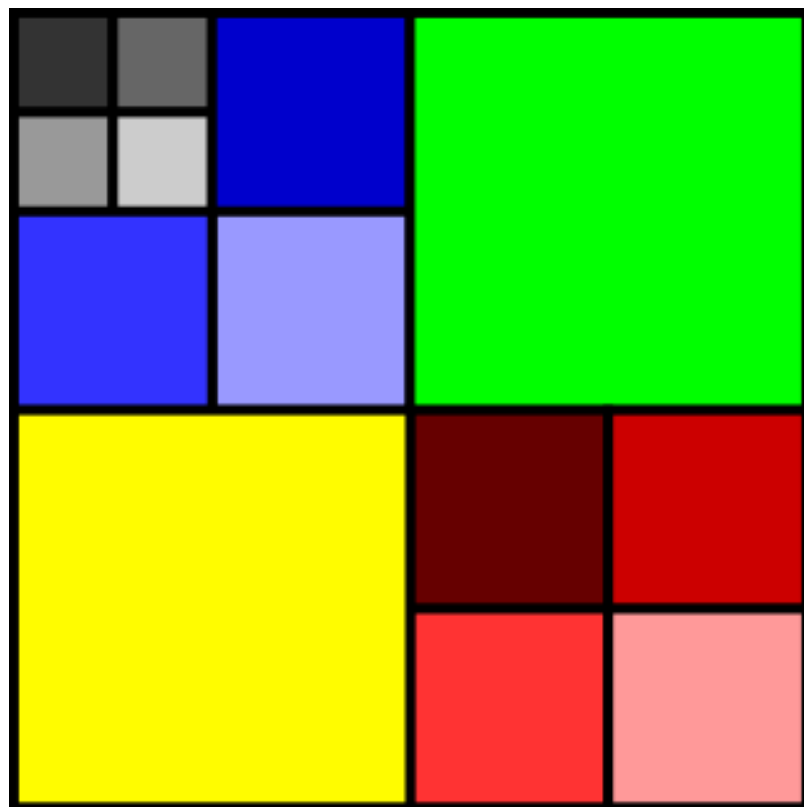


Implicit Layouts for Trees

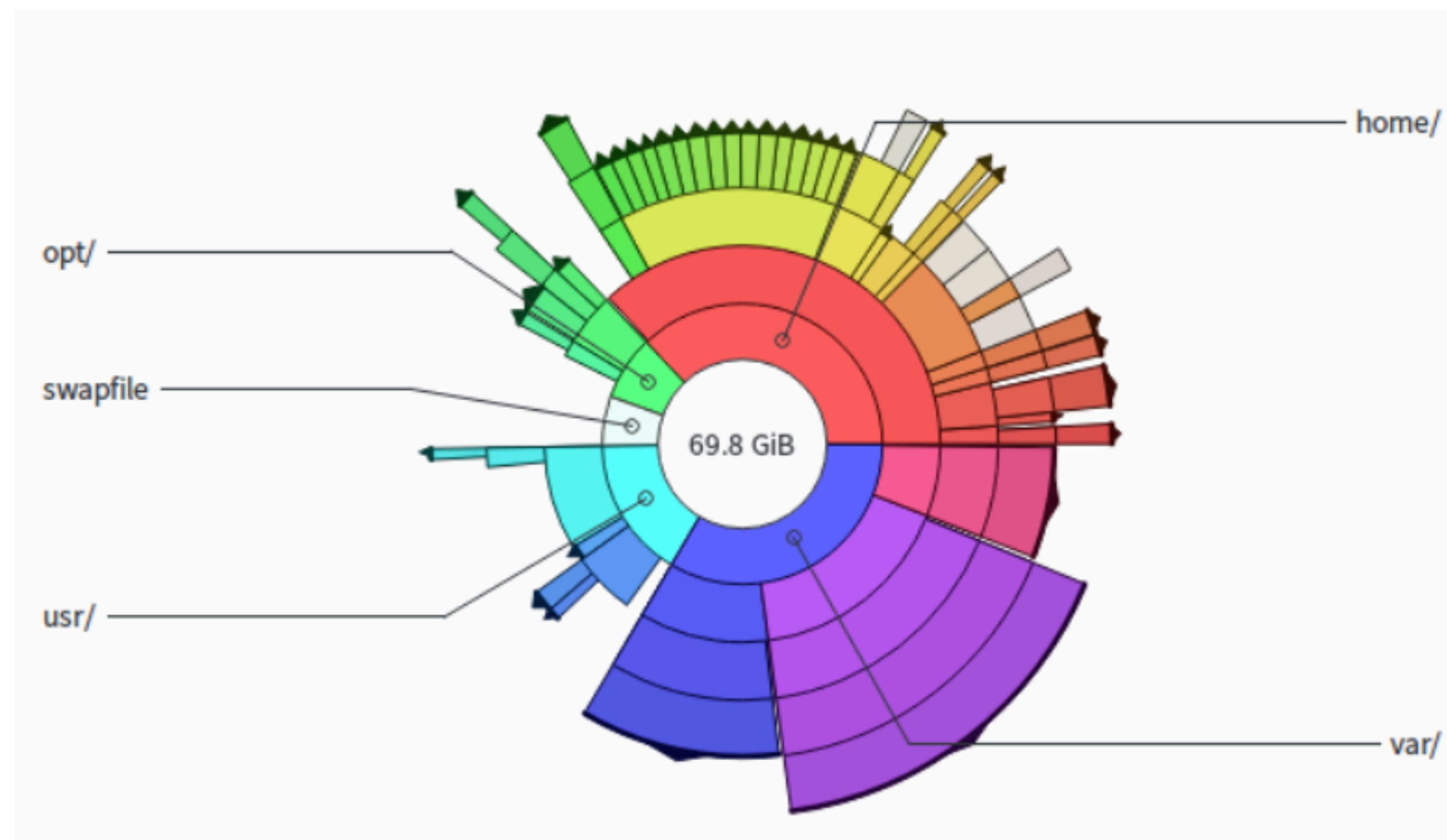


Implicit Layout Options

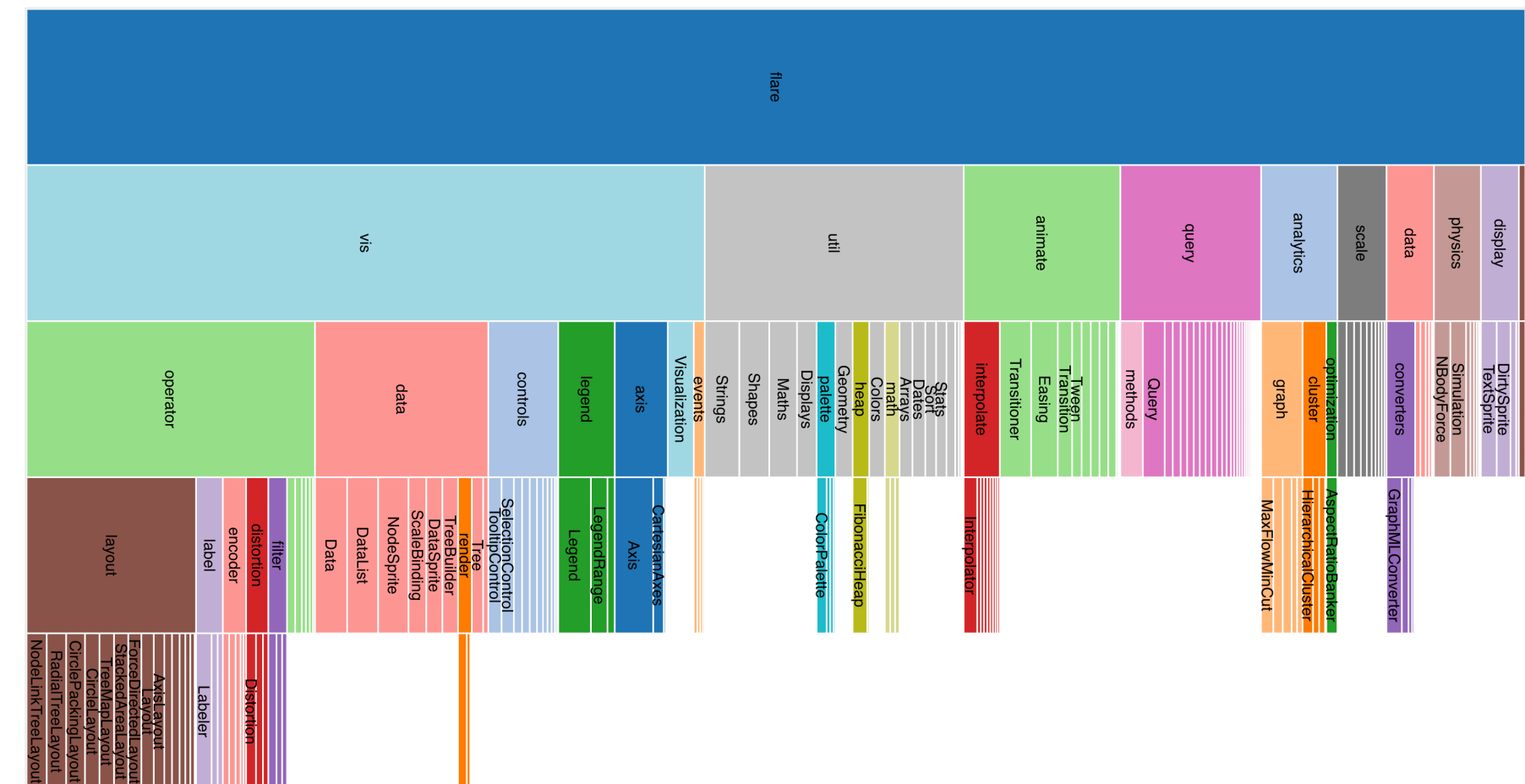
Treemap



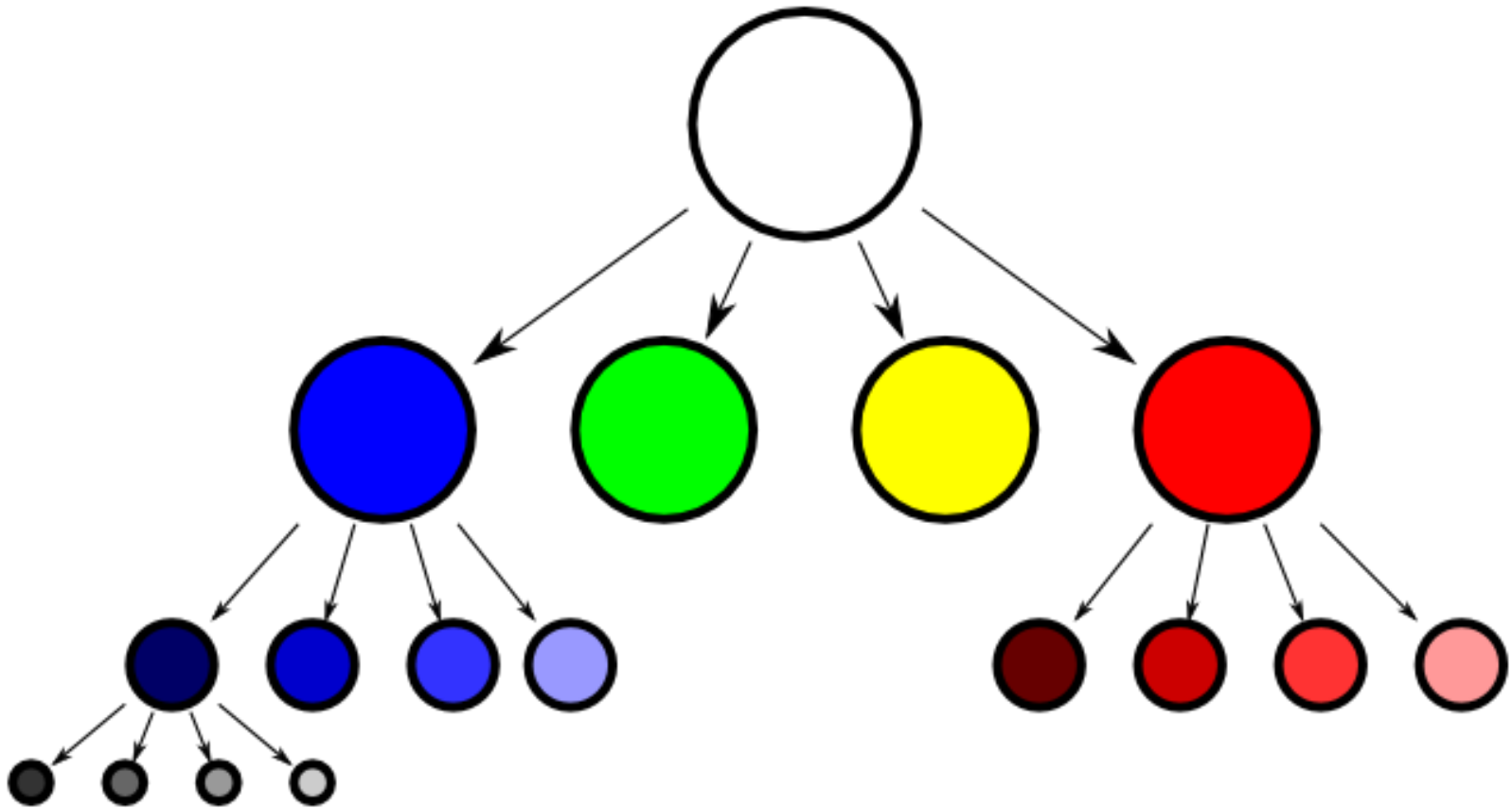
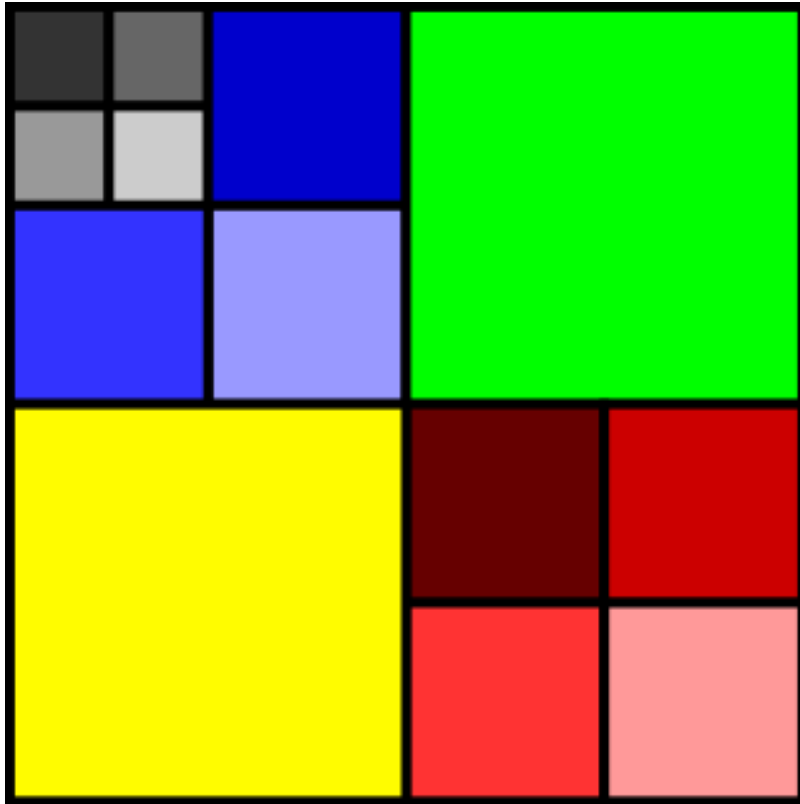
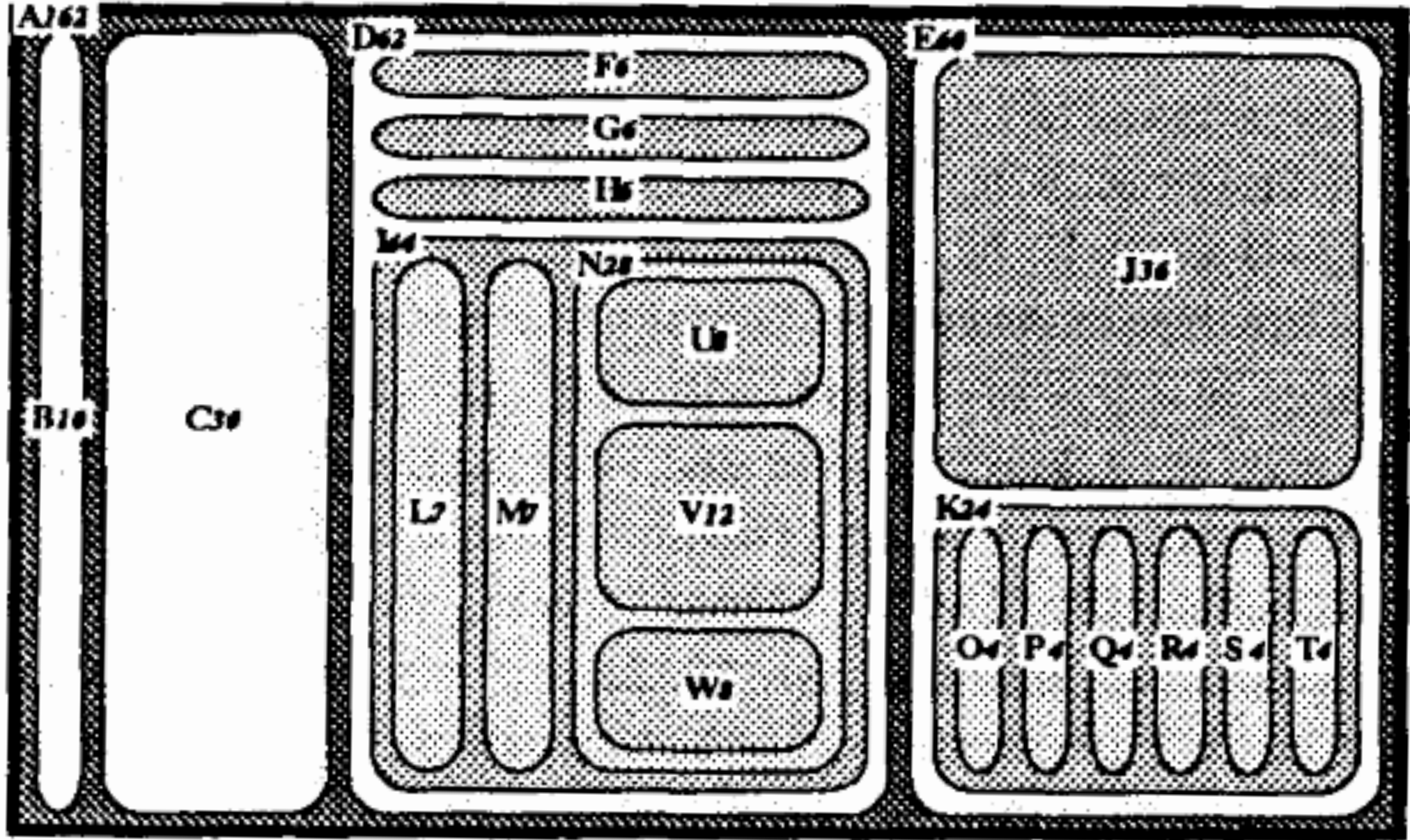
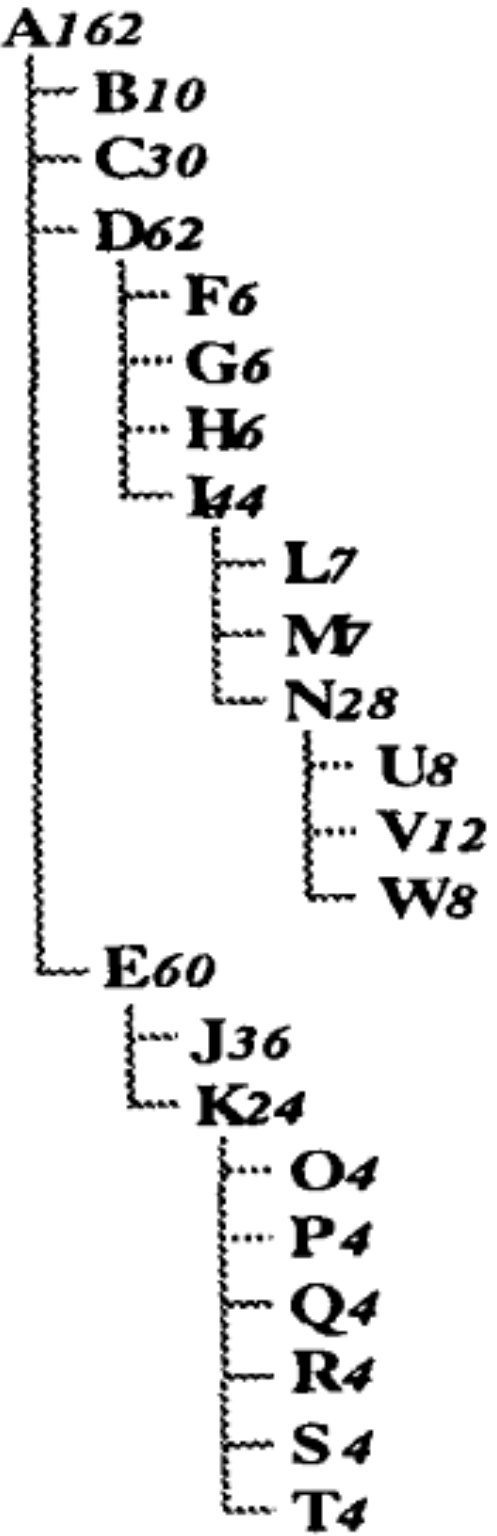
Sunburst



Icicle Plot

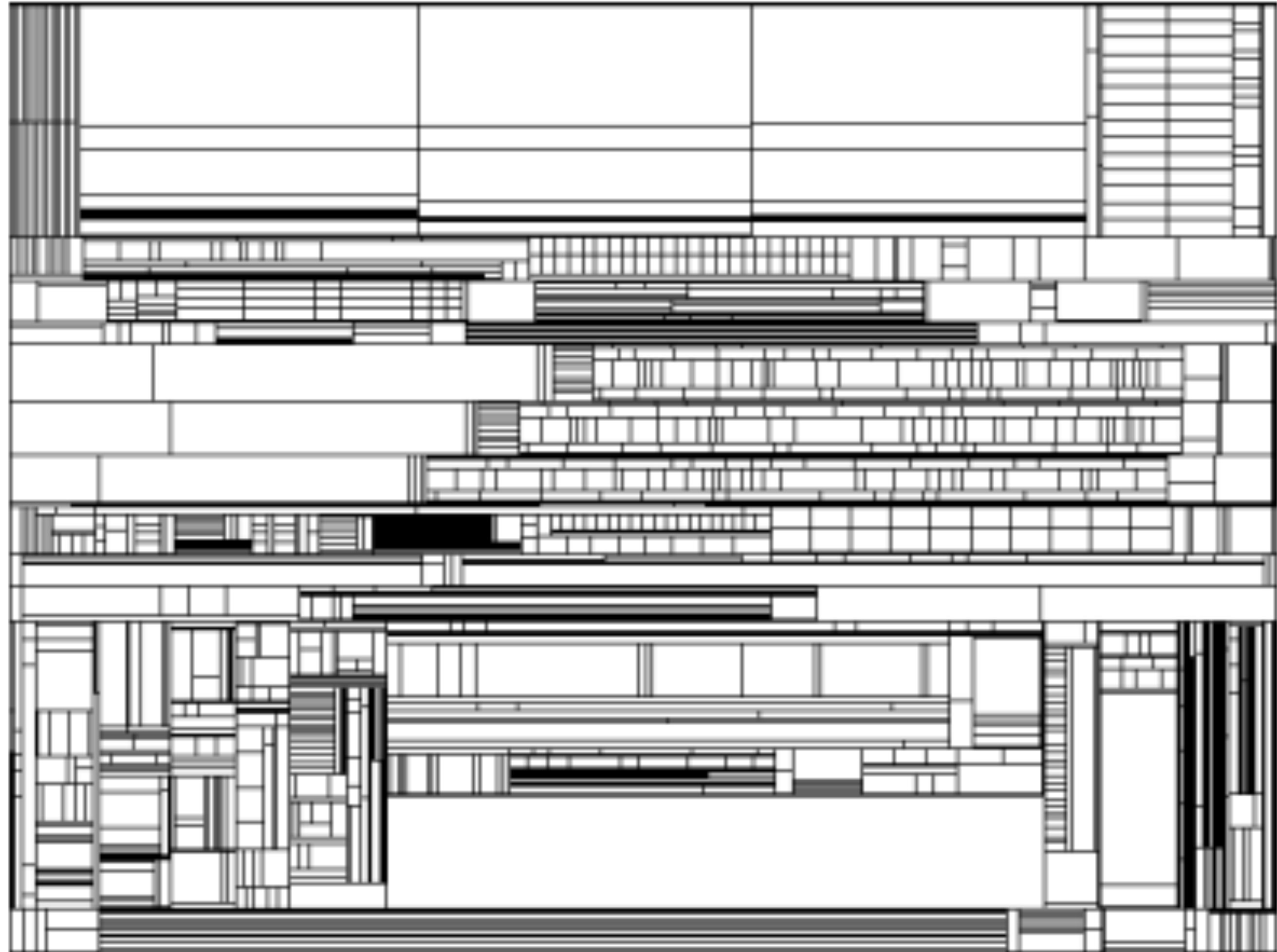


Tree Maps

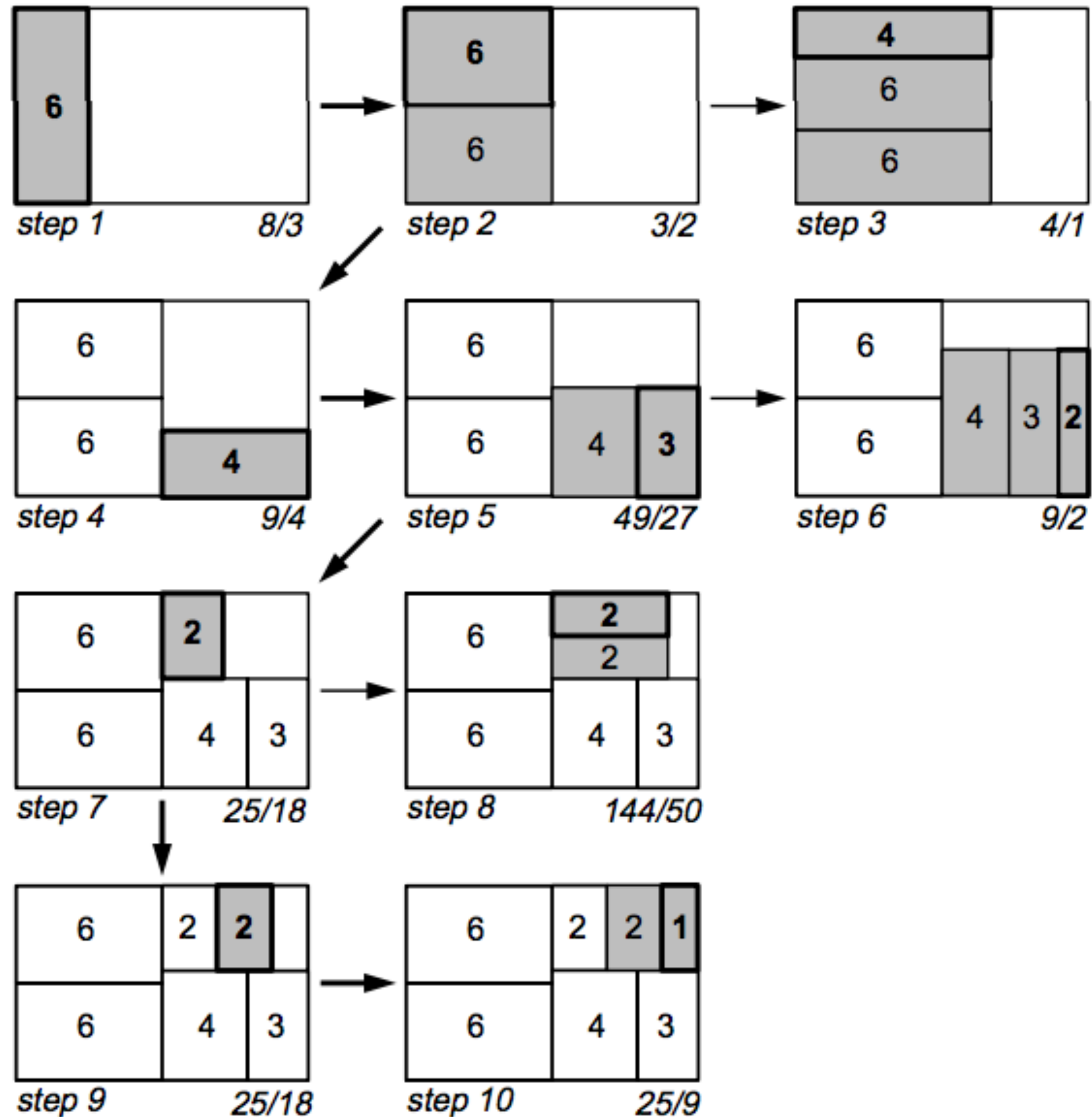


Squarified Treemaps

Original
Algorithm lead
to thin slices



Squarified Treemaps



Algo by Bruls, Huizing, Van Wijk 2000]

1: Horizontal subdivision to optimize aspect ratio

2: adding rect improves aspect ration

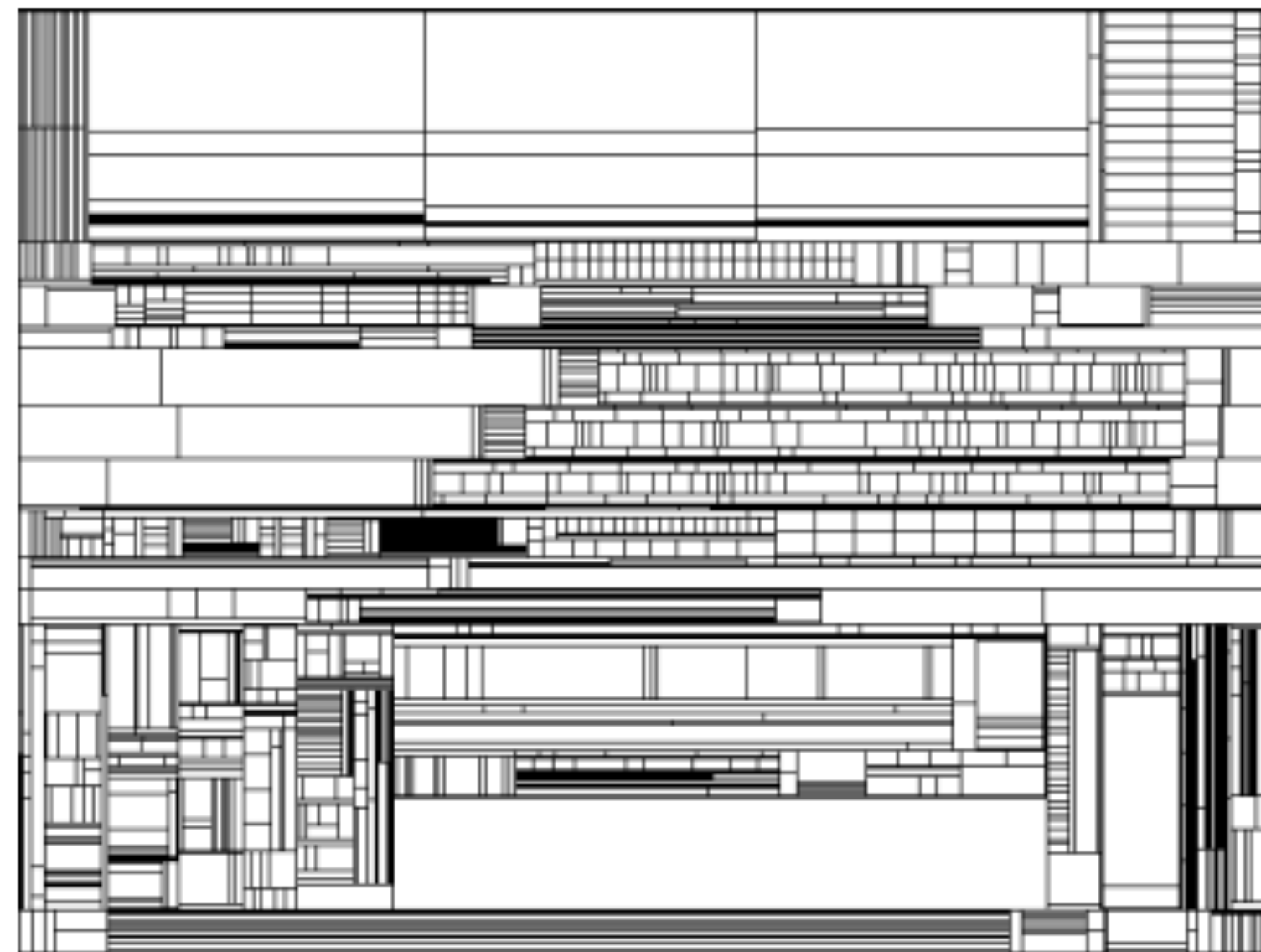
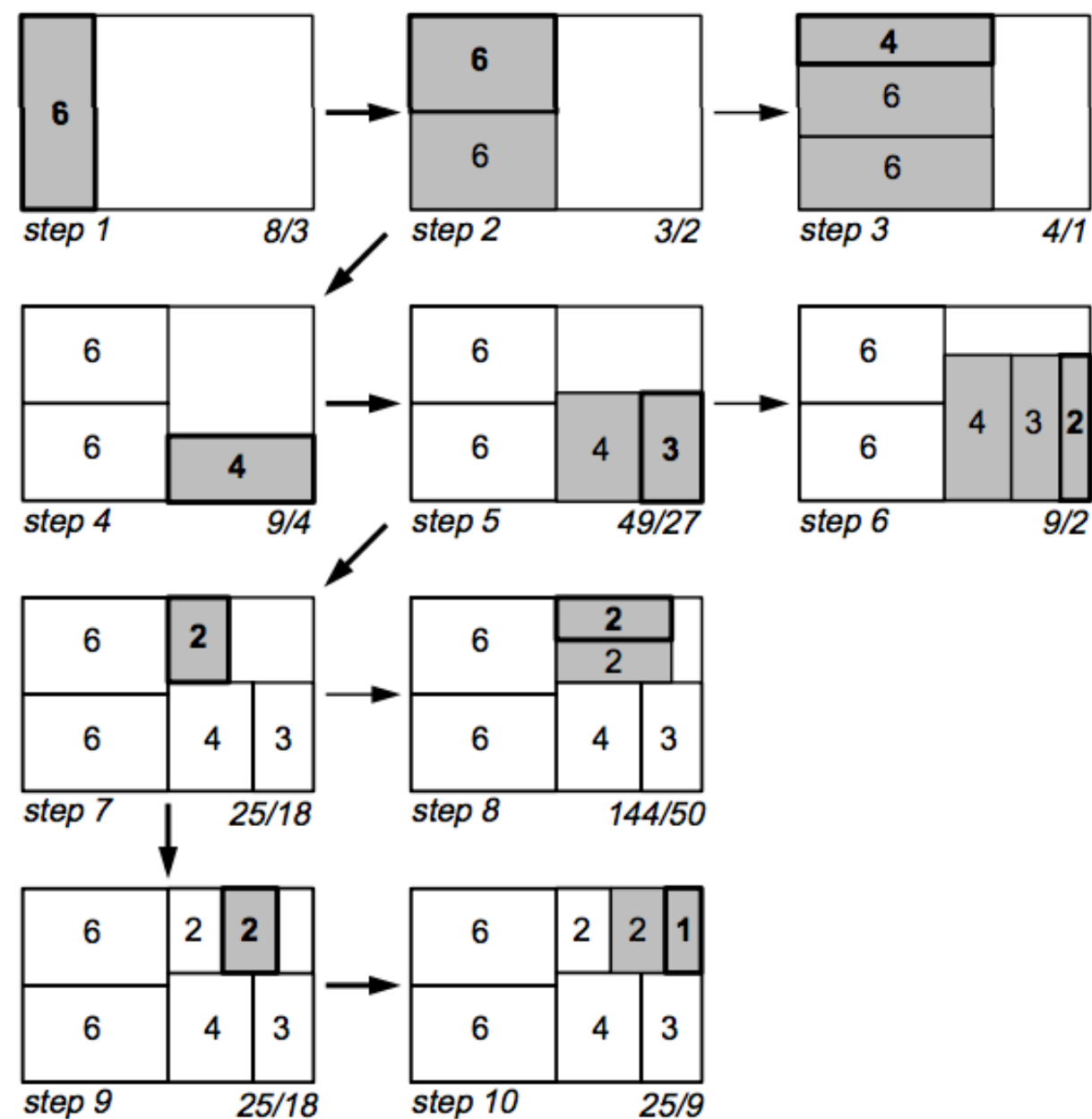
3: adding another deteriorates aspect ratio, back-track

4: add rect to unused area

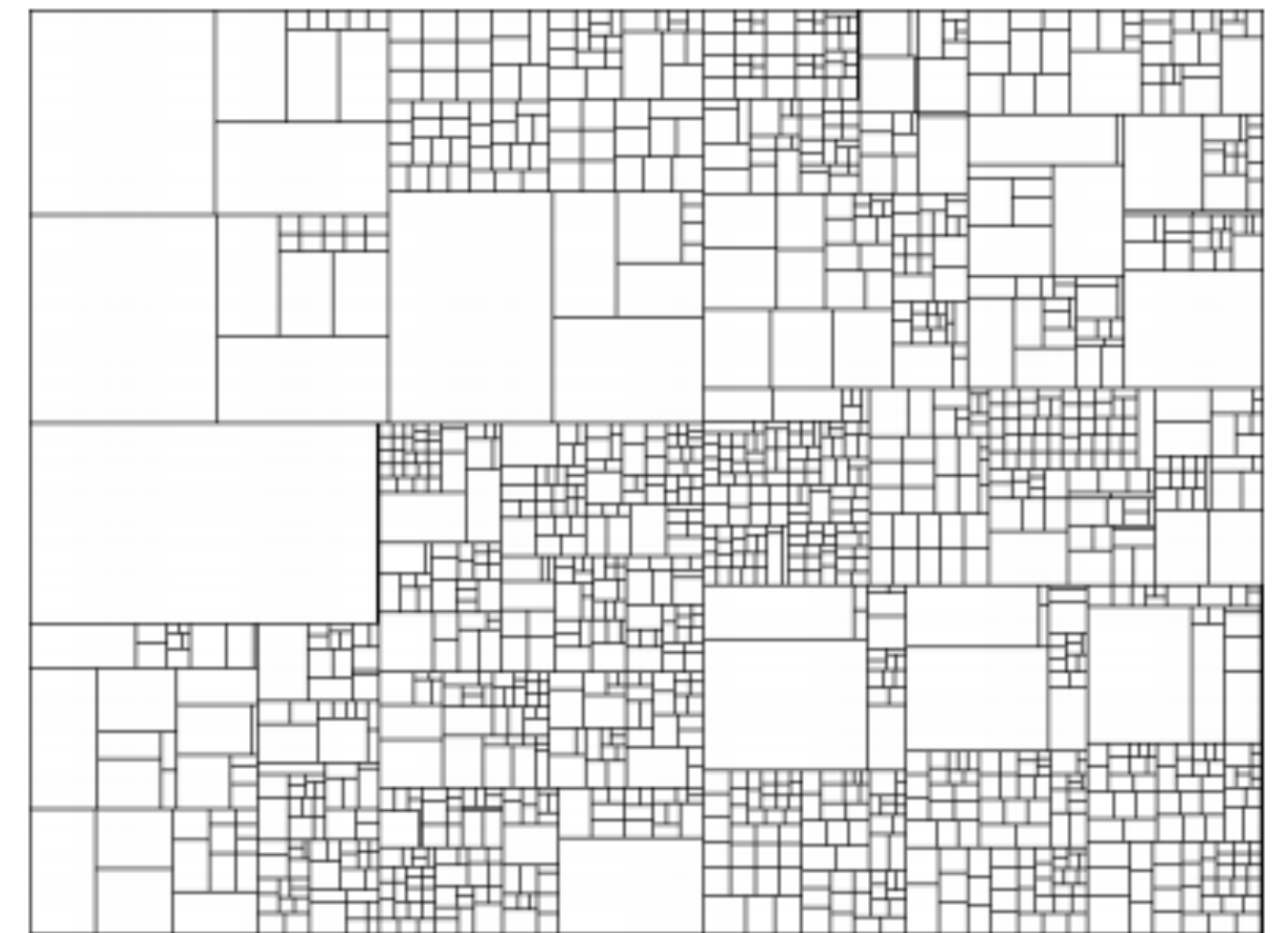
5: ...

Squarified Treemaps

Squarified treemaps [Bruls, Huizing, Van Wijk 2000]

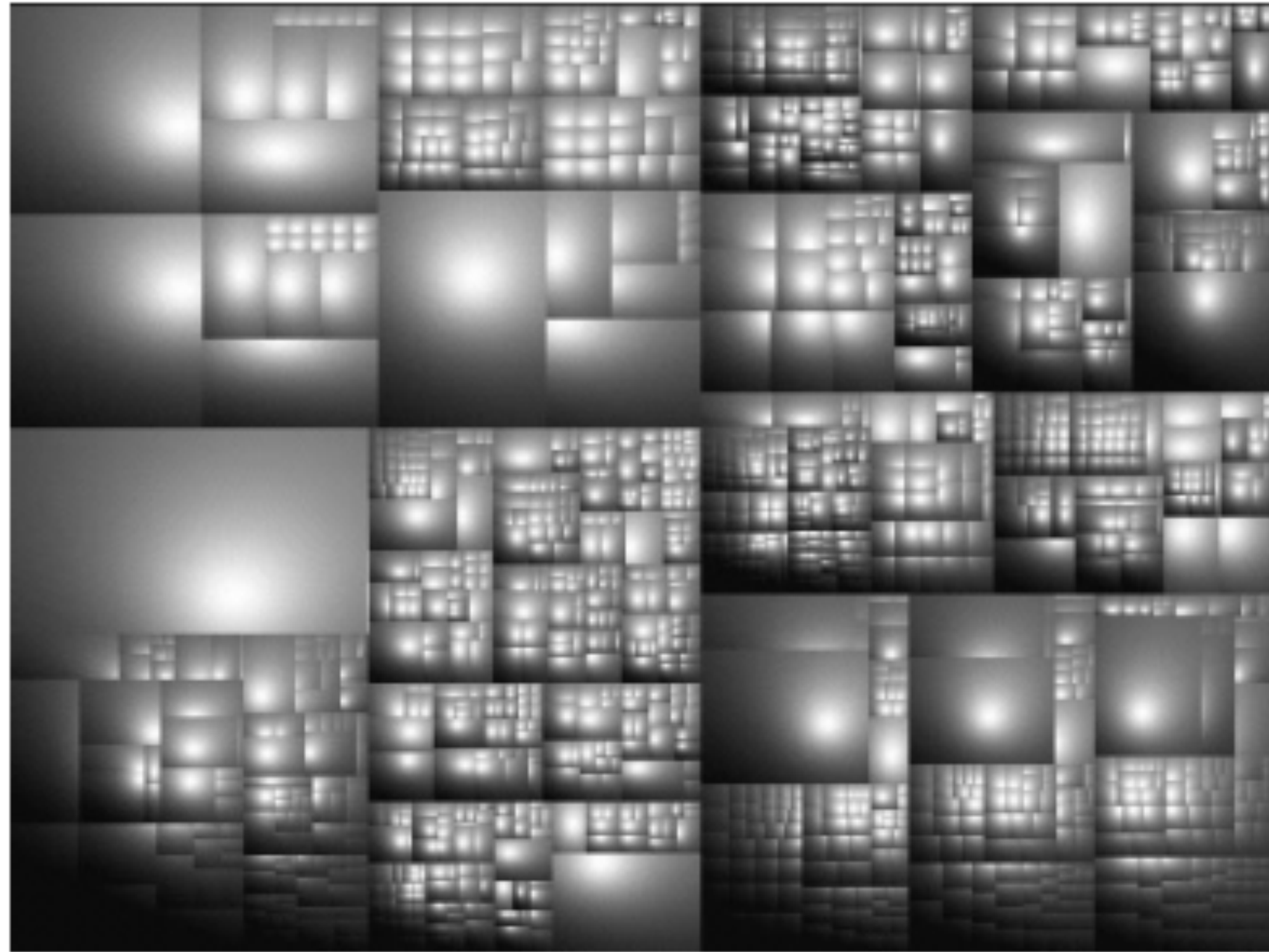


Before

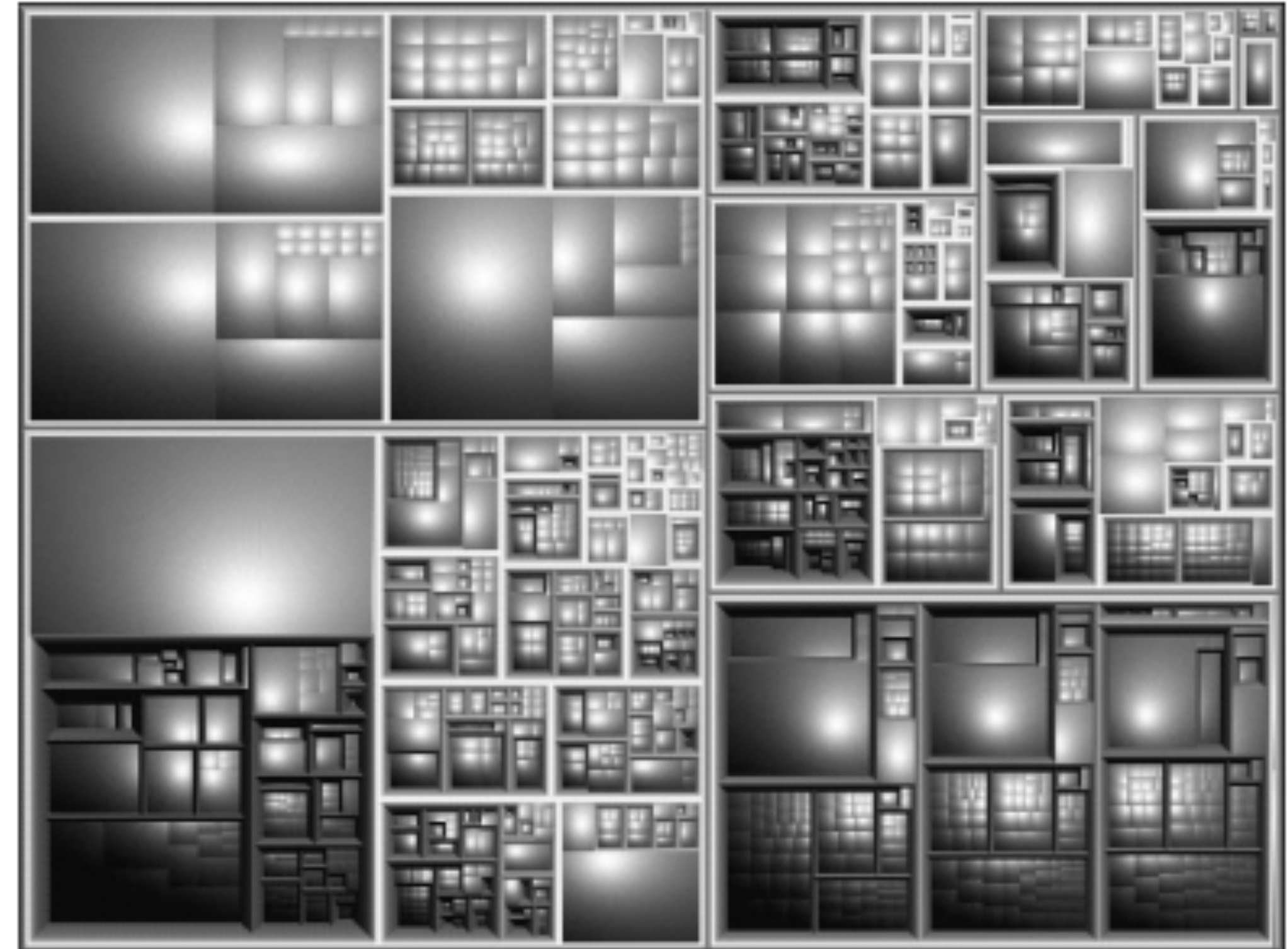


After

Seeing Tree Structure



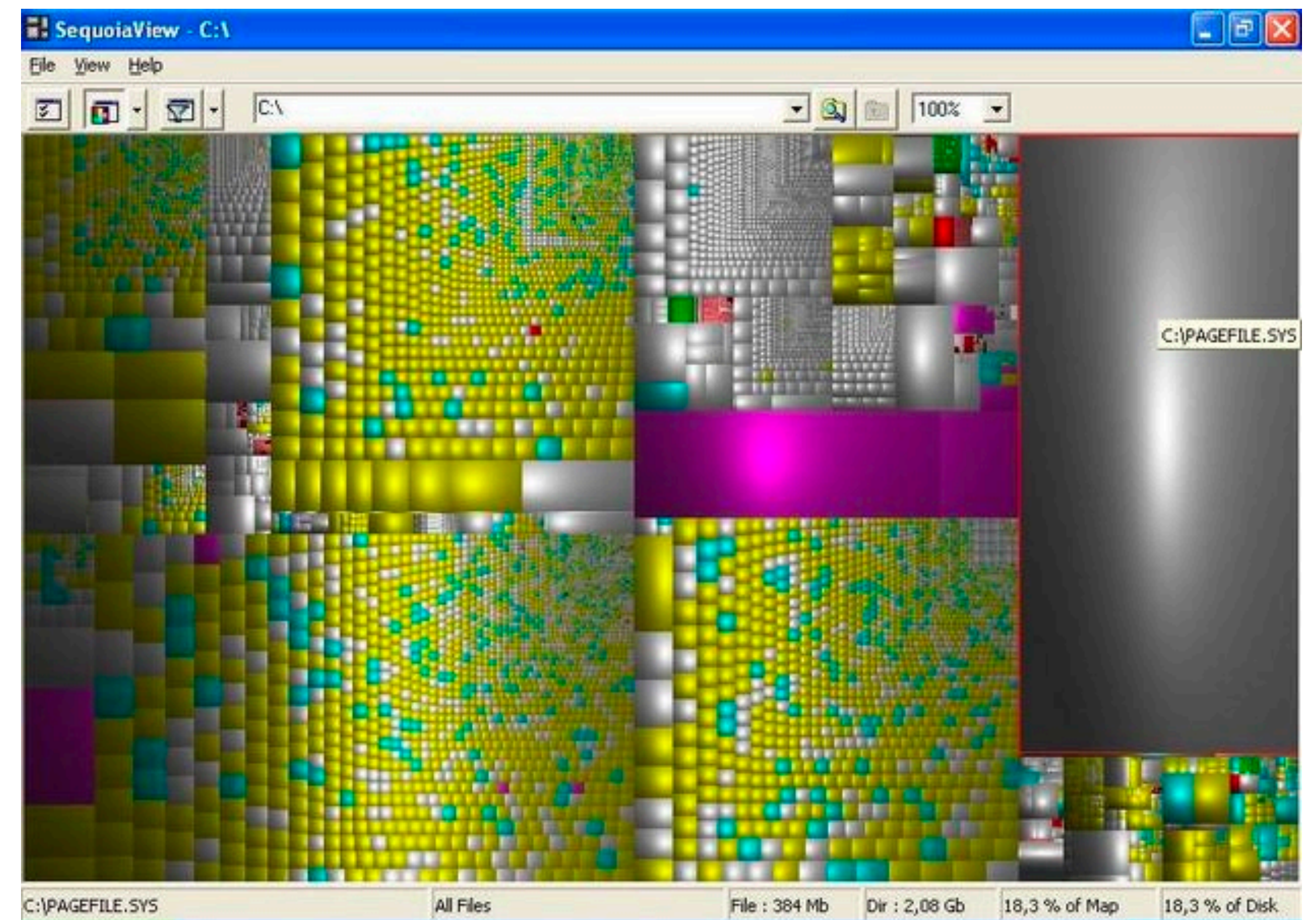
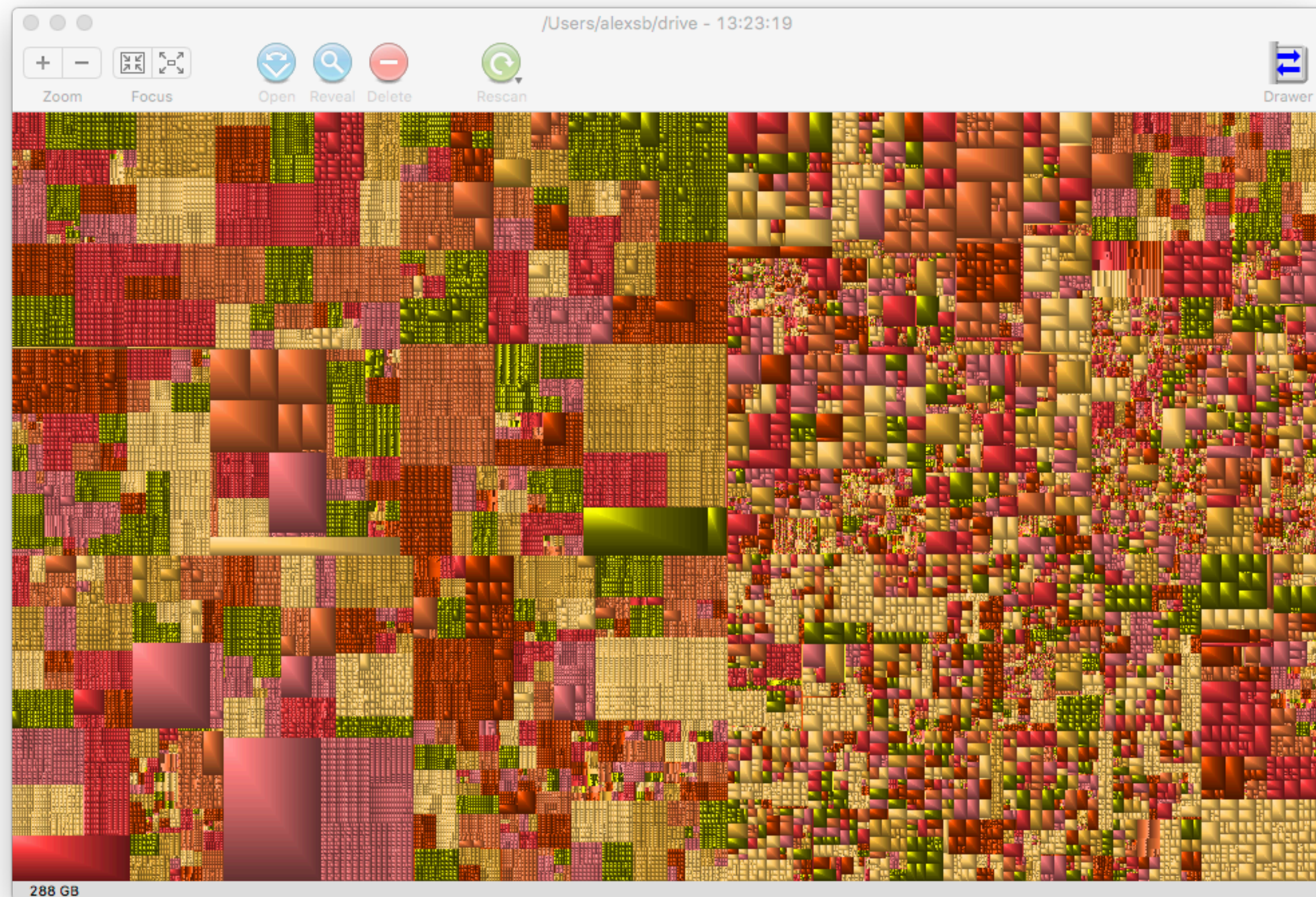
Unframed



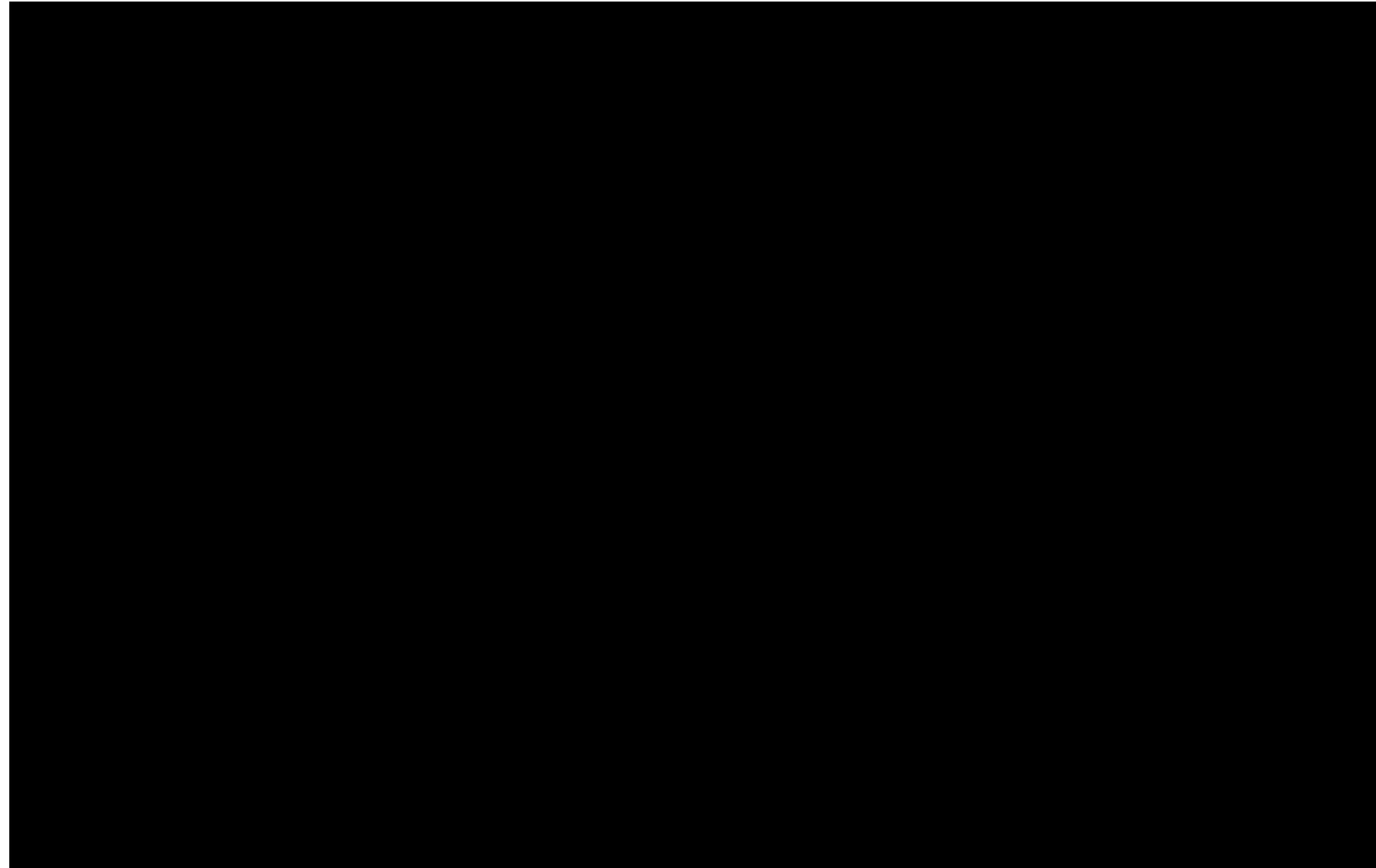
Framed

Software

Mac: GrandPerspective Windows: Sequoia View

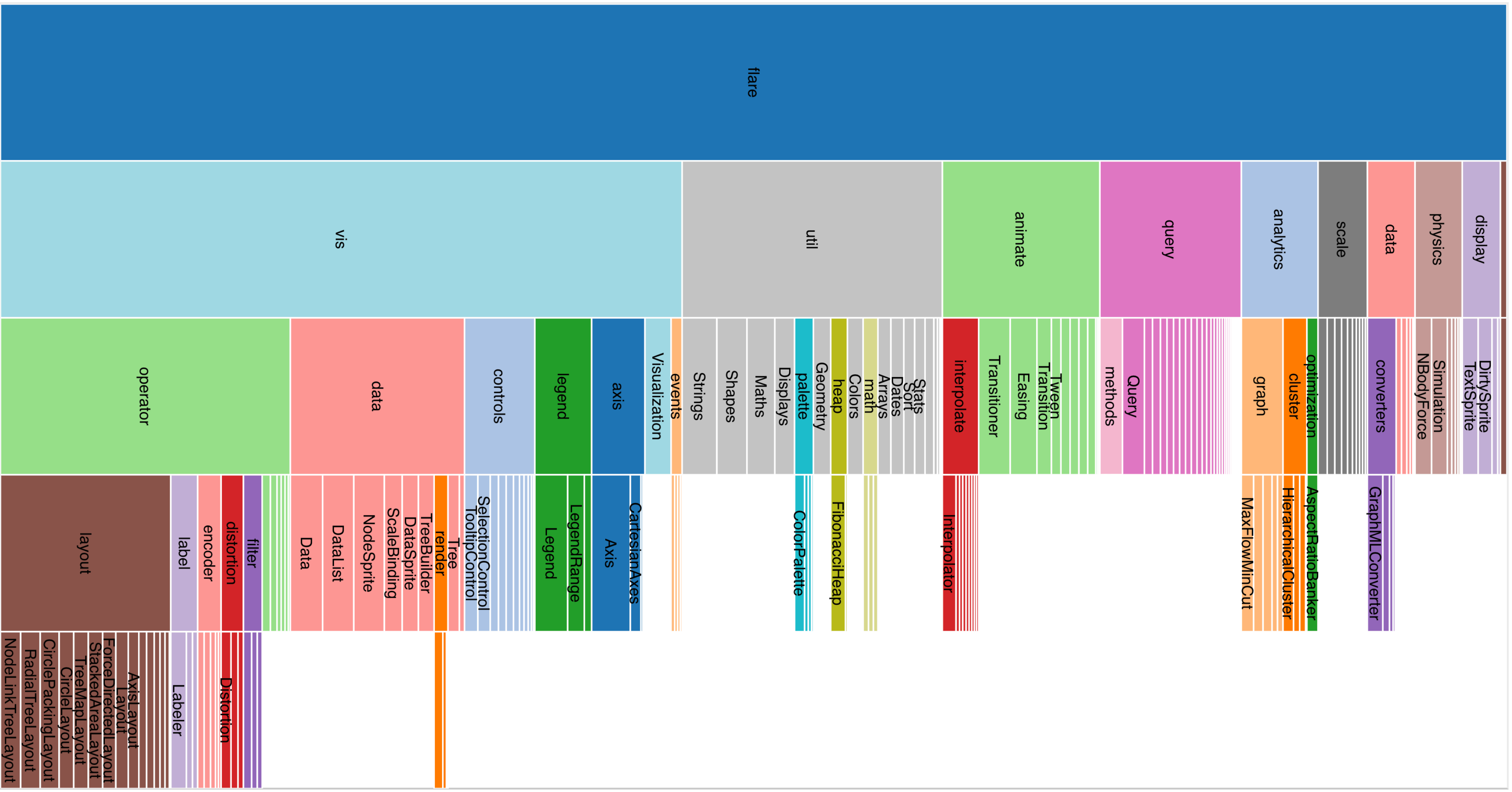


Sunburst: Radial Layout

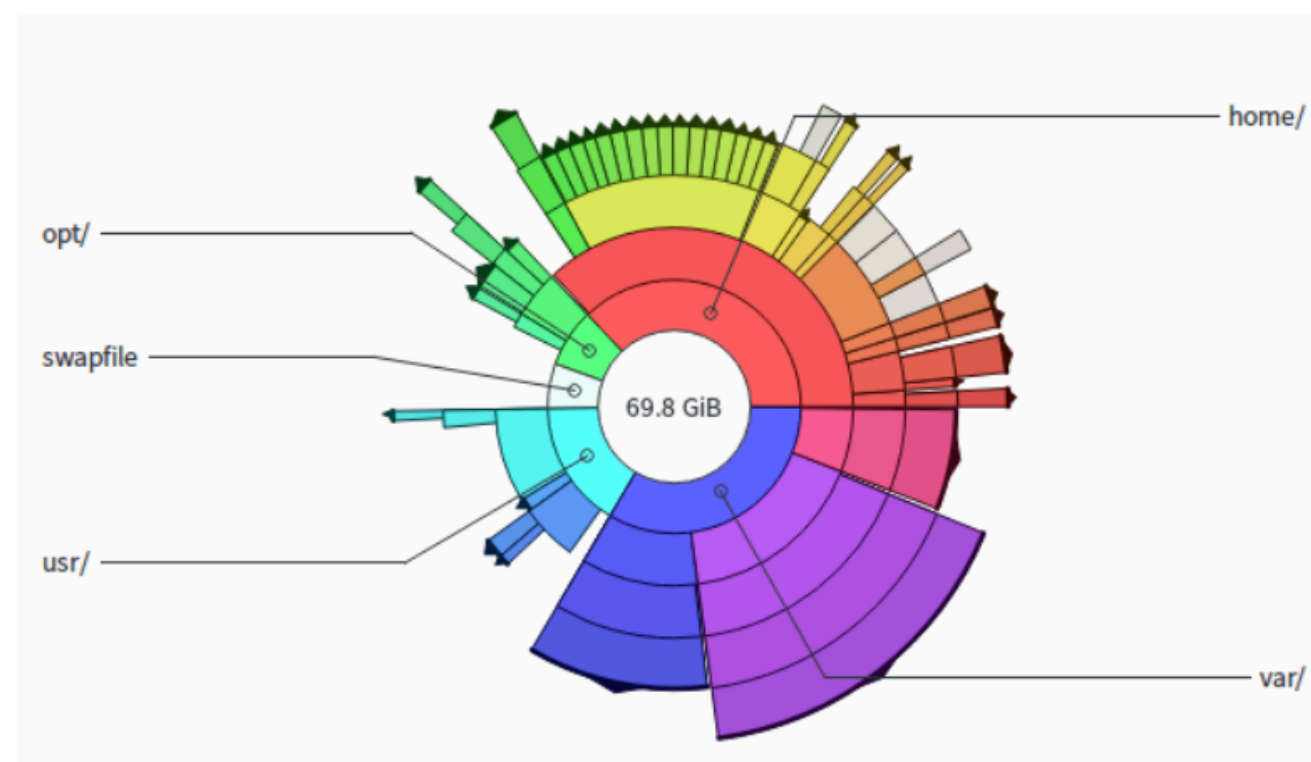
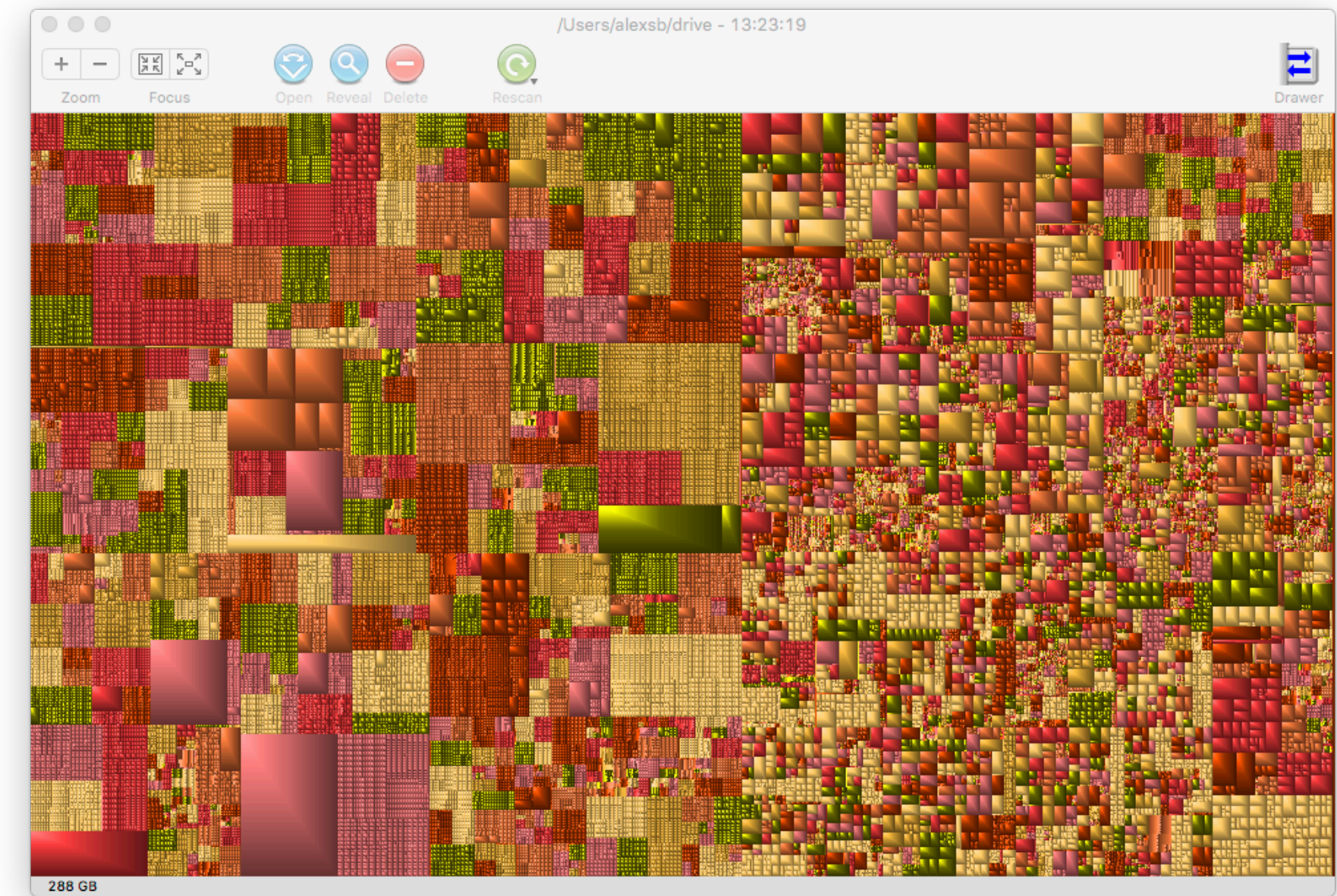
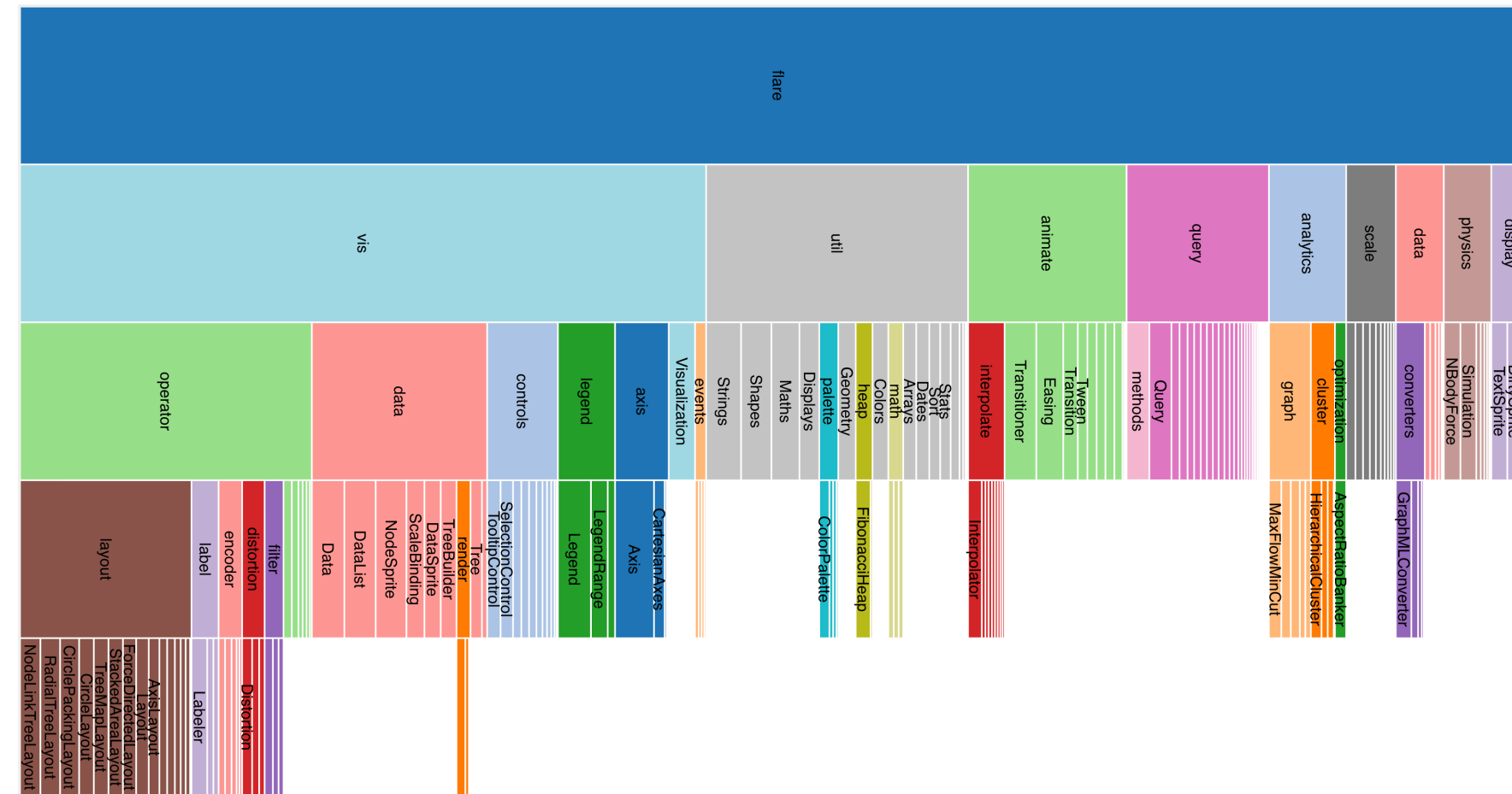


[Sunburst by John Stasko, Implementation in Caleydo by Christian Partl]

Icicle Plot



Differences? Pros, Cons?



Inner Nodes and Leaves Visible

Only Leaves Visible

Implicit Representations

Pros:

- space-efficient because of the lack of explicitly drawn edges: scale well up to very large graphs

- in most cases well suited for ABTs on the node set

- depending on the spatial encoding also useful for TBTs

Cons:

- can only represent trees

- since the node positions are used to represent edges, they can no longer be freely arranged (e.g., to reflect geographical positions)




- useless to pursue any task on the edges




Tree Visualization Reference




How to cite this site? [Check out other surveys!](#)

treevis.net - A Visual Bibliography of Tree Visualization 2.0 by Hans-Jörg Schulz

v.21-OCT-2014

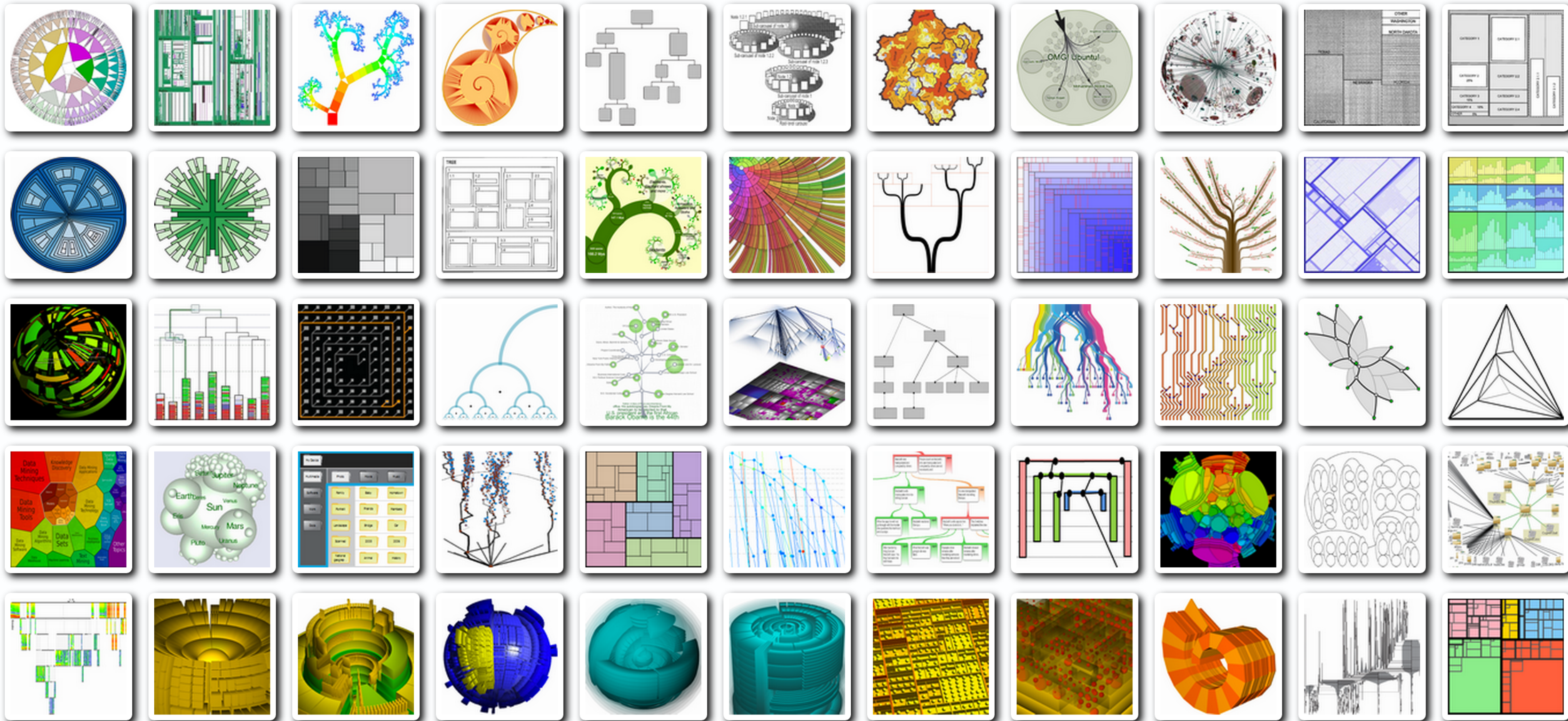
Dimensionality: All   

Representation: All   

Alignment: All   

Fulltext Search: x

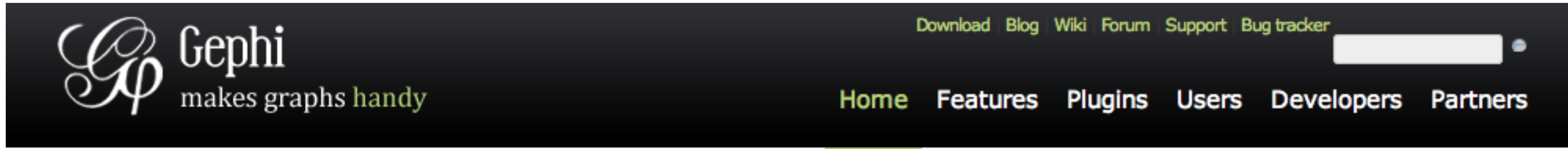
Techniques Shown: 277



Graph Tools & Applications

Gephi

<http://gephi.org>



The Open Graph Viz Platform

Gephi is a visualization and exploration platform for all kinds of networks and complex systems, dynamic and hierarchical graphs.

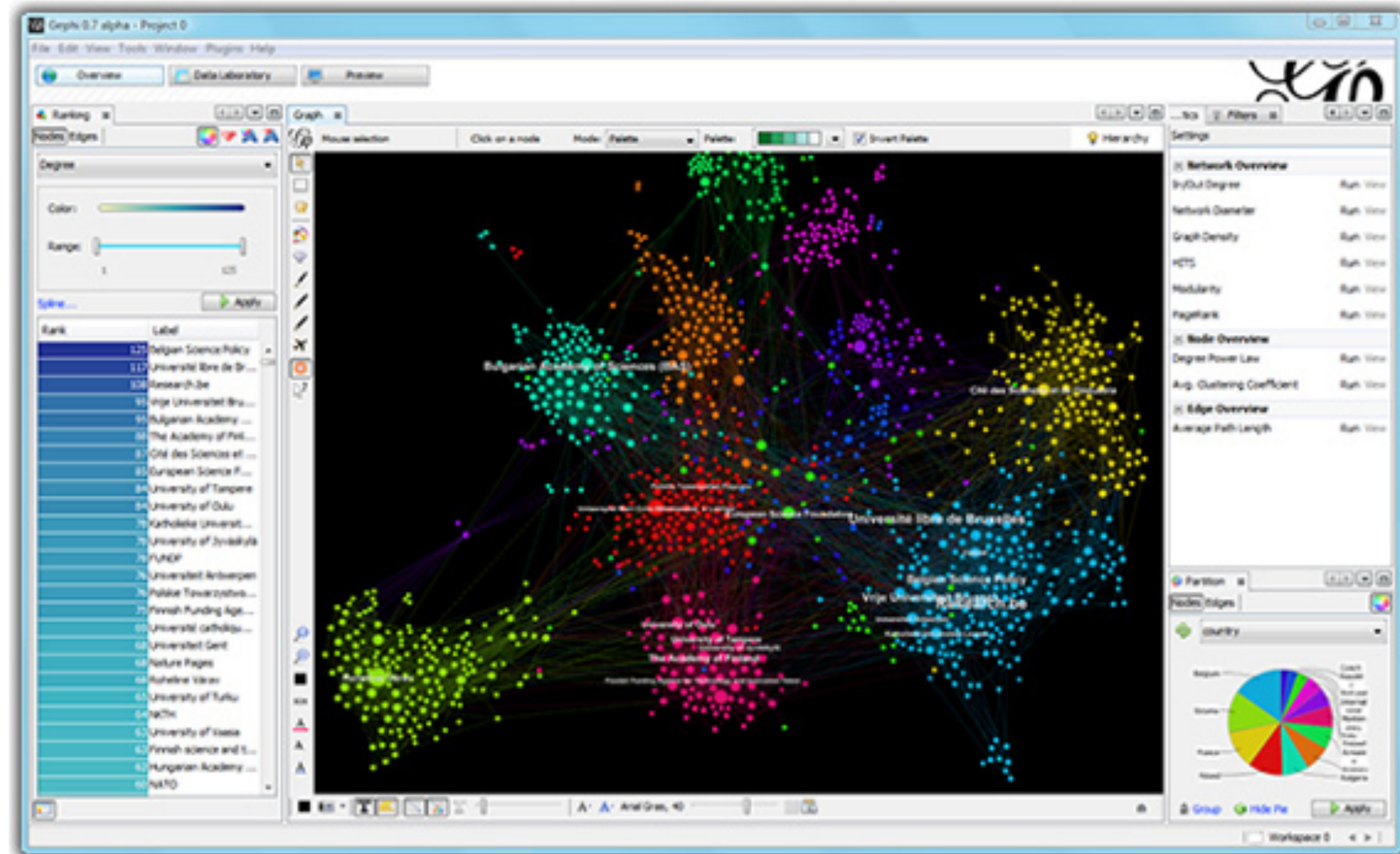
Runs on Windows, Linux and Mac OS X. Gephi is open-source and free.

[Learn More on Gephi Platform »](#)



[Release Notes](#) | [System Requirements](#)

- [Features](#)
- [Screenshots](#)
- [Quick start](#)
- [Videos](#)



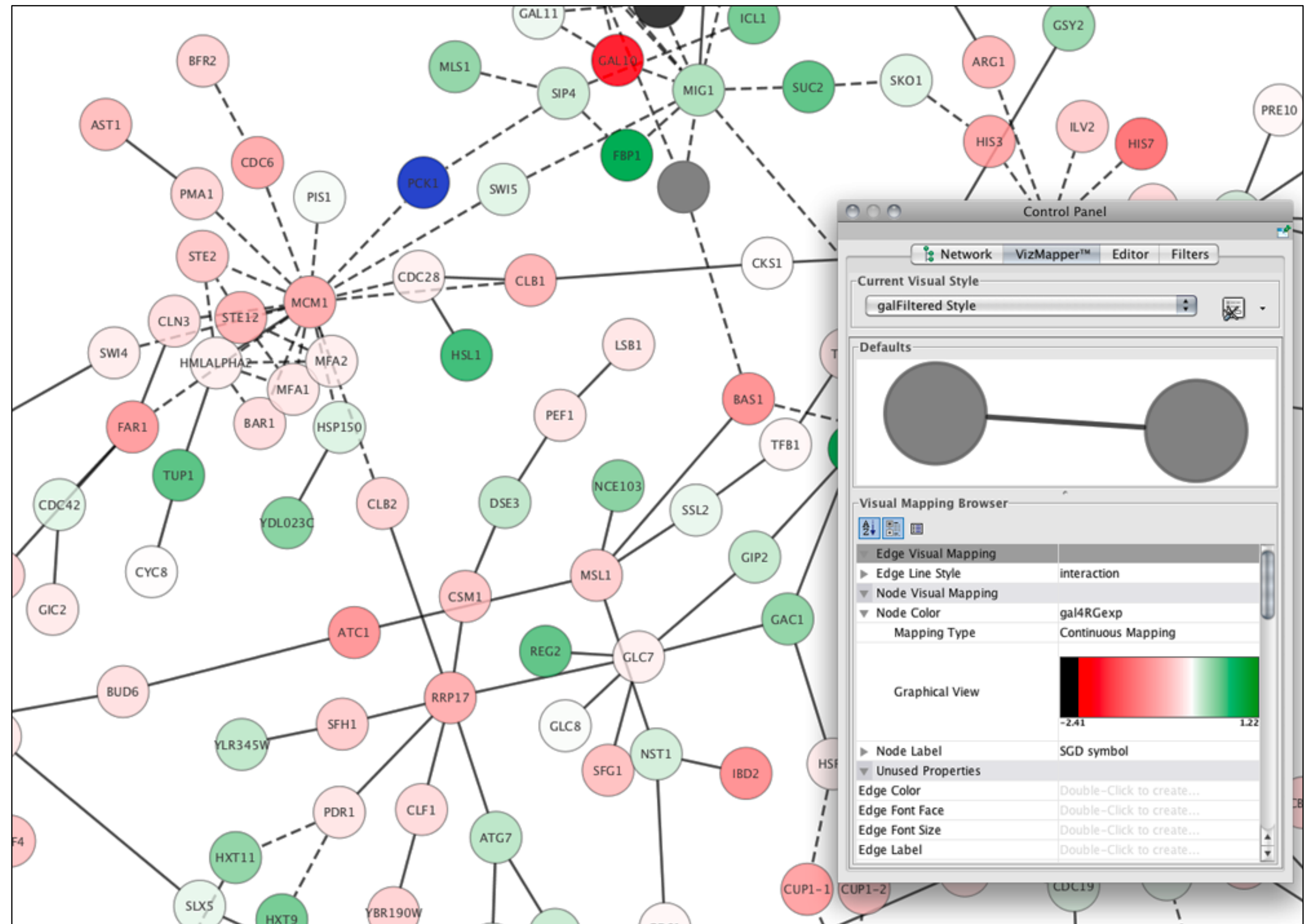
Gephi has been accepted again for Google Summer of Code! The program is the best way for students around the world to start contributing to an open-source project. Students, apply now for Gephi proposals. Come to the GSOC forum section and say Hi! to [this topic](#).

[Learn More »](#)

Cytoscape

Open source platform for complex network analysis

<http://www.cytoscape.org/>



Cytoscape Web

<http://cytoscapeweb.cytoscape.org/>

Cytoscape Web Feature Showcase Demo

This is a separate demo application, built around the Cytoscape Web visualization. Because this showcase is complex, you may experience issues, such as slowdowns, on older or less efficient browsers.

Save file Open file Style Layout

Examples Visual style Filter Properties

Nodes Edges Reset filters

Filter such that every any filter is satisfied.

id
Find a value to filter

label
Find a value to filter

shape
Find a value to filter

weight
0.03 0.45

```
graph TD; A01((A01)) -- solid blue arrow --> A05[/A05/]; A01 -.-> A02(ΔA02); A01 -.-> A03(⬡A03); A02 -.-> A03; A02 -.-> A06[■A06]; A03 -.-> A07[▭A07]; A03 -.-> A08(⬡A08); A04{A04} -.-> A09(★A09); A08 -.-> A09; A08 -.-> A01; A05 -.-> A01; A05 -.-> A02; A07 -.-> A03; A06 -.-> A02; A08 -.-> A01; A09 -.-> A04; A09 -.-> A08; A01 -.-> A08; A01 -.-> A09; A02 -.-> A09; A03 -.-> A09; A04 -.-> A01; A04 -.-> A02; A04 -.-> A03; A04 -.-> A08; A04 -.-> A09; A05 -.-> A08; A05 -.-> A09; A06 -.-> A08; A06 -.-> A09; A07 -.-> A08; A07 -.-> A09; A08 -.-> A05; A08 -.-> A06; A08 -.-> A07; A08 -.-> A09; A09 -.-> A05; A09 -.-> A06; A09 -.-> A07; A09 -.-> A08; A09 -.-> A09
```

NetworkX

<https://networkx.github.io/>

NetworkX

[NetworkX Home](#) | [Documentation](#) | [Download](#) | [Developer \(Github\)](#)

High-productivity software for complex networks

NetworkX is a Python language software package for the creation, manipulation, and study of the structure, dynamics, and functions of complex networks.



[Documentation](#)

all documentation

[Examples](#)

using the library

[Reference](#)

all functions and methods

Features

- Python language data structures for graphs, digraphs, and multigraphs.
- Nodes can be "anything" (e.g. text, images, XML records)
- Edges can hold arbitrary data (e.g. weights, time-series)
- Generators for classic graphs, random graphs, and synthetic networks
- Standard graph algorithms
- Network structure and analysis measures
- Open source [BSD license](#)
- Well tested: more than 1800 unit tests, >90% code coverage
- Additional benefits from Python: fast prototyping, easy to teach, multi-platform

Versions

Latest Release

1.8.1 - 4 August 2013
[downloads](#) | [docs](#) | [pdf](#)

Development

1.9dev
[github](#) | [docs](#) | [pdf](#)
build passing
coverage 83%

Contact

[Mailing list](#)
[Issue tracker](#)
[Developer guide](#)



Design Critique

Connected China



<https://goo.gl/YXkWYX>

<http://china.fathom.info/>